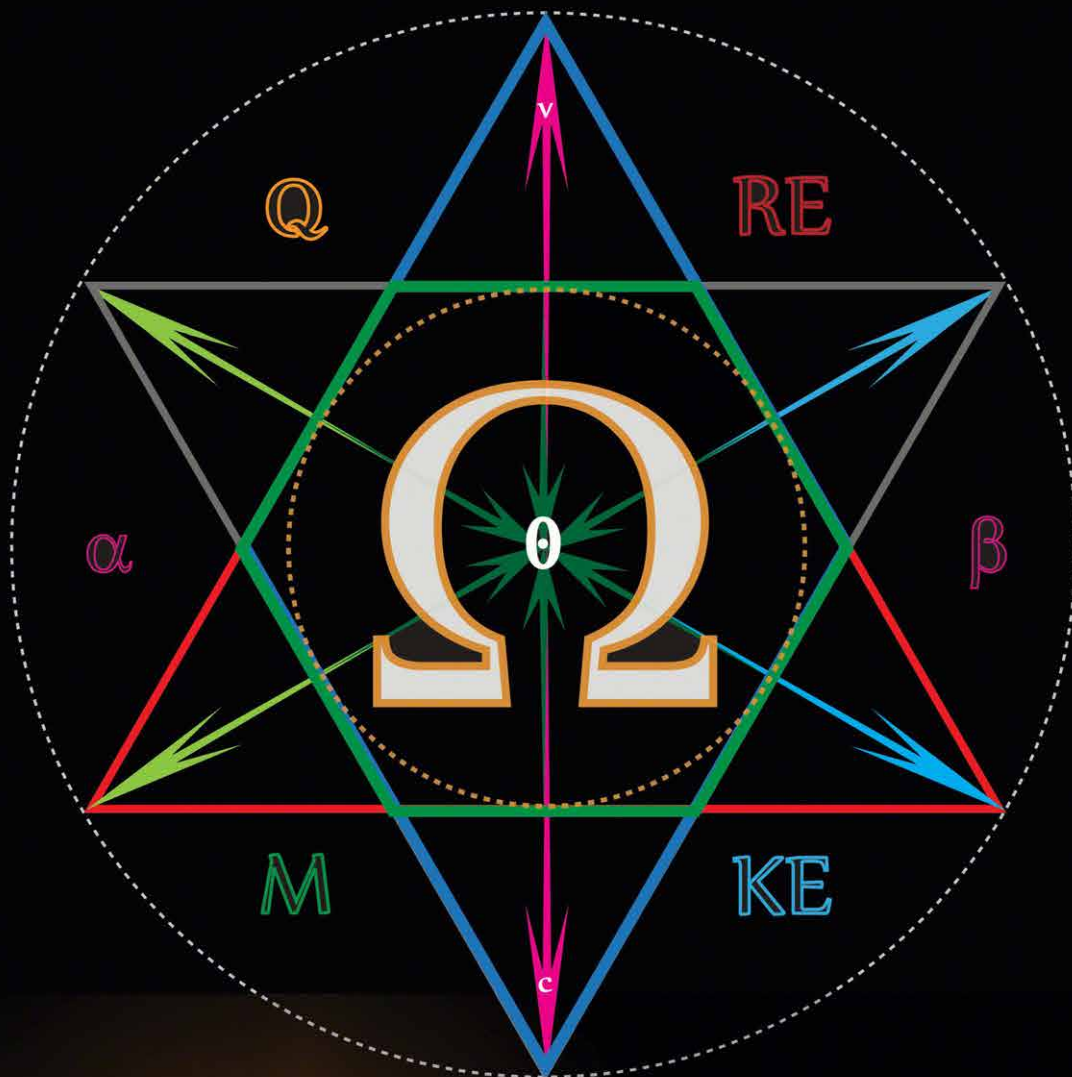


TETRYONICS

The equilateral geometry underpinning the mathematics of Physics



Foundational physics Mathematics

Abraham

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[Second Edition © 2012]

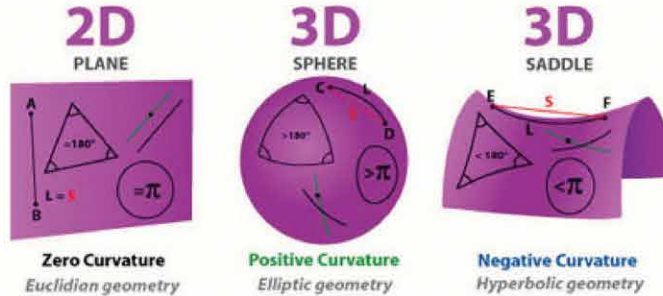
Geometry and the Theory of Everything

Plato



(c.428-348 BC)

DIFFERENT TYPE OF GEOMETRIES



(studied by Omar Khayyam, Girolamo Saccheri, Bernhard Riemann, ...)

Euclid



(c.330-275 BC, fl. c.300 BC)

The Socratic tradition was not particularly congenial to mathematics, as may be gathered from Socrates' inability to convince himself that 1 plus 1 equals 2, but it seems that his student Plato gained an appreciation for mathematics after a series of conversations with his friend Archytas in 388 BC.

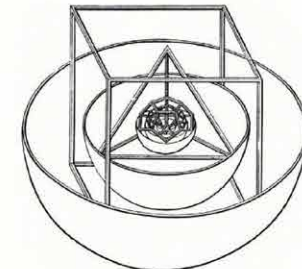
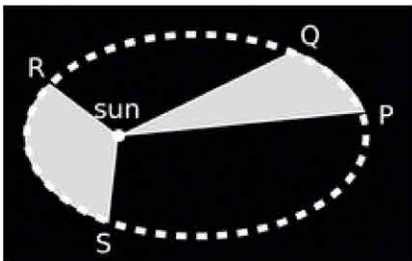
One of the things that most caught Plato's imagination was the existence and uniqueness of what are now called the five "Platonic solids".

It's uncertain who first described all five of these shapes - it may have been the early Pythagoreans - but some sources (including Euclid) indicate that Theaetetus (another friend of Plato's) wrote the first complete account of the five regular solids.

Presumably this formed the basis of the constructions of the Platonic solids that constitute the concluding Book XIII of Euclid's Elements.

In any case, Plato was mightily impressed by these five definite shapes that constitute the only perfectly symmetrical arrangements of a set of (non-planar) points in space, and late in life he expounded a complete "theory of everything", in the treatise called Timaeus, based explicitly on these five solids.

Interestingly, almost 2000 years later, Johannes Kepler was similarly fascinated by these five shapes, and developed his own cosmology from them

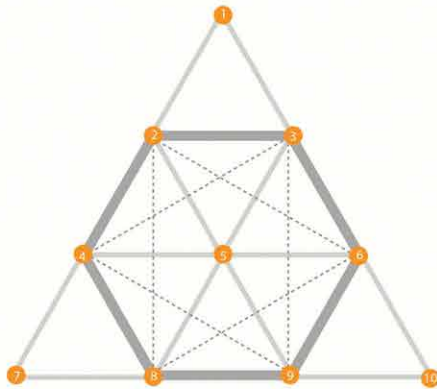


Tetractys

The Greek Tetractys is a triangular figure consisting of ten points arranged in four rows:

one, two, three, and four points in each row, which is the geometrical representation of the fourth triangular number.

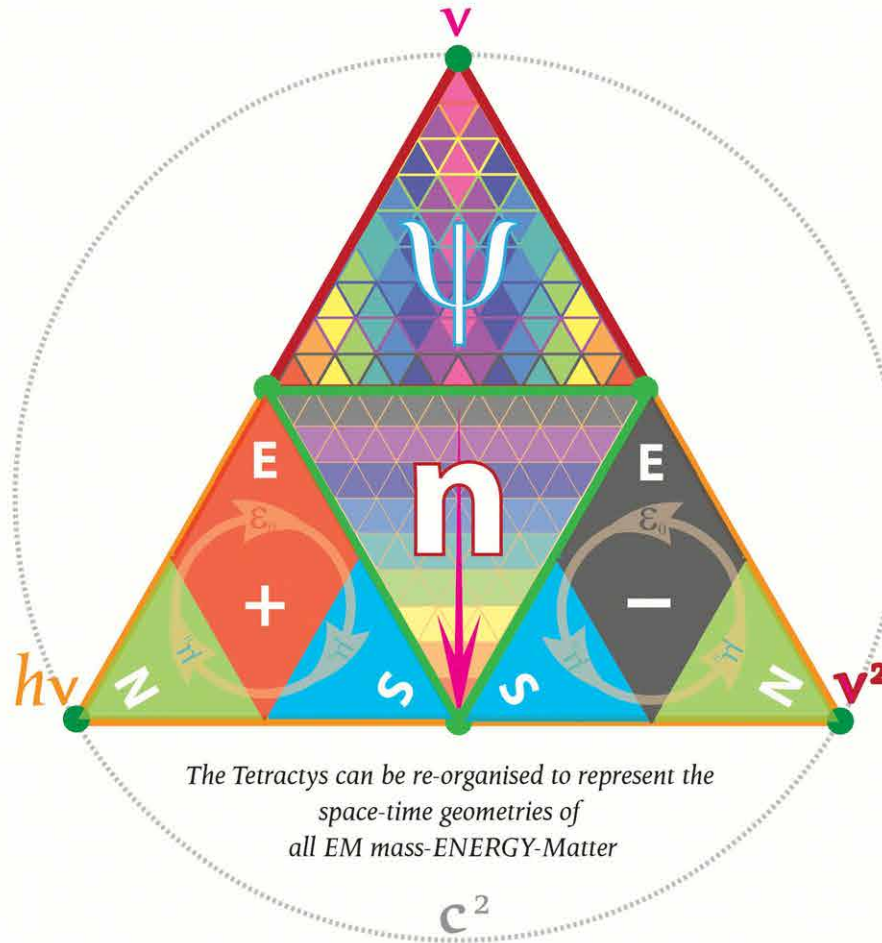
As a mystical symbol, it was very important to the secret worship of the Pythagoreans.



Sacred numbers



The Tetractys historically symbolized the four elements [Earth, Air, Fire, and Water] and the relationship between Humanity and the cosmos created by GOD

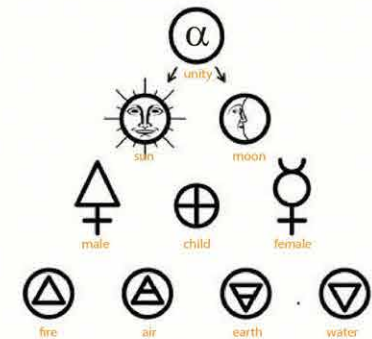


The Tetractys can be re-organised to represent the space-time geometries of all EM mass-ENERGY-Matter

- The single triangle in the first row represents zero-dimensions (a point)
- A vector direction in one-dimension can be represented as a line between any two points
- The second row represents a Boson (two-dimensions in a plane defined by a rhombus of three triangles)
- The whole figure folded represents three-dimensions (a tetrahedron defined by four apex points)
- Photons of ElectroMagnetic mass-Energy quanta are represented by two opposing triangles

The tetrad was the name given to the number four - in Pythagorean philosophy there were four seasons and four elements, and the number was also associated with planetary motions and music

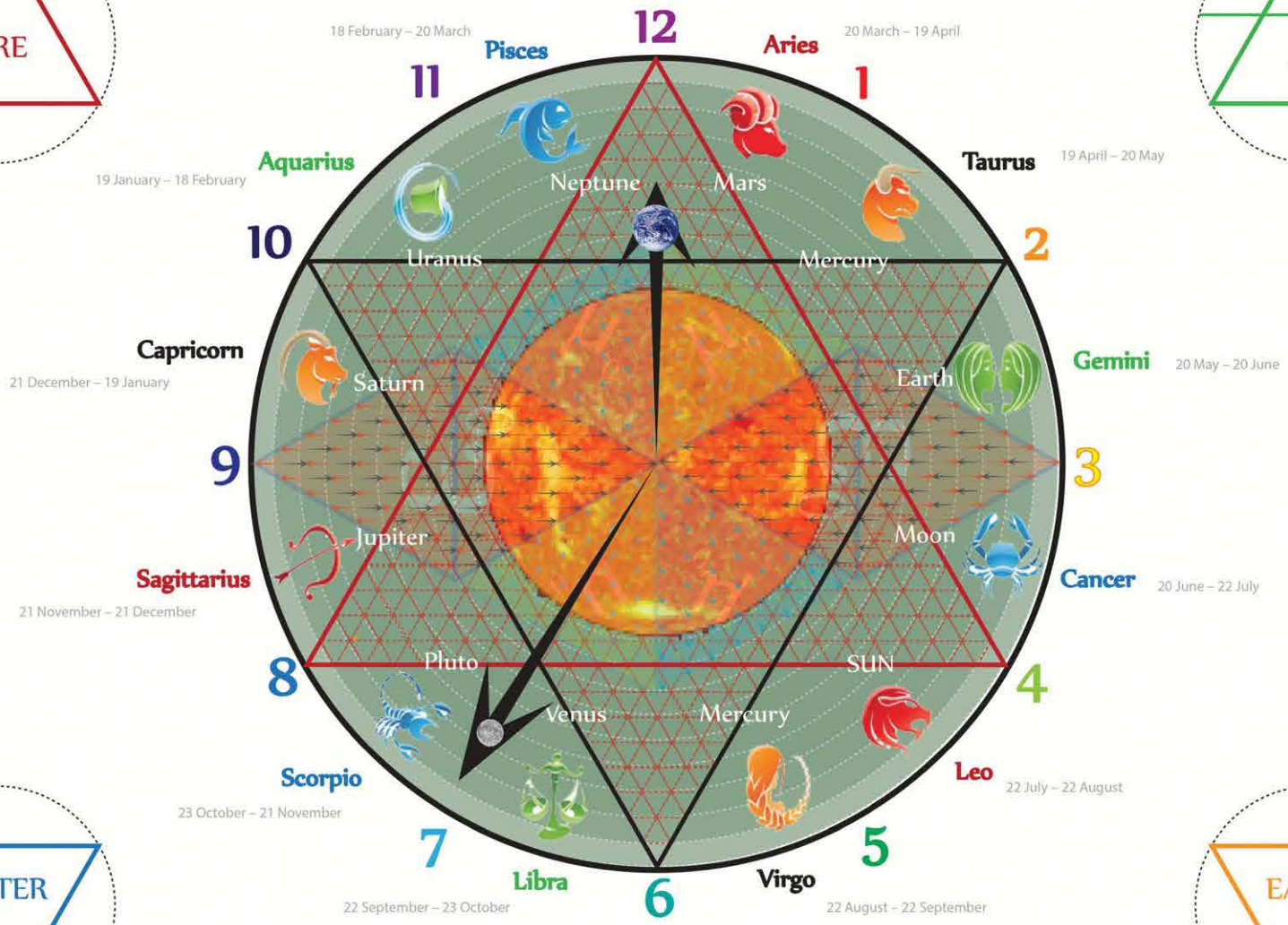
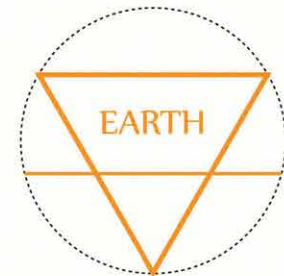
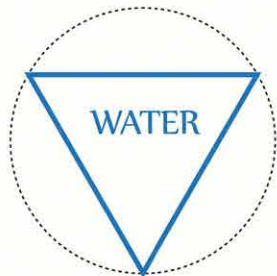
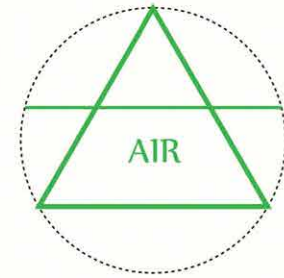
As a mystical symbol, it was very important to the secret worship of the Pythagoreans.



The Cosmos



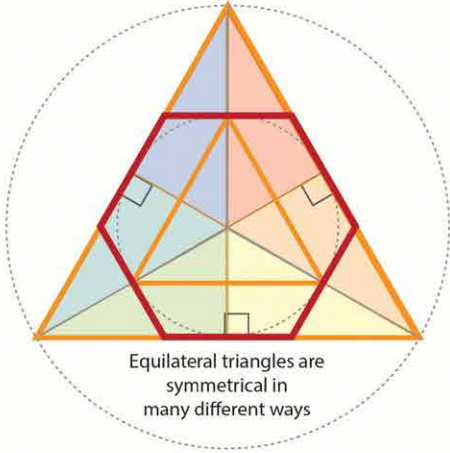
The Greek Zodiac



The Greek Elements

Equilateral Triangles

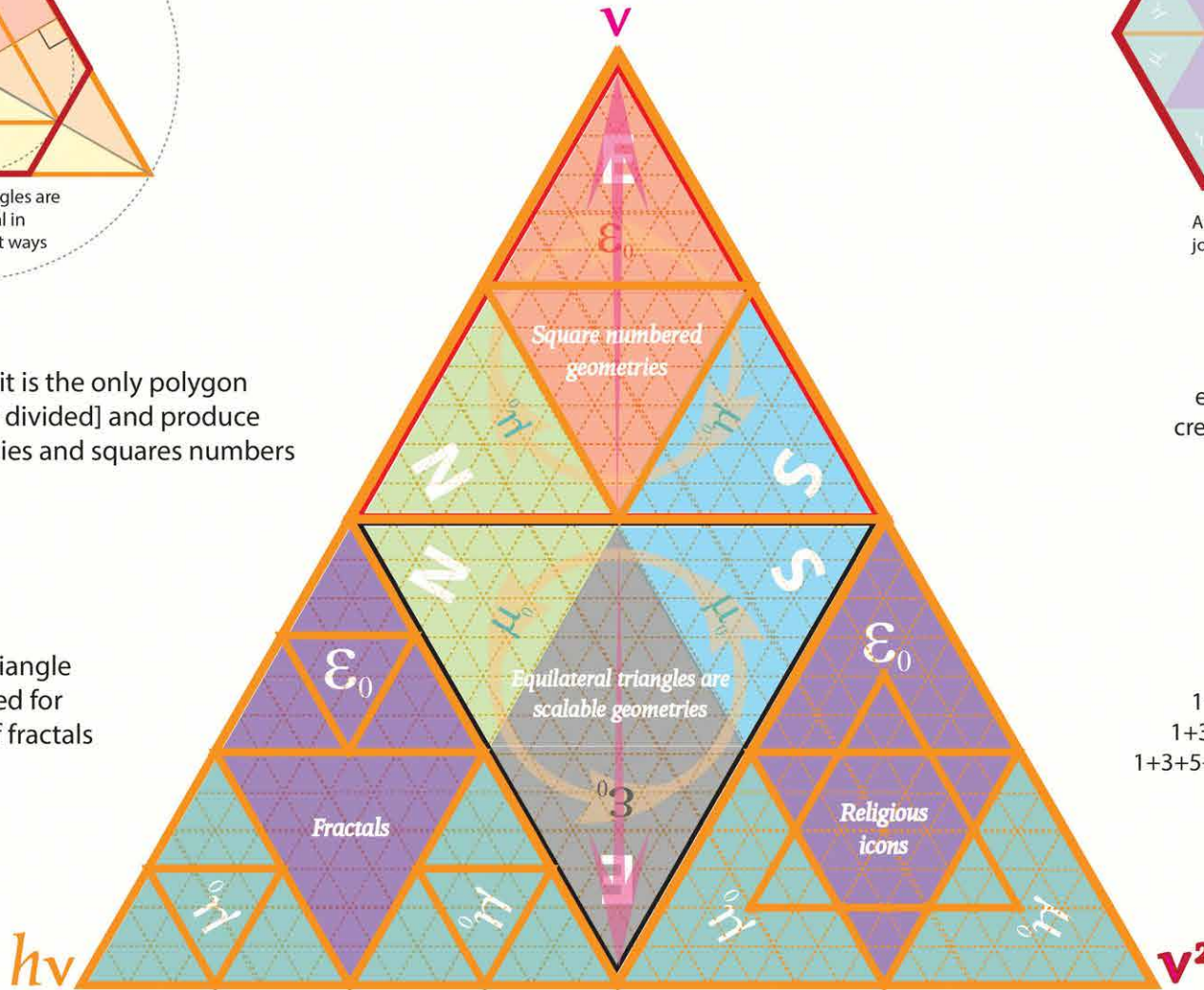
An equilateral triangle is a triangle in which all three sides are equal



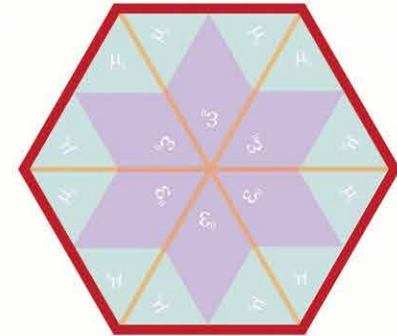
Equilateral triangles are symmetrical in many different ways

It is unique in that it is the only polygon that can be tiled [or divided] and produce only identical geometries and squares numbers

The equilateral triangle is eminently suited for the construction of fractals



An equilateral triangle is simply a specific case of a regular polygon with 3 sides



Any six equilateral triangles joined can make a hexagon.

The tessellation of odd numbered equilateral triangles creates square numbers

That is,

$$\begin{aligned}
 &1 \\
 &1+3 = 4 \\
 &1+3+5 = 9 \\
 &1+3+5+7 = 16 \\
 &1+3+5+7+9 = 25 \\
 &1+3+5+7+9+11 = 36 \\
 &1+3+5+7+9+11+13 = 49 \\
 &1+3+5+7+9+11+13+15 = 64 \\
 &\text{etc}
 \end{aligned}$$

The Pythagorean Theorem

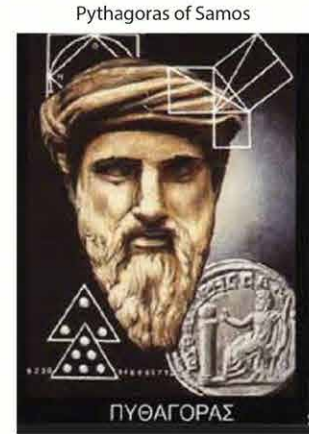
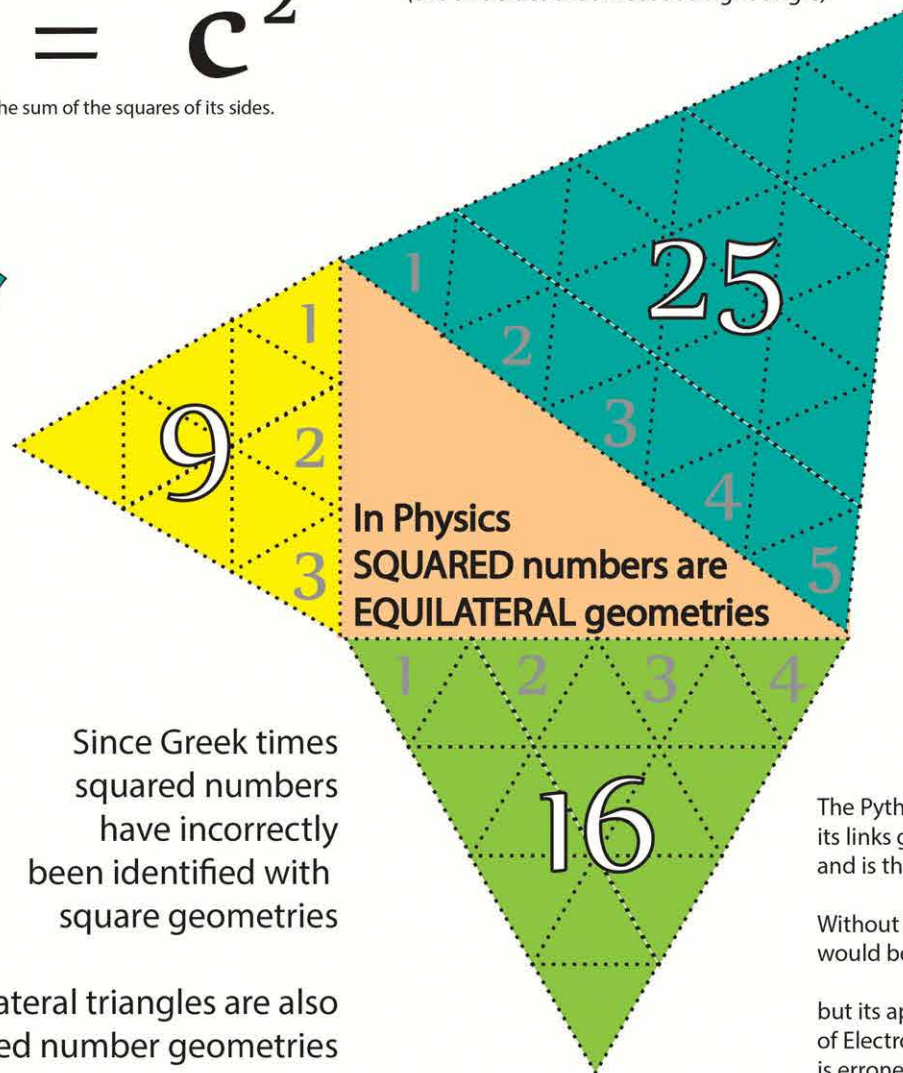
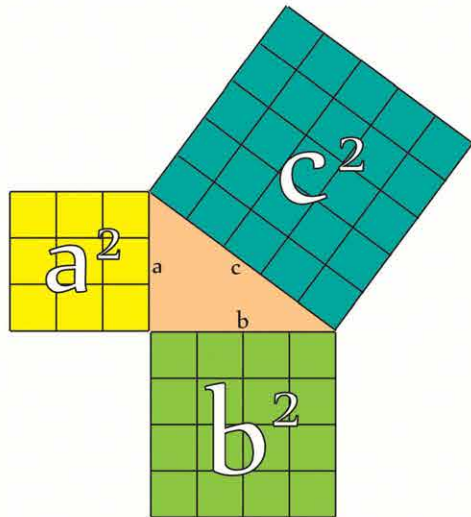
Though attributed to Pythagoras, it is not certain that he was the first person to prove it.

The first clear proof came from Euclid, and it is possible the concept was known 1000 years before Pythagoras by the Babylonians

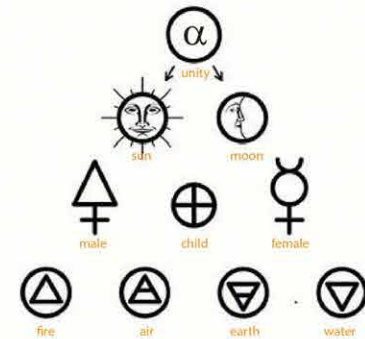
$$a^2 + b^2 = c^2$$

The square of the hypotenuse of a triangle is equal to the sum of the squares of its sides.

*In any right triangle,
the area of the square whose side is the hypotenuse
(the side opposite the right angle) is equal to
the sum of the areas of the squares
whose sides are the two legs
(the two sides that meet at a right angle)*



Pythagoras of Samos
about (570 – 495 BC)



Pythagorean Tetractys



Since Greek times squared numbers have incorrectly been identified with square geometries

Equilateral triangles are also squared number geometries

The Pythagorean equation is at the core of much of geometry, it links geometry with algebra, and is the foundation of trigonometry.

Without it, accurate surveying, mapmaking, and navigation would be impossible,

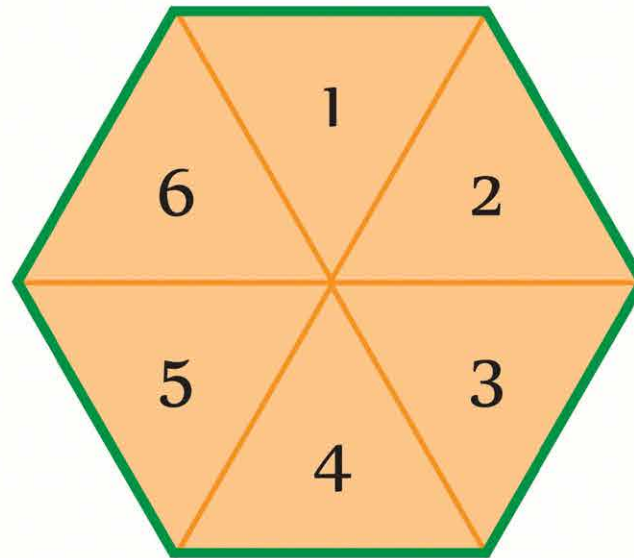
but its application to the energy-momenta geometries of ElectroMagnetic fields and Matter in motion in Physics is erroneous and must be corrected for science to advance

Hexagons

A regular hexagon can be subdivided into six equilateral triangles



Hexagons are the only regular polygon that can be subdivided into another regular polygon

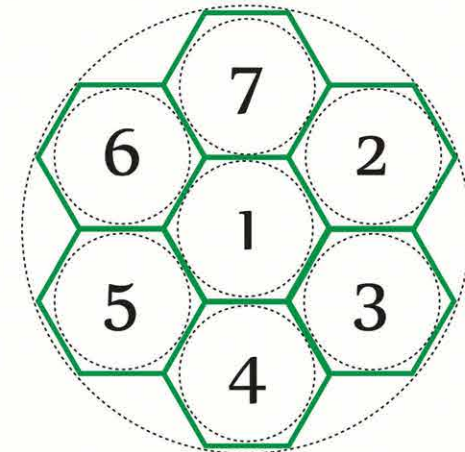


Hexagons are the unique regular polygon such that the distance between the center and each vertex is equal to the length of each side

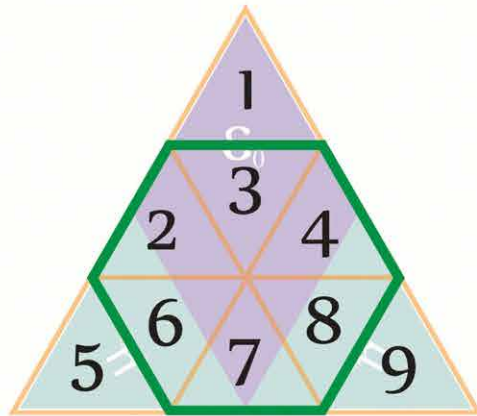
Six is a highly composite number, the second-smallest composite number, and the first perfect number.

$$\text{That is, } 1 \cdot 2 \cdot 3 = 1 + 2 + 3 = 6$$

An interesting relationship between circular and hexagonal geometry is that hexagonal patterns often appear spontaneously when natural forces are trying to approximate circles

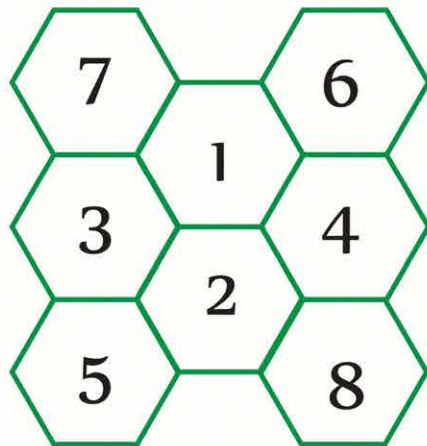


Hexagonal tessellation is topologically identical to the close packing of circles on a plane



Energy geometries

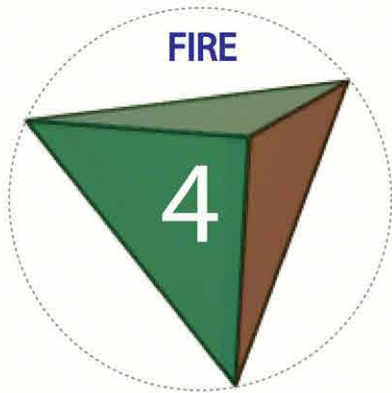
Atomic nuclei geometries



Hexagons can be tiled or tessellated in a regular pattern on a flat two-dimensional plane

Platonic Solids

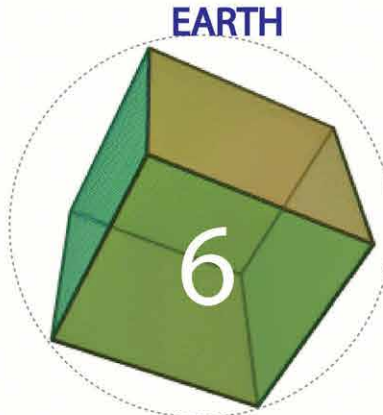
The Pythagoreans knew that there were only five regular convex solids, the tetrahedron, cube, octahedron, icosahedron and dodecahedron and each one could be accurately circumscribed by a sphere.



FIRE

4

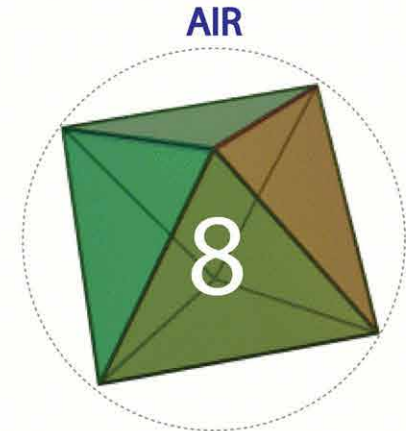
4 triangles meet to form a Tetrahedron



EARTH

6

6 squares meet to form a Cube



AIR

8

8 triangles meet to form an Octahedron

2 tetryons
regular deltahedrons

5 leptons

quarks 7
regular deltahedrons

Baryons 18

$$F - E + V = 2$$

faces edges vertices

Plato



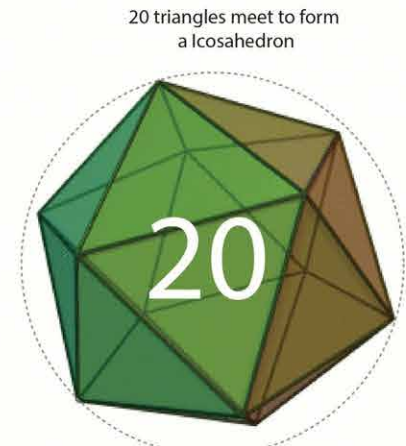
(c.428-348 BC)

The philosopher Plato concluded that they must be the fundamental building blocks – the atoms – of nature, and assigned to them what he believed to be the essential elements of the universe.



12 pentagons meet to form a Dodecahedron

THE HEAVENS



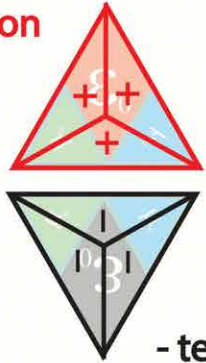
20 triangles meet to form an Icosahedron

WATER

Tetryonic Solids

+ tetryon

4 faces
6 edges
4 vertices

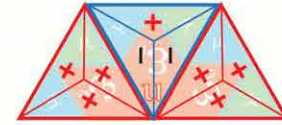


2

- tetryon

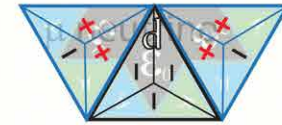
Despite their unique topologies Tetryonic solids are not unlike Platonic solids save that their topologies are comprised entirely from complex hitherto undescribed $4n\pi$ equilateral Planck mass-energy momenta geometries that also match the Euler numbers of Platonic solids

up quark



2

8 faces
12 edges
6 vertices



down quark

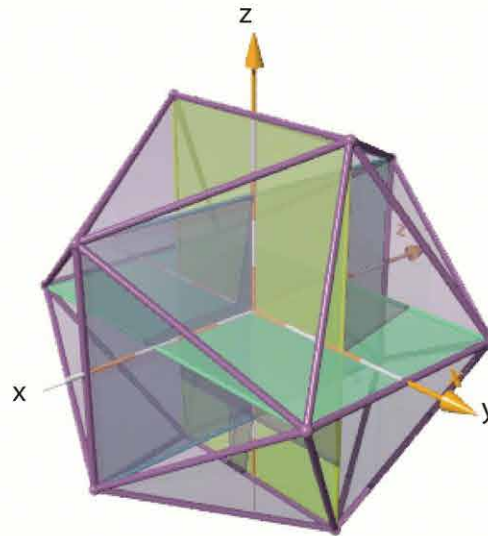
mass geometries

4π tetryons 4π

regular
deltahedrons

Matter topologies

12π leptons 12π



Matter topologies

8π quarks 12π

regular
deltahedrons

mass geometries

20π Baryons 36π

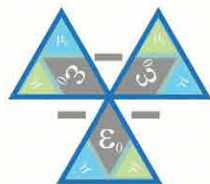


12 faces
18 edges
8 vertices

neutrino

electron

2



Their equilateral topologies are best described as regular topologic-deltahedrons:

tetra-delta-hedrals
octa-delta-hedrals
dodeca-delta-hedrals
icosa-delta-hedrals

tetryons
quarks
leptons
Baryons

4π external charge fascia
 8π external charge fascia
 12π external charge fascia
 20π external charge fascia

note:

Charged mass-energy fascia geometries and edges become "hidden" upon the meshing of delta-hedra to form Matter topologies



2

Neutron

20 faces
30 edges
12 vertices

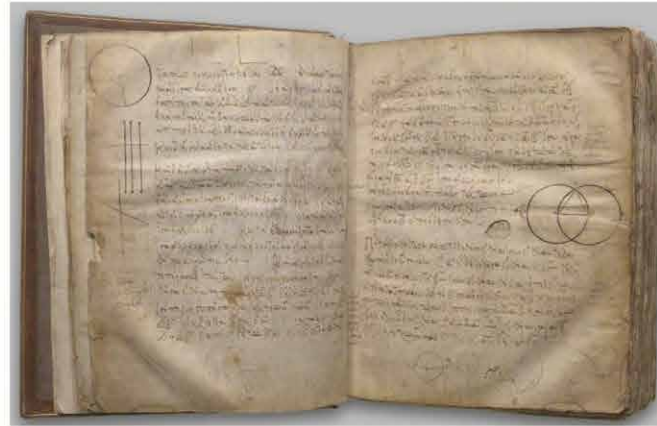


Proton

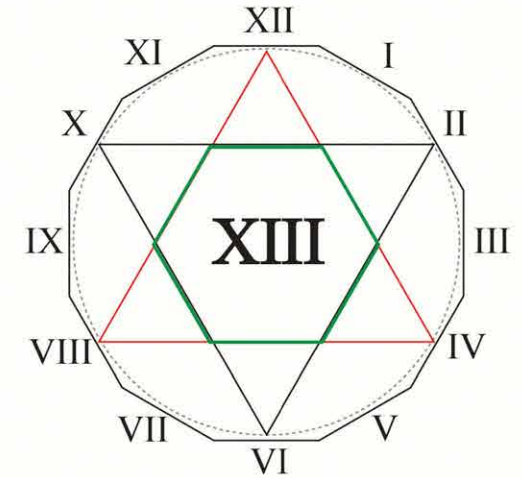
Euclidean geometry



(c.330-275 BC, fl. c.300 BC)



Arguably the most influential Mathematics book ever written is Euclid's 'The Elements'

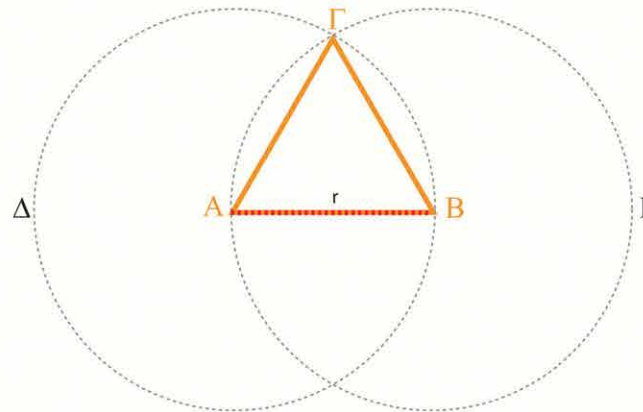


In all, it contains 465 theorems and proofs, described in a clear, logical and elegant style, and using only a compass and a straight edge.

The Elements - Book 1 - Definition 20



Of the trilateral figures, an equilateral triangle is that which has its three EQUAL sides



Euclid's Elements - Book 1 - Proposition 1
Method of constructing an Equilateral triangle

Euclid's five general axioms were:

Things which are equal to the same thing are equal to each other.

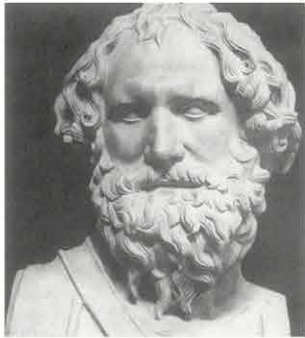
If equals are added to equals, the wholes (sums) are equal.

If equals are subtracted from equals, the remainders (differences) are equal.

Things that coincide with one another are equal to one another.

The whole is greater than the part

Archimedes



c. (287 BC – c. 212 BC)

As its definition relates to the circle, π is found in many formulae in trigonometry and geometry, especially those concerning circles, ellipses, or spheres.

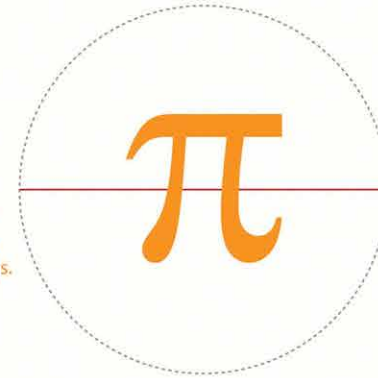
It is also found in formulae from other branches of science, such as cosmology, number theory, statistics, fractals, thermodynamics, mechanics, and electromagnetism

Incorrect identification of Pi [c/d] as opposed to Pi radians in Physics has led to the inappropriate association of spherical particles to the physical sciences whereas equilateral triangles & tetrahedra form its true geometry

The number π is a mathematical constant that is the ratio of a circle's circumference to its diameter.

Pi

π is an irrational number its decimal representation never ends and never repeats.



$$\pi = c/d$$

The ratio C/d is constant, regardless of the circle's size

3.141592654.....

Proof of the fact that $C=2\pi r$ and how Archimedes proved it

Draw any circle.

Make a point anywhere on the circumference of the [green] circle.

Use that point as the center of a second [blue] circle with the same radius as the green circle.

The edge of the blue circle should touch the center of the green circle.

Draw the line segment connecting the centers of the two circles.

That forms the radius of both of the circles.

Now draw the line connecting the center of the blue circle to where it crosses the green circle on both sides, and complete the triangles.

You should have two equilateral triangles whose sides are equal to the radius of the green circle

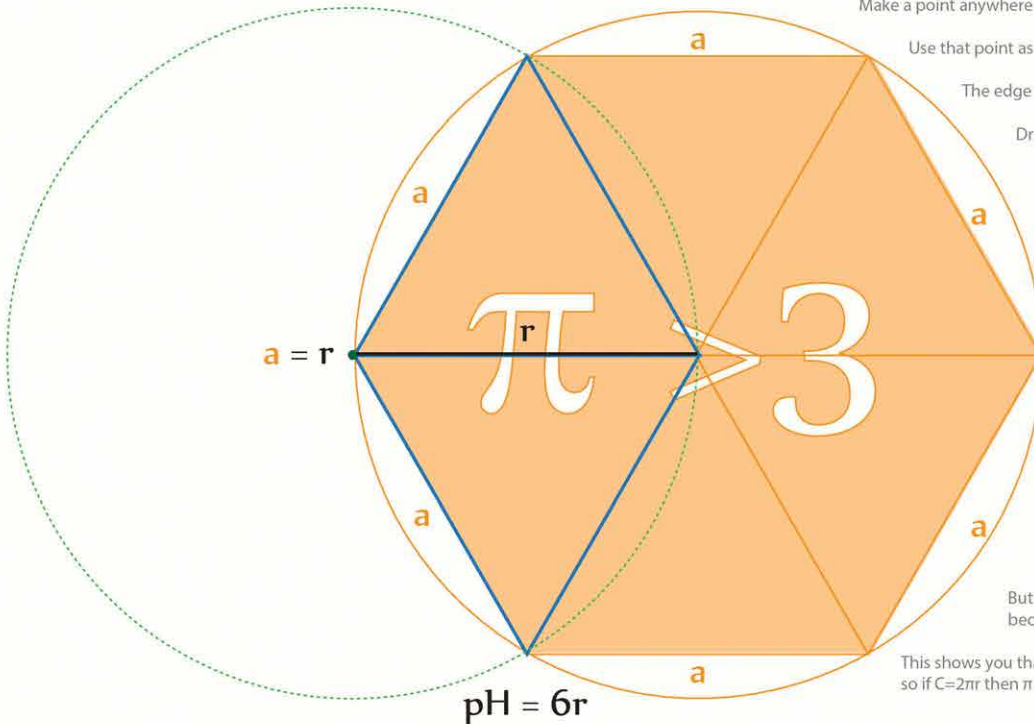
Now extend all of the radius lines so they become diameter lines, all the way across the circle, and finish drawing all of the triangles to connect them.

You've got six equilateral triangles now, that make an orange hexagon.

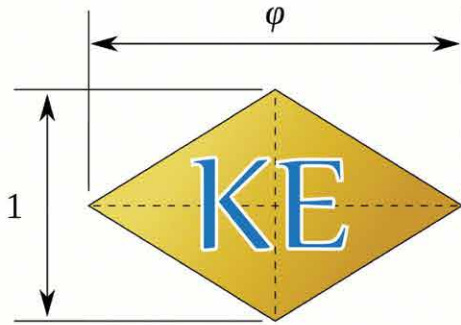
So the perimeter of your hexagon is the same as six times the radius of your circle.

But your circumference is a little bigger than the perimeter of your hexagon, because the shortest distance between two points is always a straight line.

This shows you that the circumference of the blue circle has to be more than $6r$, so if $C=2\pi r$ then π (pi) has to be a little bigger than 3, which it is.



The more sides we draw on our polygon, the closer we will get to the real value of pi (3.14159 etc.). Using a polygon with 96 sides, Archimedes was able to calculate that π was a little bigger than 3.1408

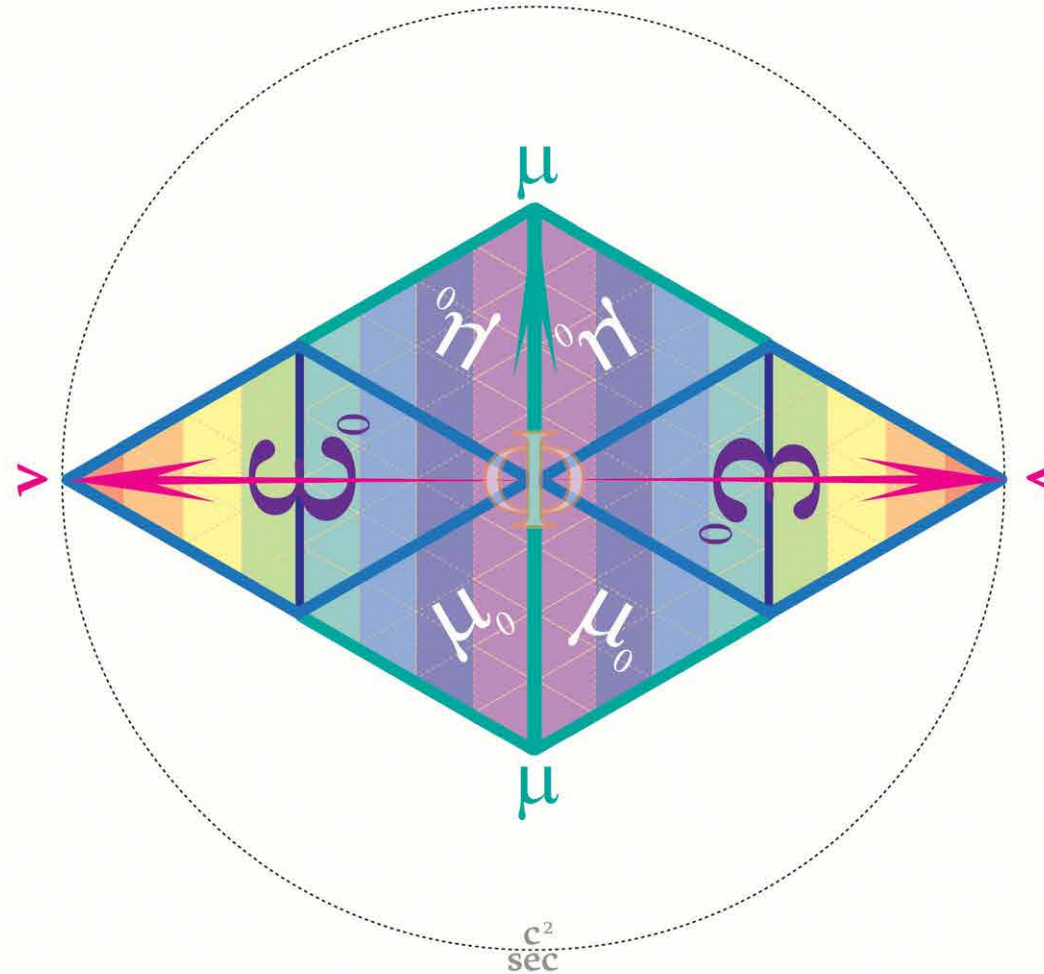


The Golden Rhombus

Applying the golden ratio (ϕ) to quantum scale electrodynamic geometry we can quickly determine that the linear momentum and magnetic moment vectors of photons & EM waves can also be expressed as a golden ratio

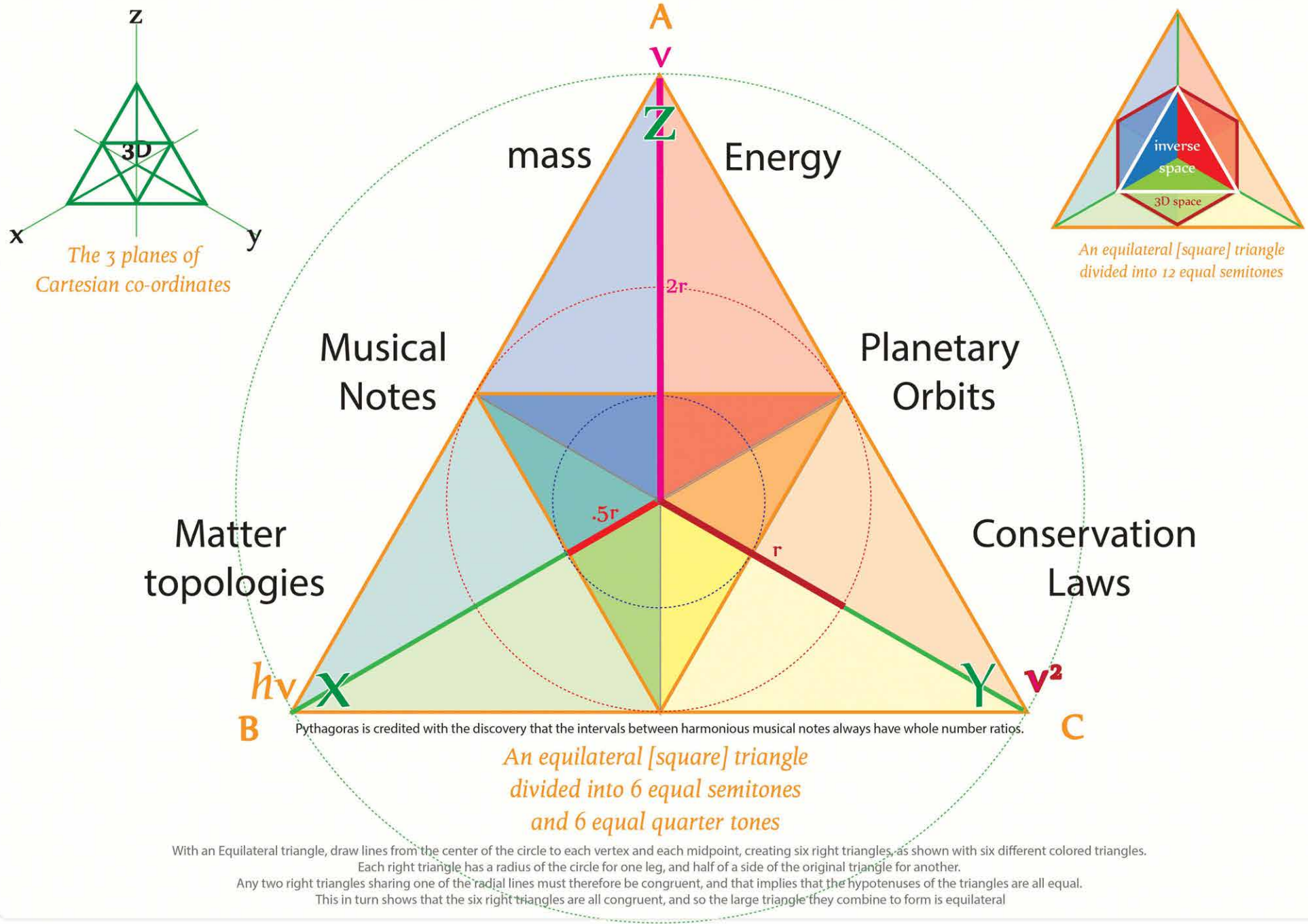
vector velocities
VS
magnetic vector

Φ
Golden ratio phi
[1.61803]

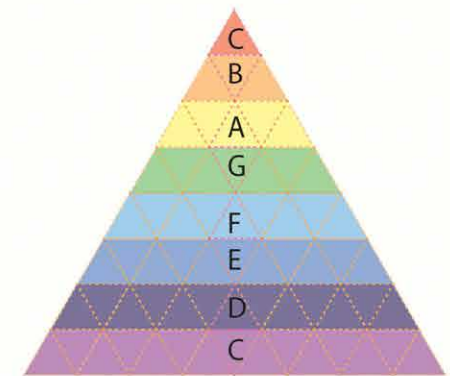
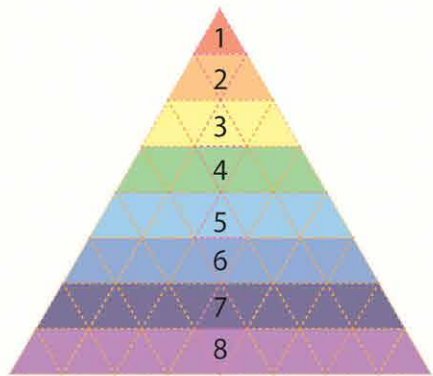
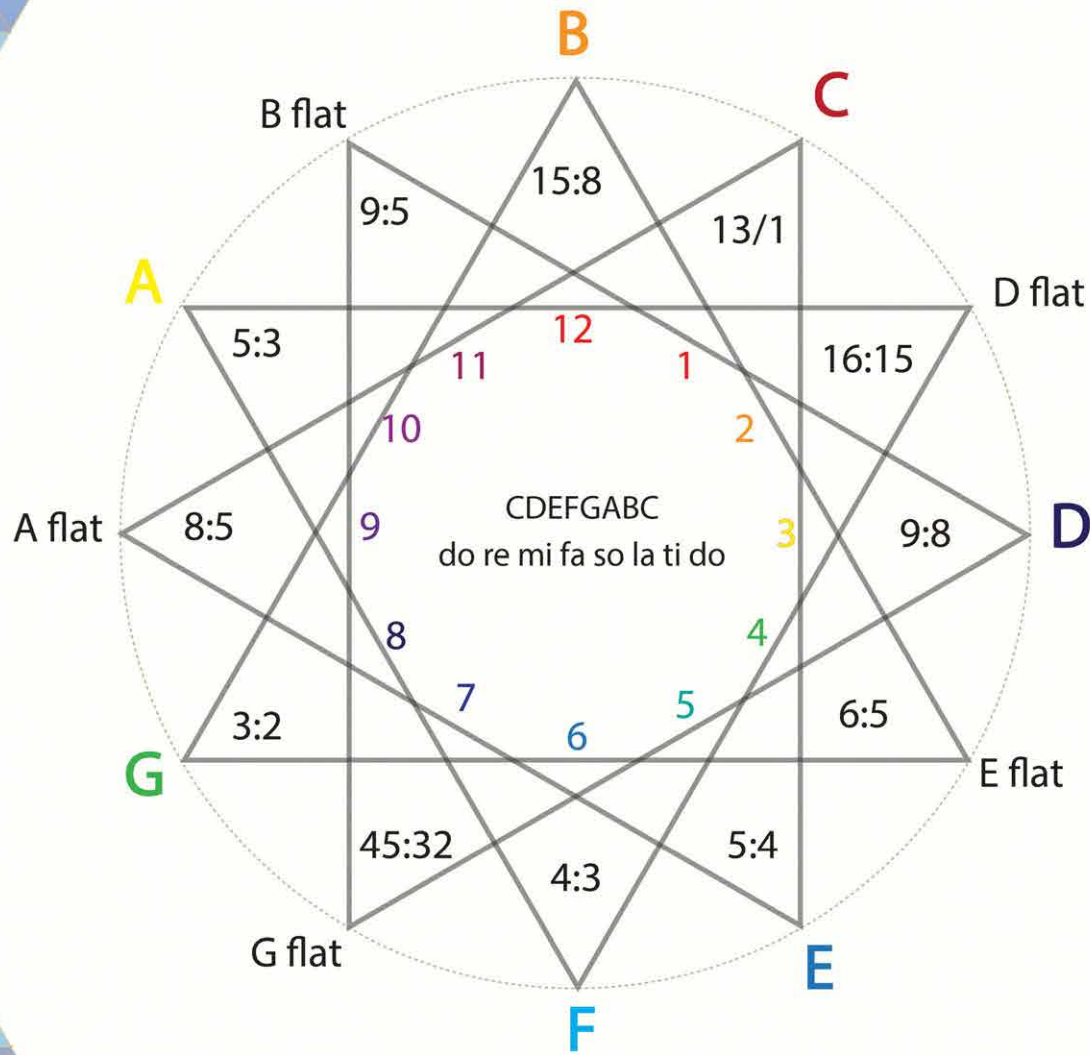
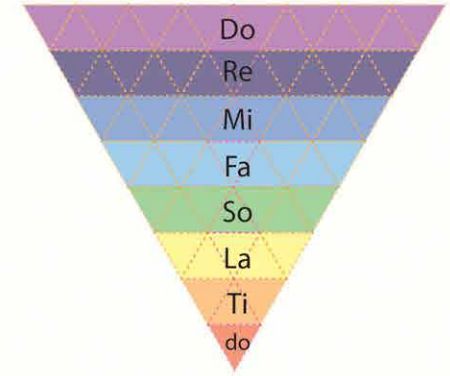
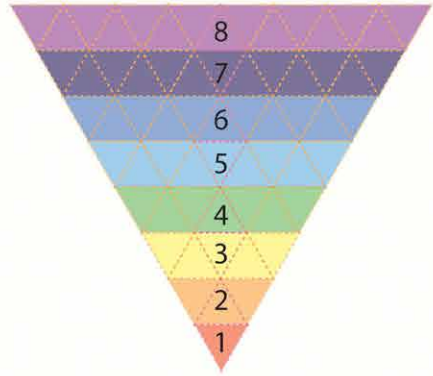


magnetic Force
VS
electric Force

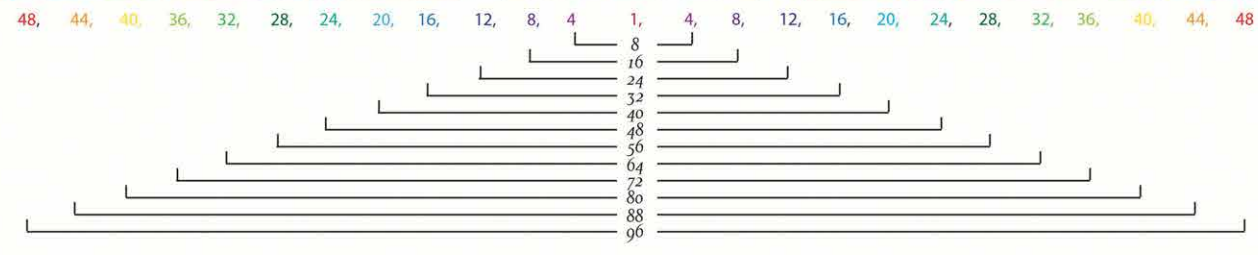
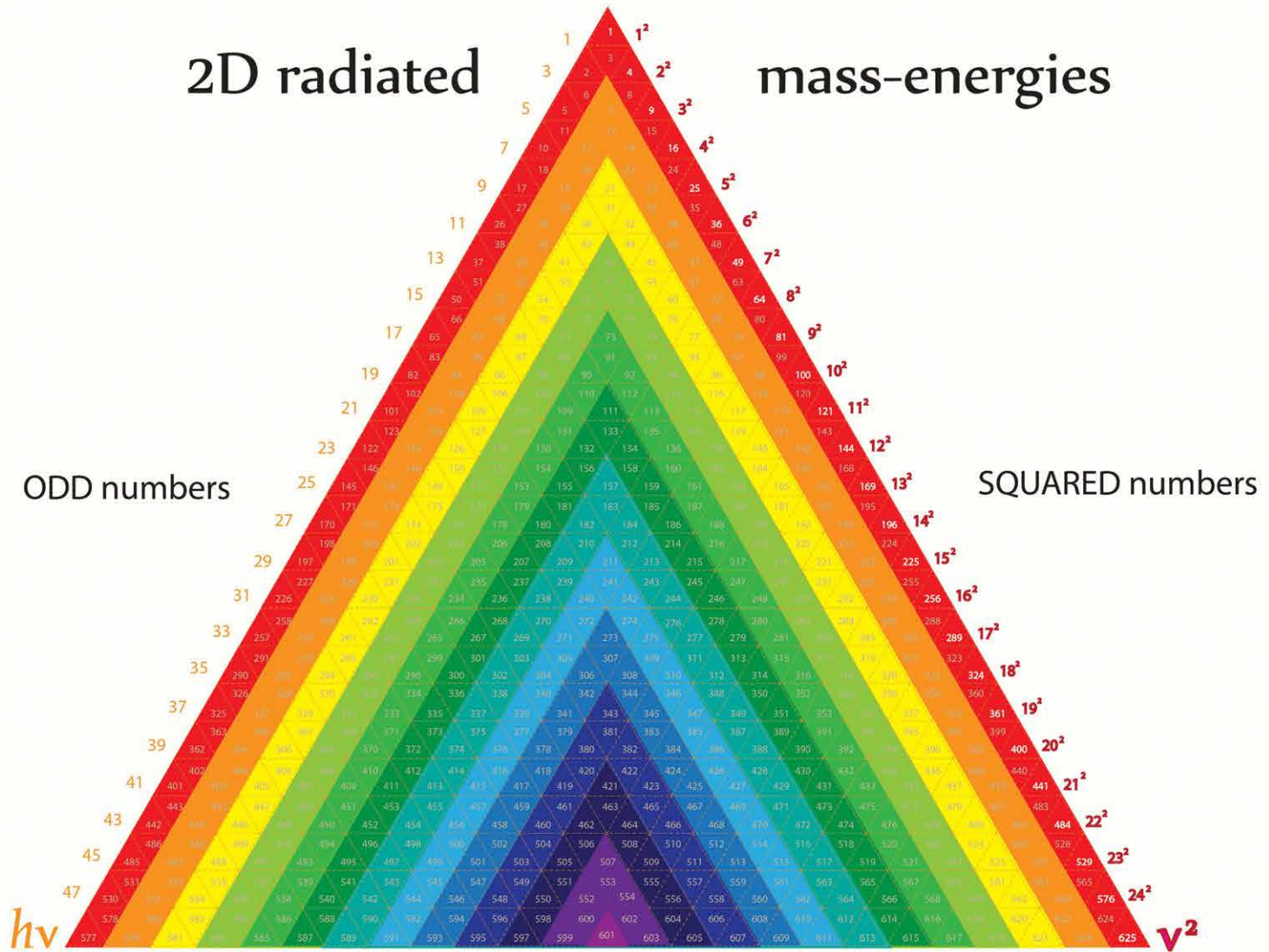
photons
of
EM energy



Equilateral Fifths



Musical Notes

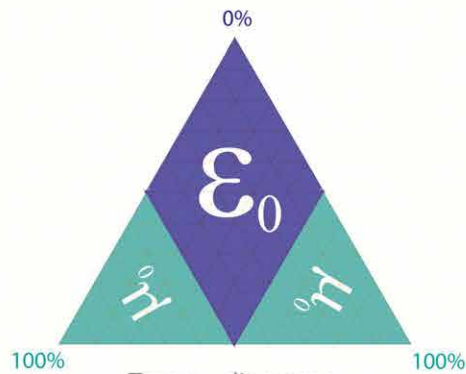


Equilateral

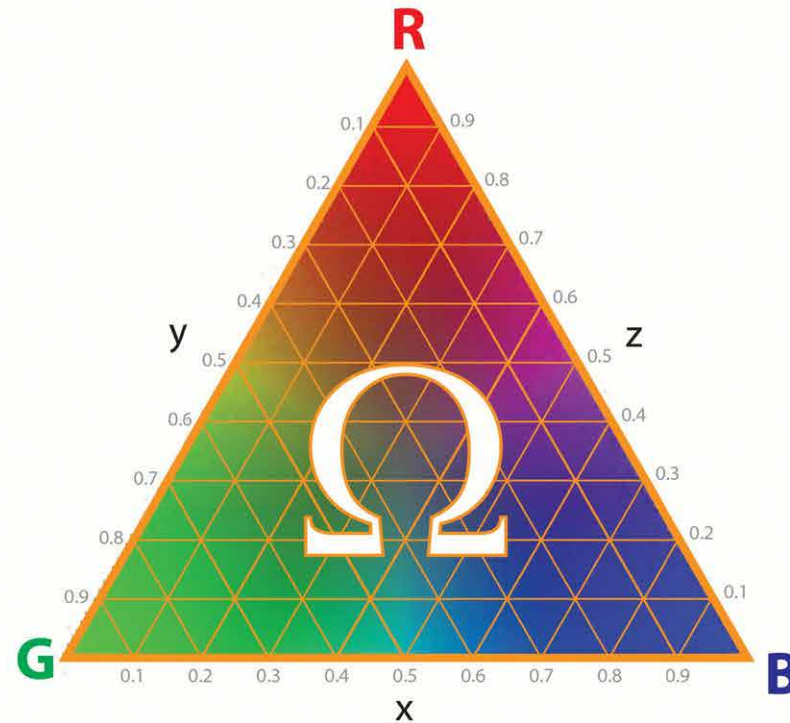
Octaves

Ternary Diagrams

Viviani's Theorem implies that lines parallel to the sides of an equilateral triangle provide (homogeneous/barycentric/areal/trilinear) coordinates for ternary diagrams for representing three quantities A,B,C whose sum is a constant (which can be normalized to unity).

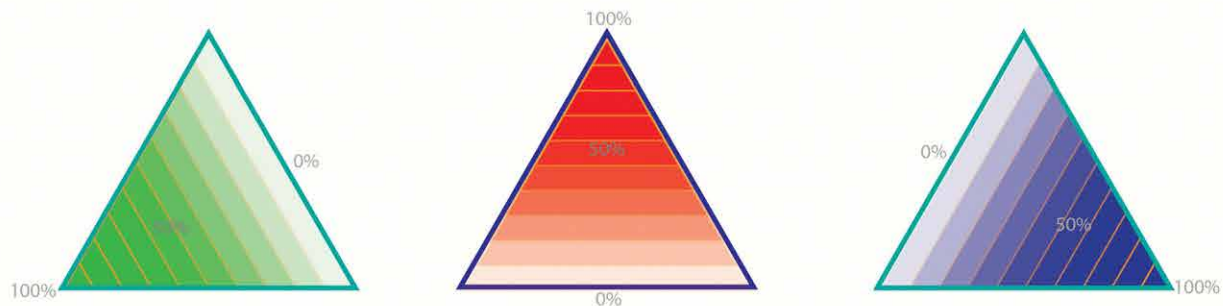


Ternary diagrams should NOT be used to model EM field strengths



In a ternary plot, of EM energy the Electric field [E] and the Magnetic dipole [N-S] must renormalise to 1

A ternary diagram is simply a triangular coordinate system in which the 3 edges correspond to the axes.



Trilinear charts are commonly used for finding the result of mixing three components (such as gases, chemical compounds, soil, color, etc.) that add to 100% of a quantity.

Whilst the Pythagorean Theorem boasts a slightly greater economy of terms than the Eutrigon Theorem (Wayne Roberts 2003), the latter contains an important area not included in the former:

the area enclosed or swept out by the three points of the triangle in question

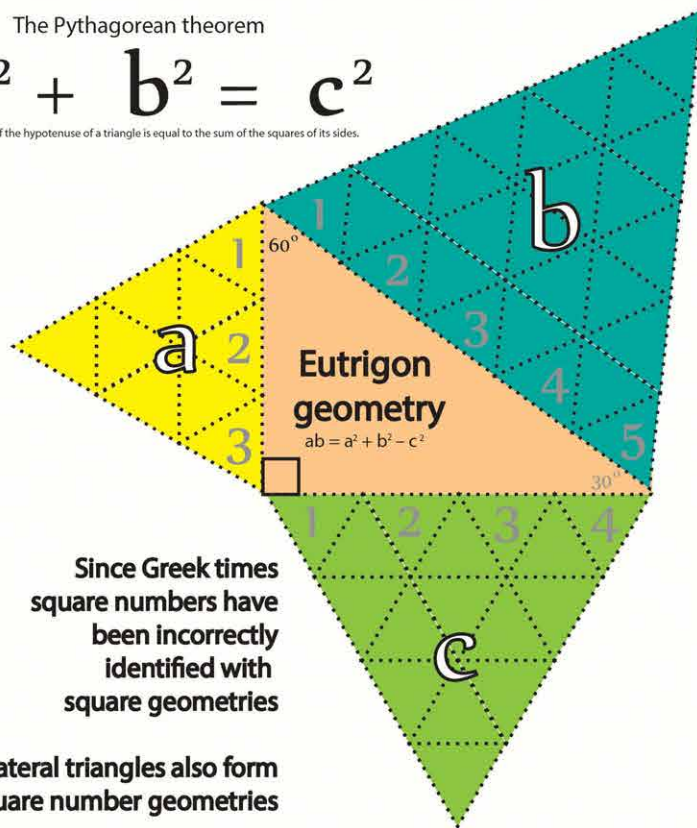
$$ab = a^2 + b^2 - c^2$$

the area of any eutrigon is equal to the combined areas of the equilateral triangles on legs 'a' and 'b', minus the area of the equilateral triangle on its hypotenuse 'c'.

The Pythagorean theorem

$$a^2 + b^2 = c^2$$

The square of the hypotenuse of a triangle is equal to the sum of the squares of its sides.



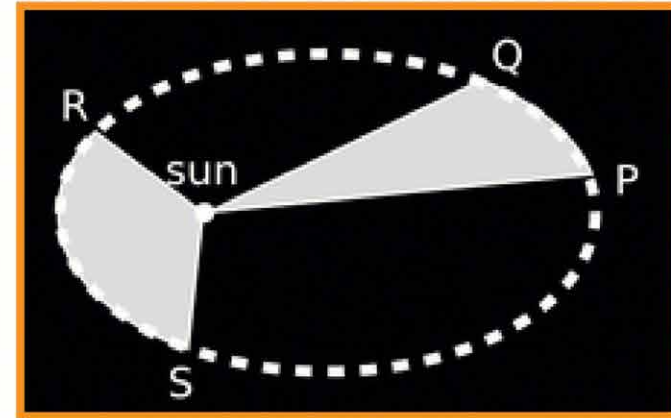
Since Greek times square numbers have been incorrectly identified with square geometries

Equilateral triangles also form square number geometries

Eutrigons

are an important new class of triangle (mathematically defined by Wayne Roberts), as the analogue of the right-triangle in orthogonal (Cartesian) coordinate geometry

Kepler's Second Law of planetary motion



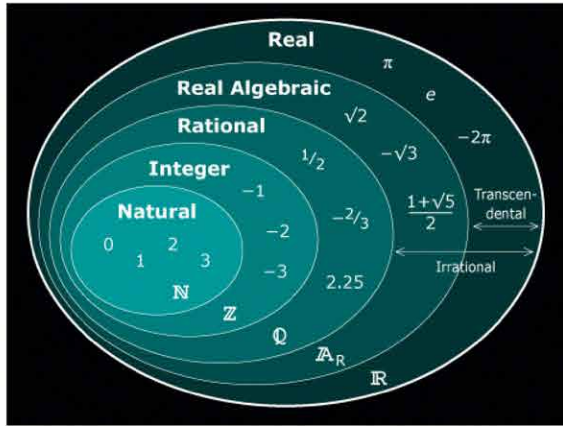
The orbit of every planet is an ellipse with the Sun at one of the two foci.

A line joining a planet and the Sun sweeps out equal areas during equal intervals of time.

The algebraic form of the Eutrigon Theorem, (like the algebraic form of Pythagoras' Theorem), is proven to be special case of the Cosine Rule...

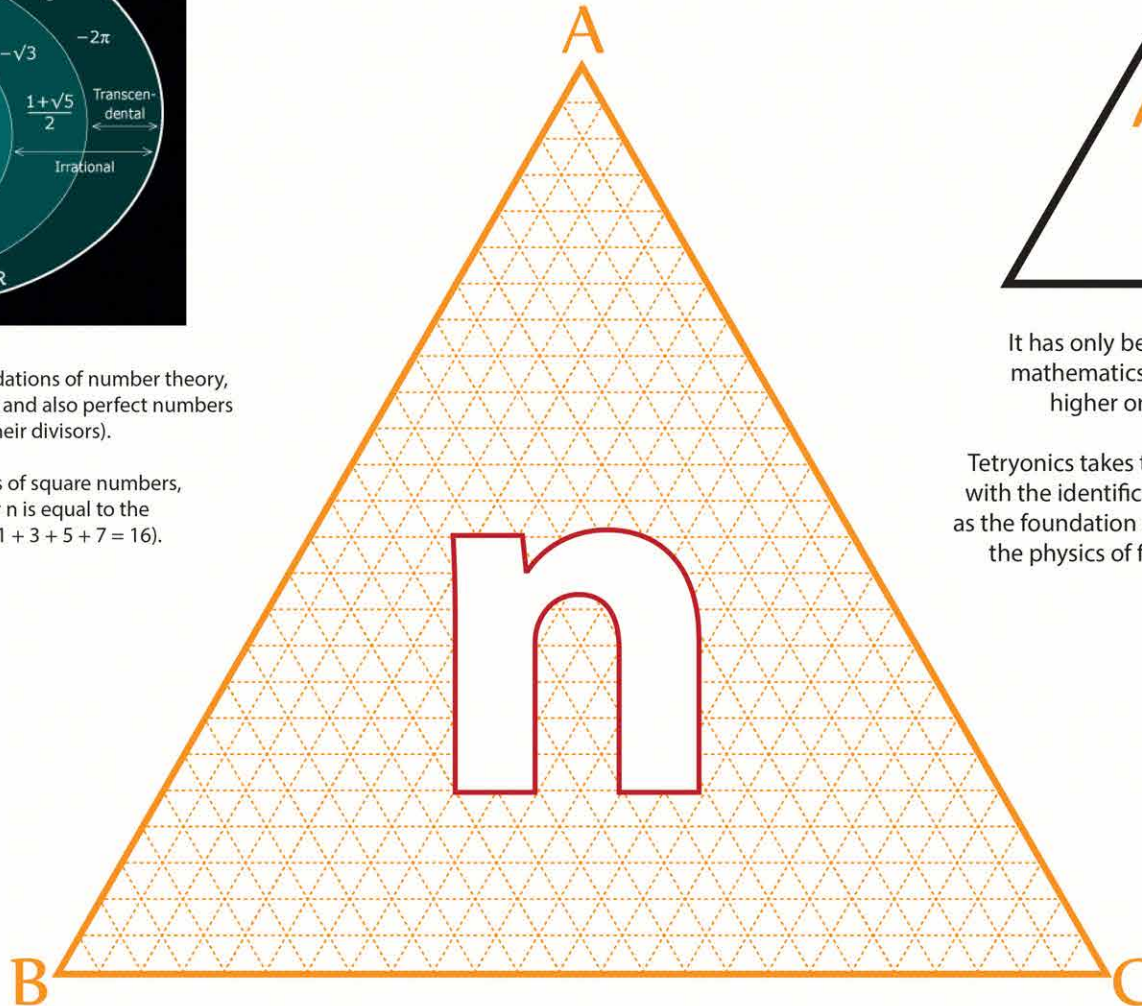
Tetryonic theory reveals the equilateral [square] energy geometry that reveals the 'harmonics at play' in physical laws such as the second law of Kepler, and in many other phenomena in physics, chemistry, cosmology, biochemistry and number theory thus providing the foundation for the mathematics of quantum mechanics

Number theory

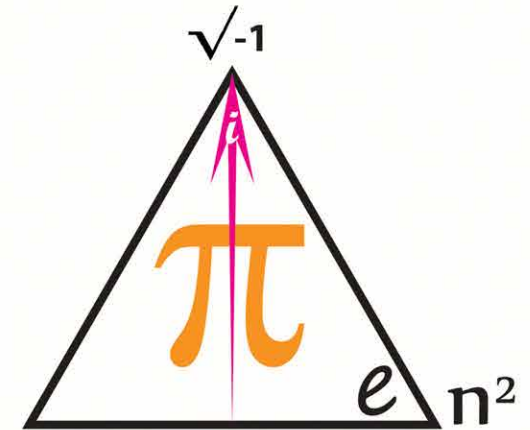


The Pythagoreans also established the foundations of number theory, with their investigations of triangular, square and also perfect numbers (numbers that are the sum of their divisors).

They discovered several new properties of square numbers, such as that the square of a number n is equal to the sum of the first n odd numbers (e.g. $1 + 3 + 5 + 7 = 16$).

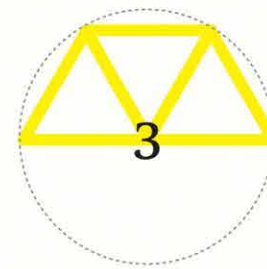
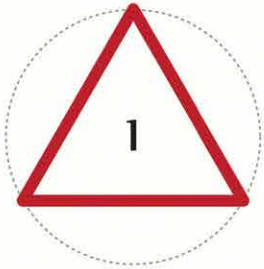


What mathematics has failed to appreciate is the significance application of equilateral geometries to the 'square' numbers of physics and science in general

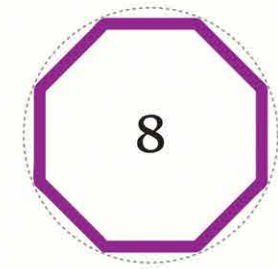
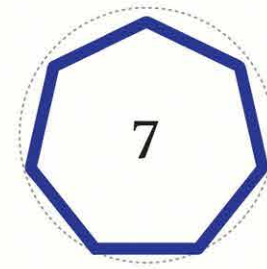
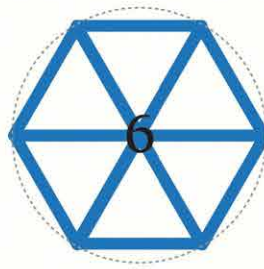
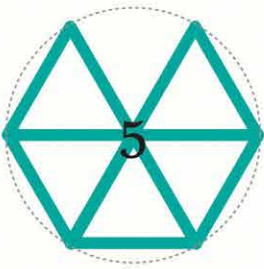


It has only been in recent centuries that mathematics has begun to explore the higher order irrational numbers

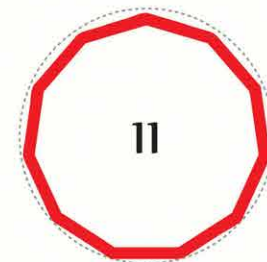
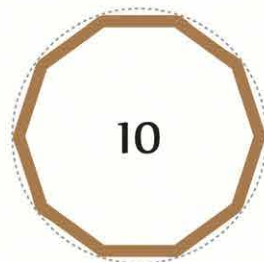
Tetryonics takes this investigation to new levels with the identification of equilateral geometries as the foundation of transcendental numbers and the physics of fields and particles in motion



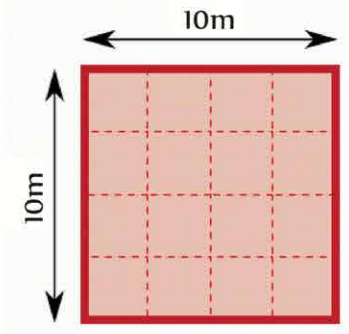
TETRYONICS



COUNTING POLYGONS



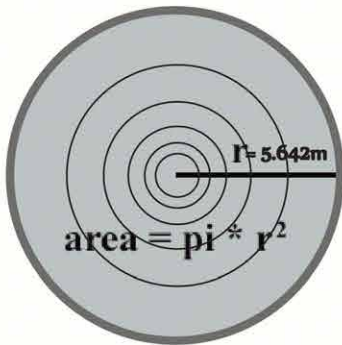
SQUARED energies in quantum mechanics are EQUILATERAL geometries



Square

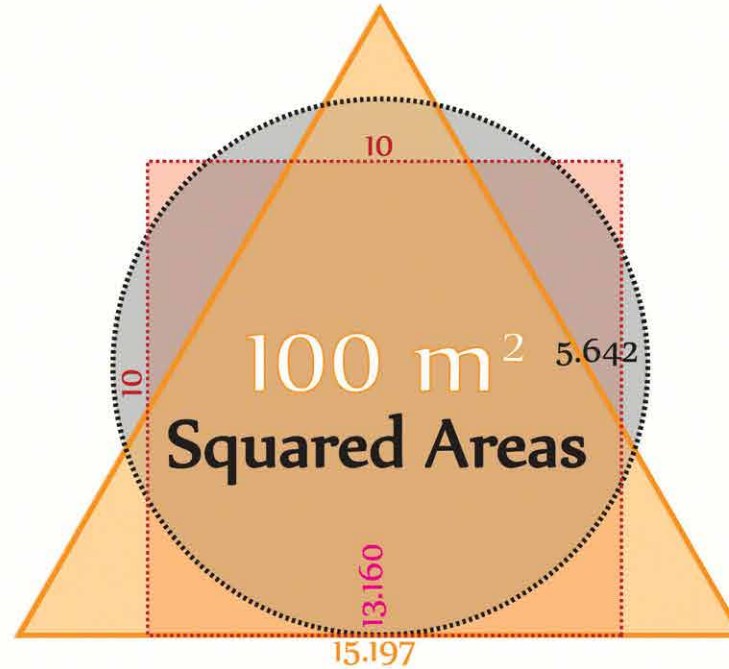
$$\text{area} = s^2 = [100]$$

Circles



$$= \pi * [5.642]^2$$

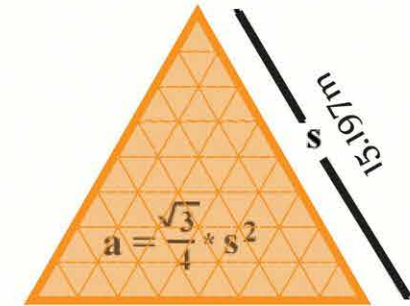
$$= 100$$



can be created by a number of planar geometries

For a long time it has been assumed by scientists (and mathematicians) that circular [and squared] geometries are the geometric foundation of all physics, leading to a seriously flawed model of particles and forces in quantum mechanics

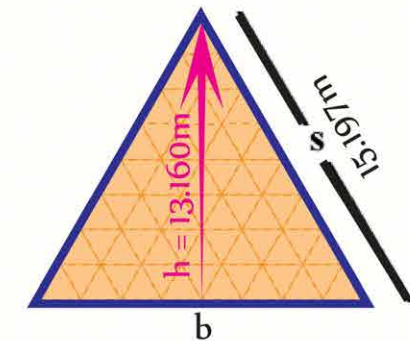
Tetryonic theory now reveals that quantised equilateral angular momenta creates the foundational geometry of all the mass-Energy-Matter & forces of physics



Equilateral

$$\text{area} = \left(\frac{1}{2} * b\right) * h$$

Triangles



$$b \quad h$$

$$[.5 * 15.197] * 13.160$$

$$= 100$$

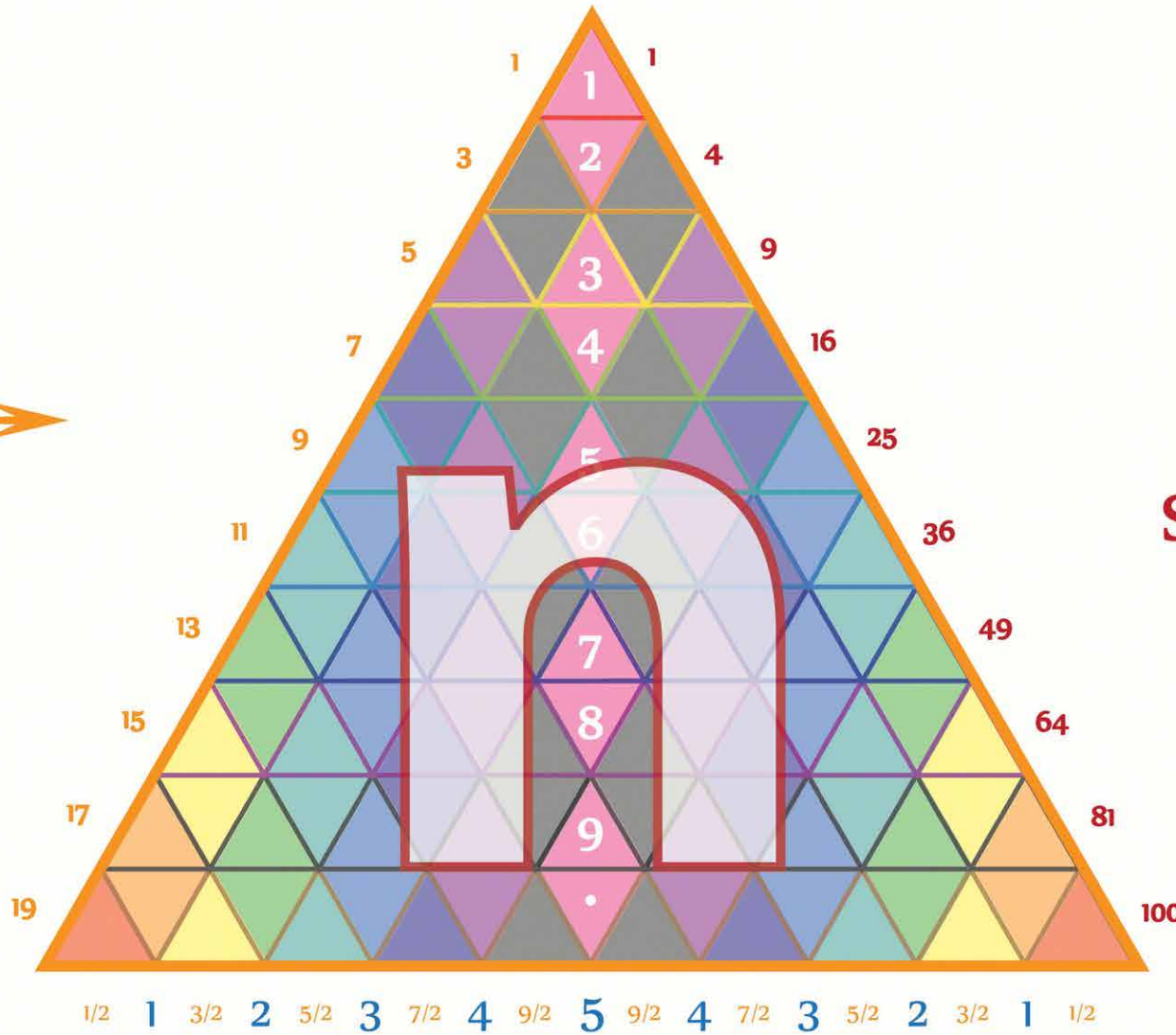
0.987654321

SQUARE ROOTS

80/81

→
ODDS

↓
SQUARES



← EVEN DISTRIBUTIONS →

Integers

The integers (from the Latin integer), literally "untouched", hence "whole" in Tetryonics it is the basis for the Planck charge quantum

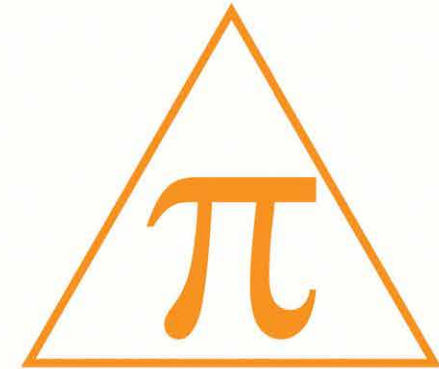


$$2n-1$$

$$[n] + [n-1]$$

Triangular numbered geometries are NOT equilateral geometries

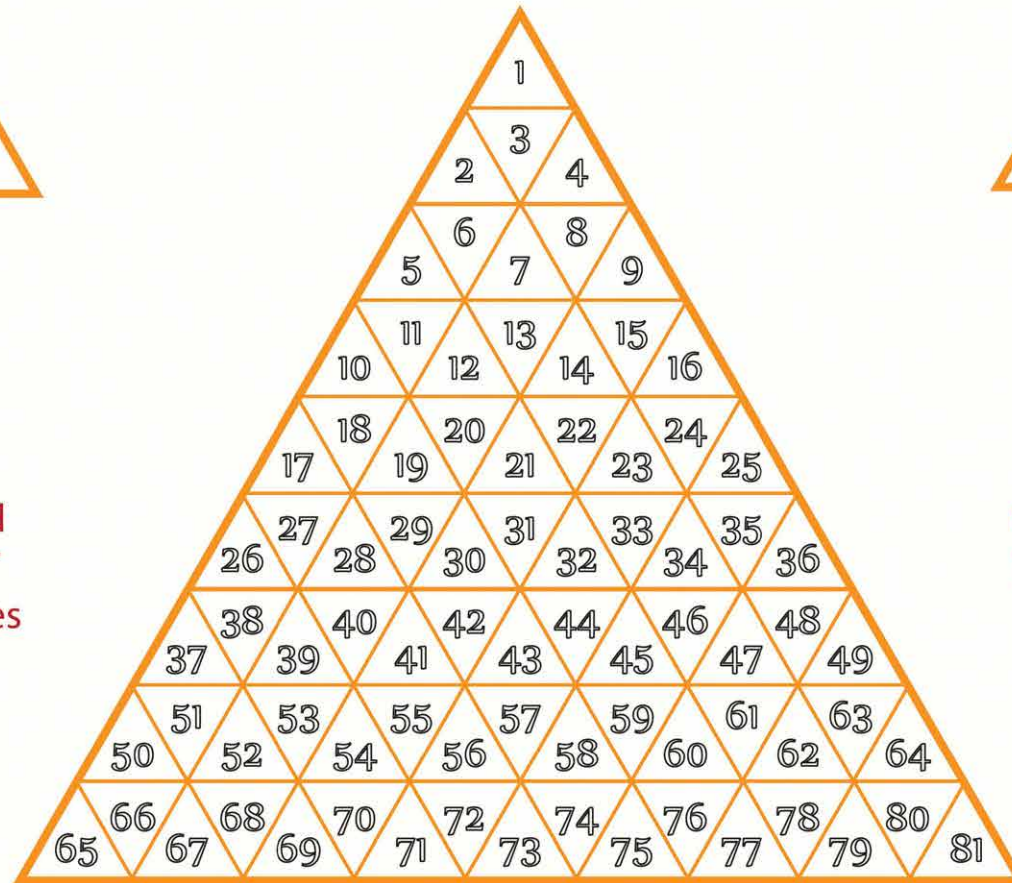
0, 1, 3, 6, 10, 15, 21, 28, 36, 45, 55,



$$\sum_1^n [2n-1]$$

Equilateral geometries form **SQUARE** number geometries

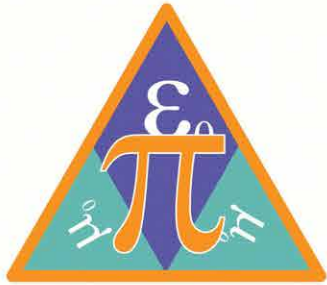
1, 4, 9, 16, 25, 49, 64, 81, 100, 121, 144,



1 2 3 4 5 6 7 8 9 8 7 6 5 4 3 2 1

Equilateral energy quanta form a normal longitudinal distribution

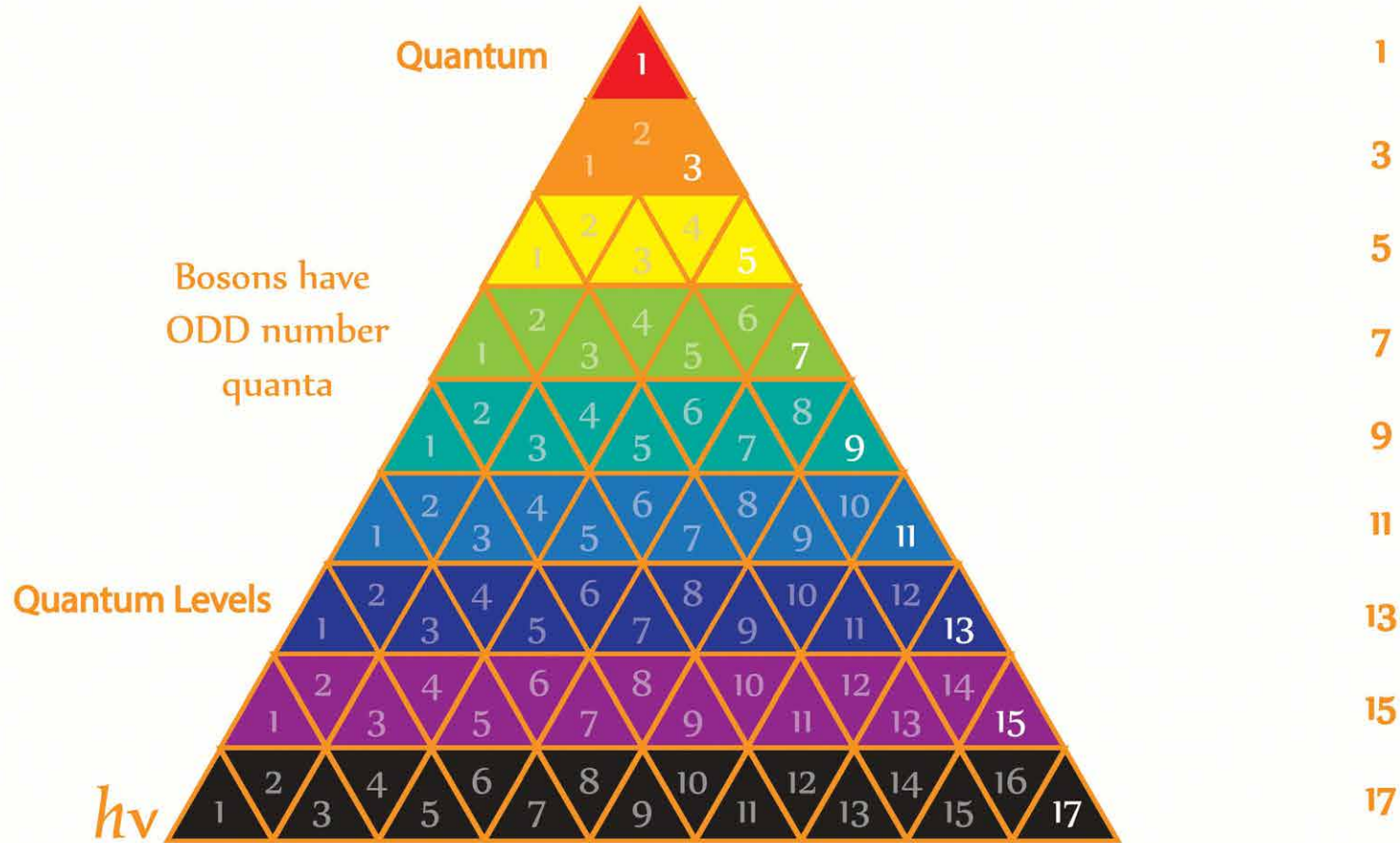
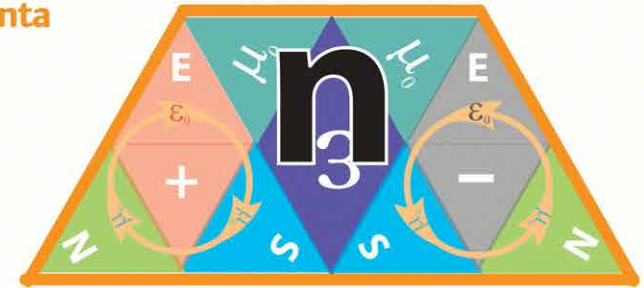
Viewed as a subset of the real numbers, they are numbers that can be written without a fractional or decimal component



Bosons are a transverse measure of scalar energy momenta

ODD numbers

An odd number is an integer which is not a multiple of two.

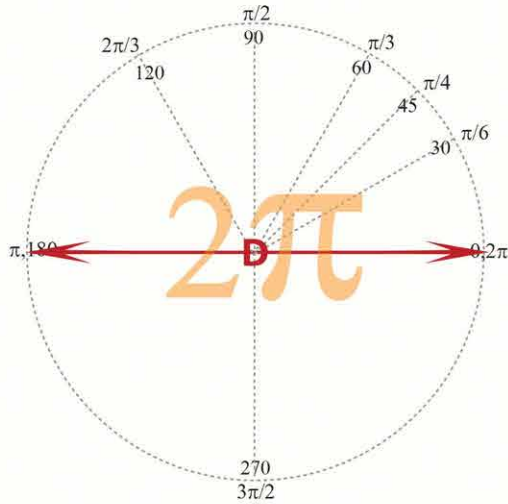


An odd number, when divided by two, will result in a fraction

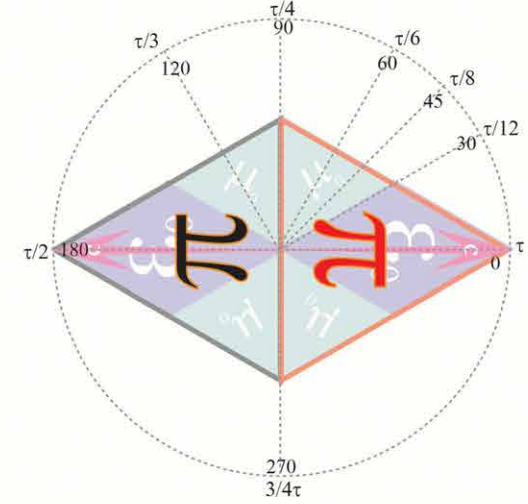
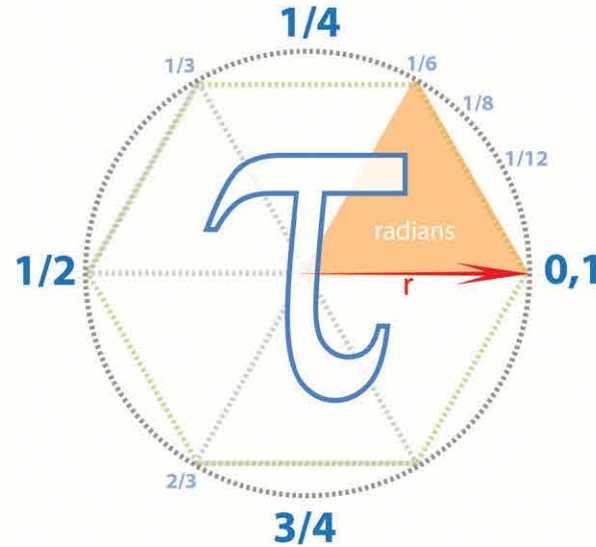
Tau radians

Around the whole outside of a circle, there are about 6.283 radians - or, Tau radians

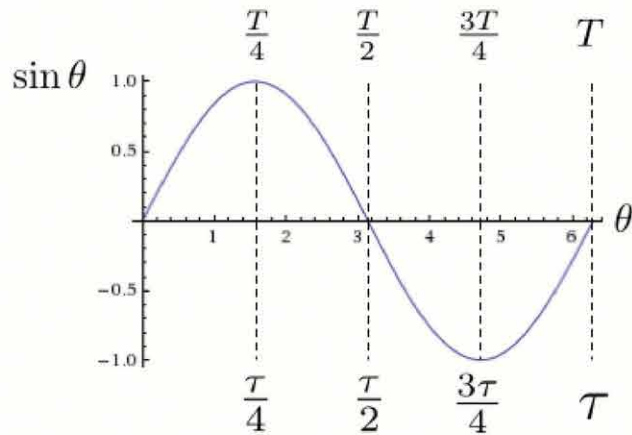
3.141592654



6.283185307

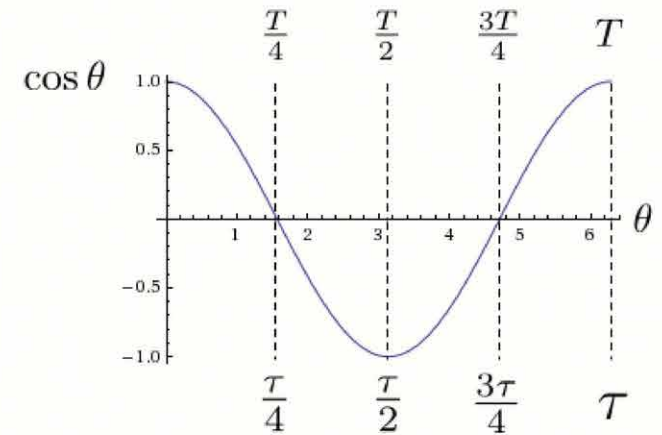


τ is a more 'natural' radian system for geometric physics than π
 Tau = 2π = 360 degree rotation about a point



π
 historically defined as the ratio of a circle's circumference to its DIAMETER should be redefined in physics to

τ
 the ratio of its circumference to its RADIUS
 in doing so many of the $\pi/2$ terms common to physics will be automatically rationalised and will better reflect the Tetryonic geometry of mass-ENERGY-Matter in motion



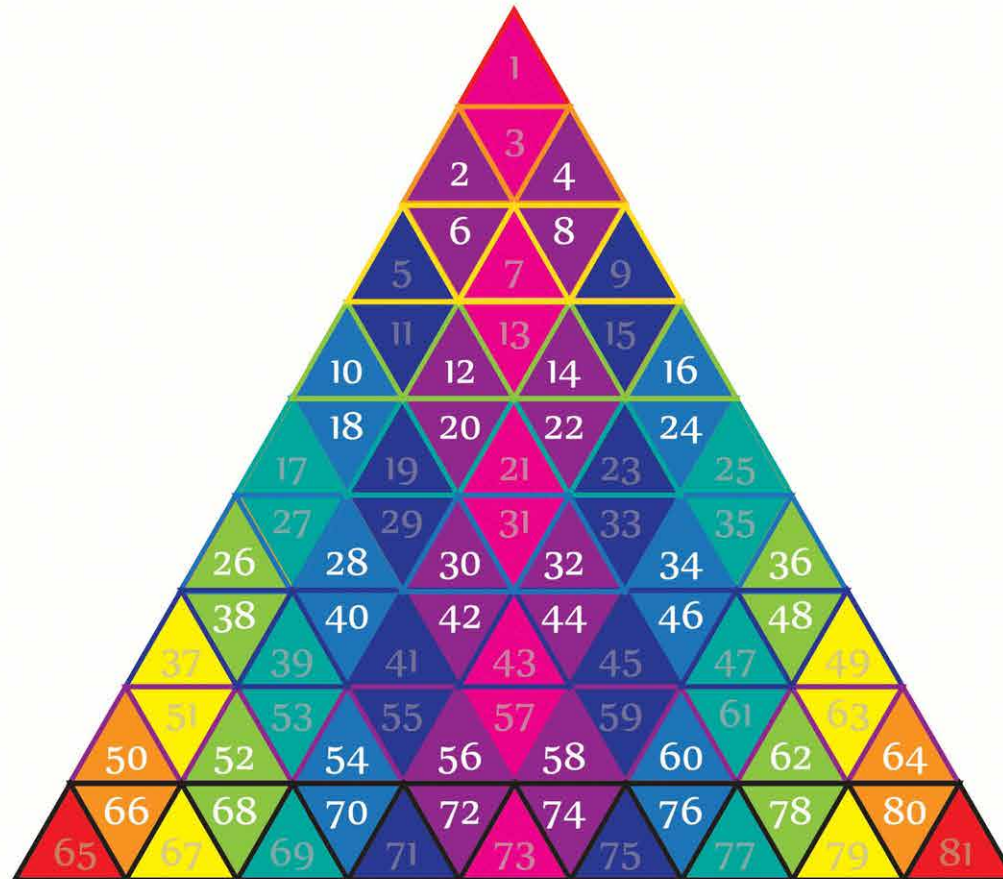
Photons are a longitudinal measure of scalar energy momenta



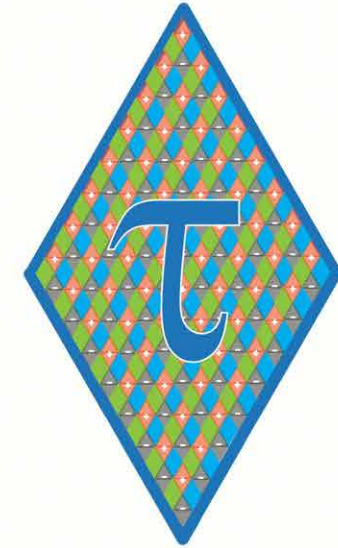
Photons are
EVEN number
quanta

EVEN numbers

An integer that is not an odd number is an even number



If an even number is divided by two, the result is another whole number
 $\frac{1}{2}$ 1 $\frac{3}{2}$ 2 $\frac{5}{2}$ 3 $\frac{7}{2}$ 4 $\frac{9}{2}$ 4 $\frac{7}{2}$ 3 $\frac{5}{2}$ 2 $\frac{3}{2}$ 1 $\frac{1}{2}$
 If an odd number is divided by two, the result is a fractional number



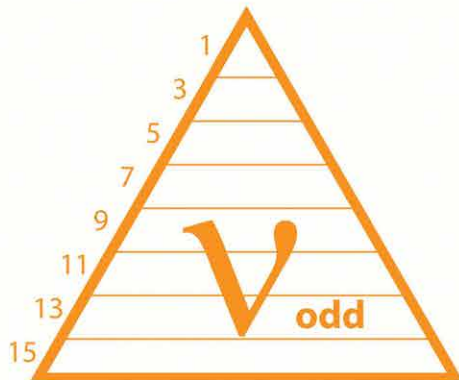
EM waves are
comprised of EVEN
numbered quanta

Triangular numbers

Historically, a triangular number counts quanta that can pack together to form an equilateral triangle

1, 3, 6, 10, 15, 21, 28, 36, 45, 55,

this form of geometric counting of same charges over-complicated the simpler physical reality

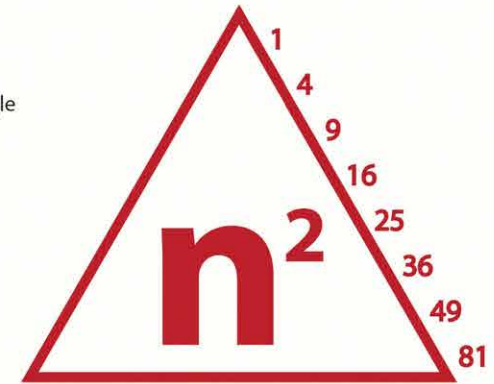


$$2v-1$$

$$[v] + [v-1]$$

Equilateral chords or quantum levels are ODD numbers

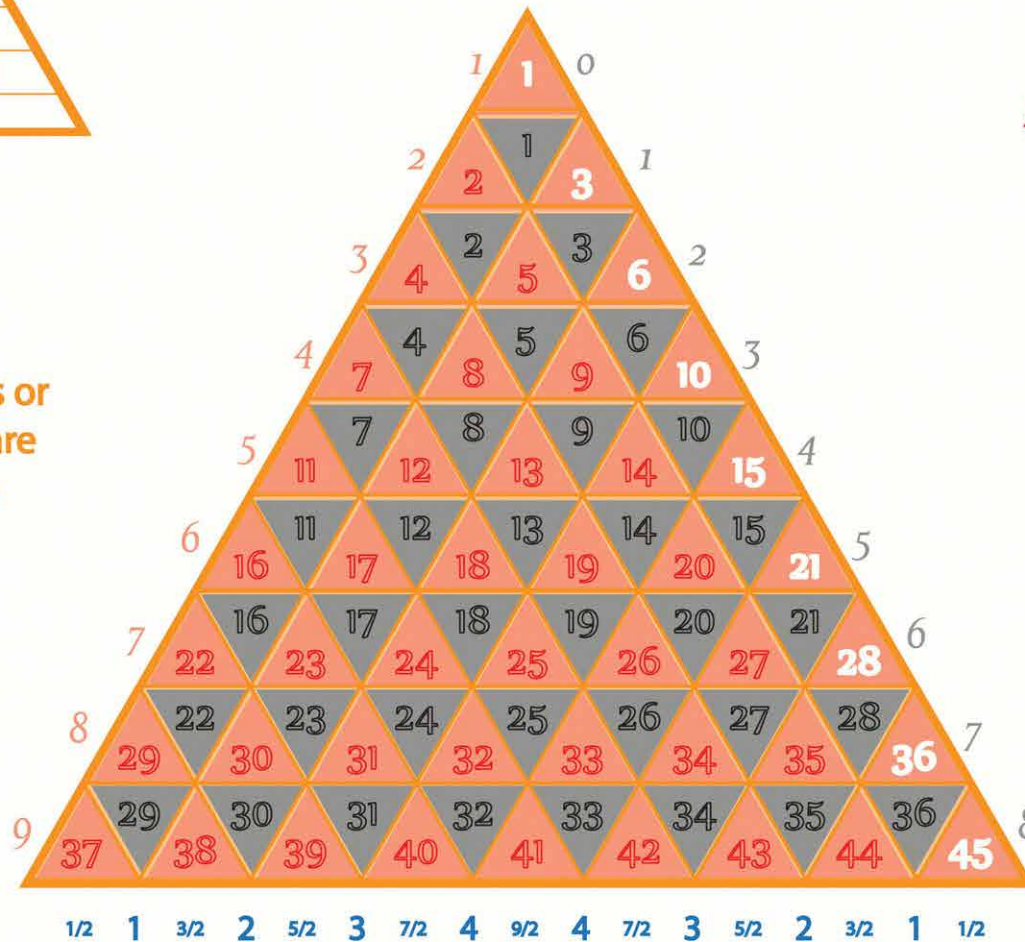
1, 3, 5, 7, 9, 11, 13, 15, 17, 19, 21,



$$\sum_{1}^n [2n-1]$$

Equilateral geometries form SQUARE numbered geometries

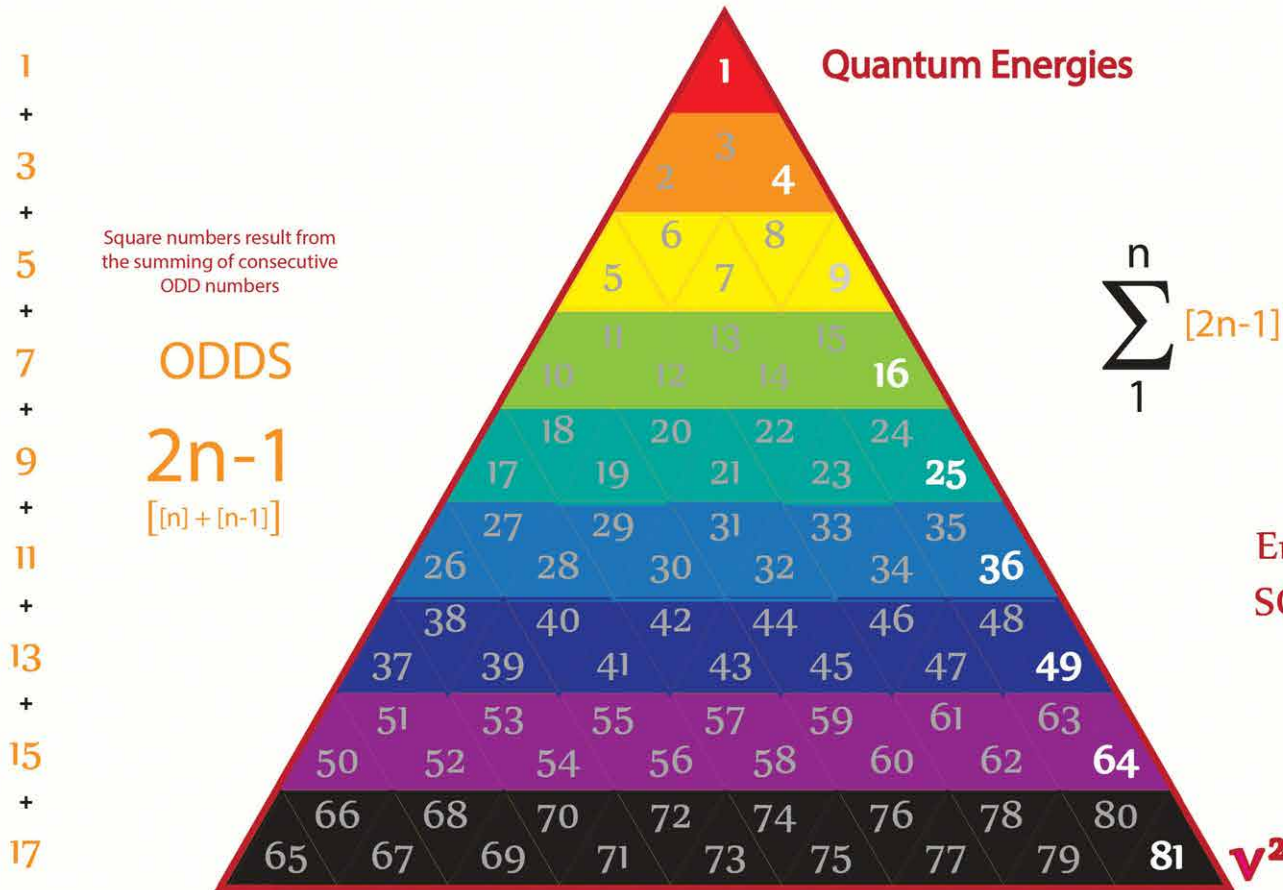
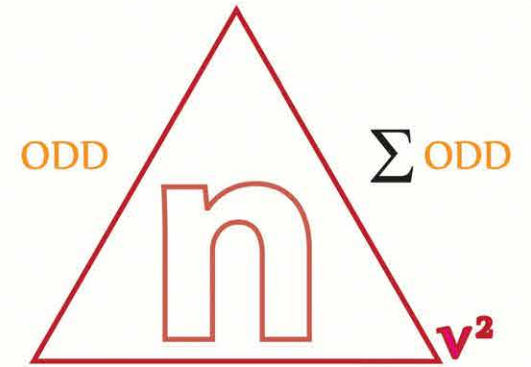
1, 4, 9, 16, 25, 49, 64, 81, 100, 121, 144,



Triangular energy quanta form normal distributions

Squared numbers

A square number, sometimes also called a perfect square, is the result of an integer multiplied by itself



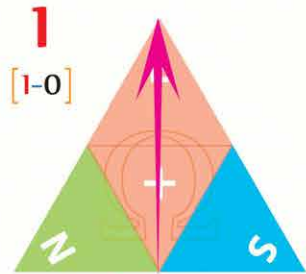
Energy levels have SQUARE number quanta

Compton Frequency

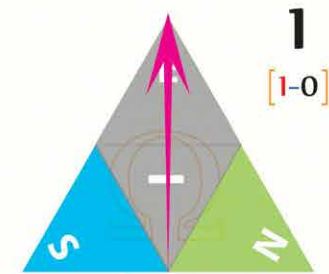
In Tetryonics Square numbers produce equilateral geometries

Square roots

A square root of a number is a number that, when it is multiplied by itself (squared), gives the first number again.

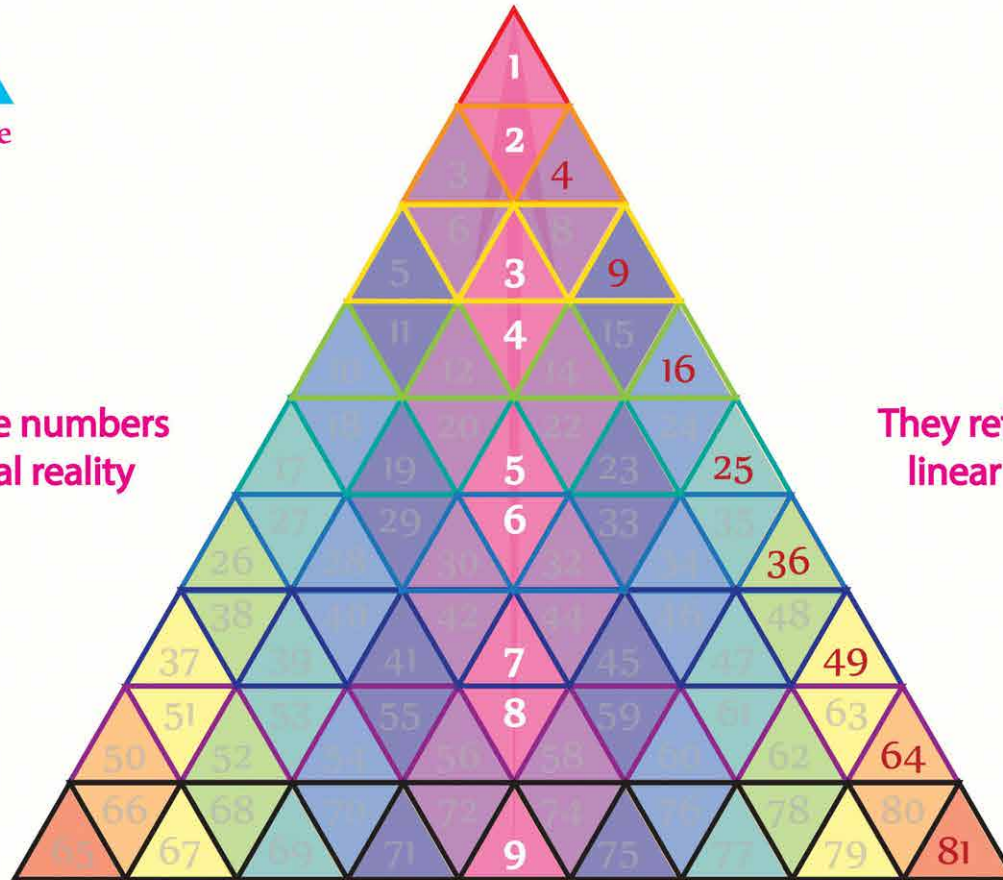


Root of positive one



Root of negative one

-i and +i



Square roots of negative numbers have a basis in physical reality

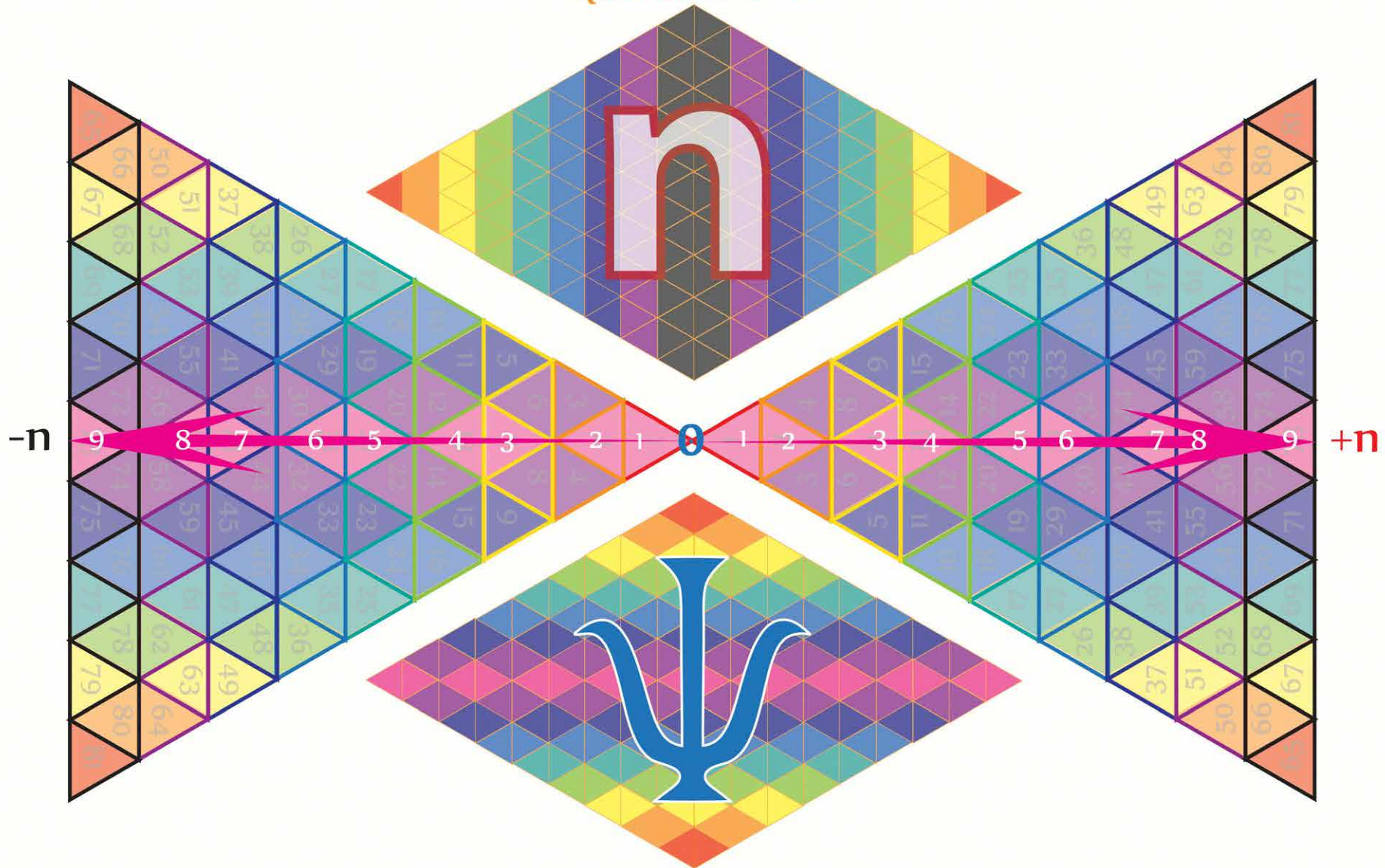
They reflect the real non-negative linear momentum of a system

A whole number with a square root that is also a whole number is called a perfect square in Tetryonic theory they are actually equilateral geometries

Real Numbers

In mathematics, a real number is a value that represents a quantity along a continuous line. The real numbers include all the rational numbers,

Quantum levels



Wave probabilities

ONE

to

∞^2

Quantum levels



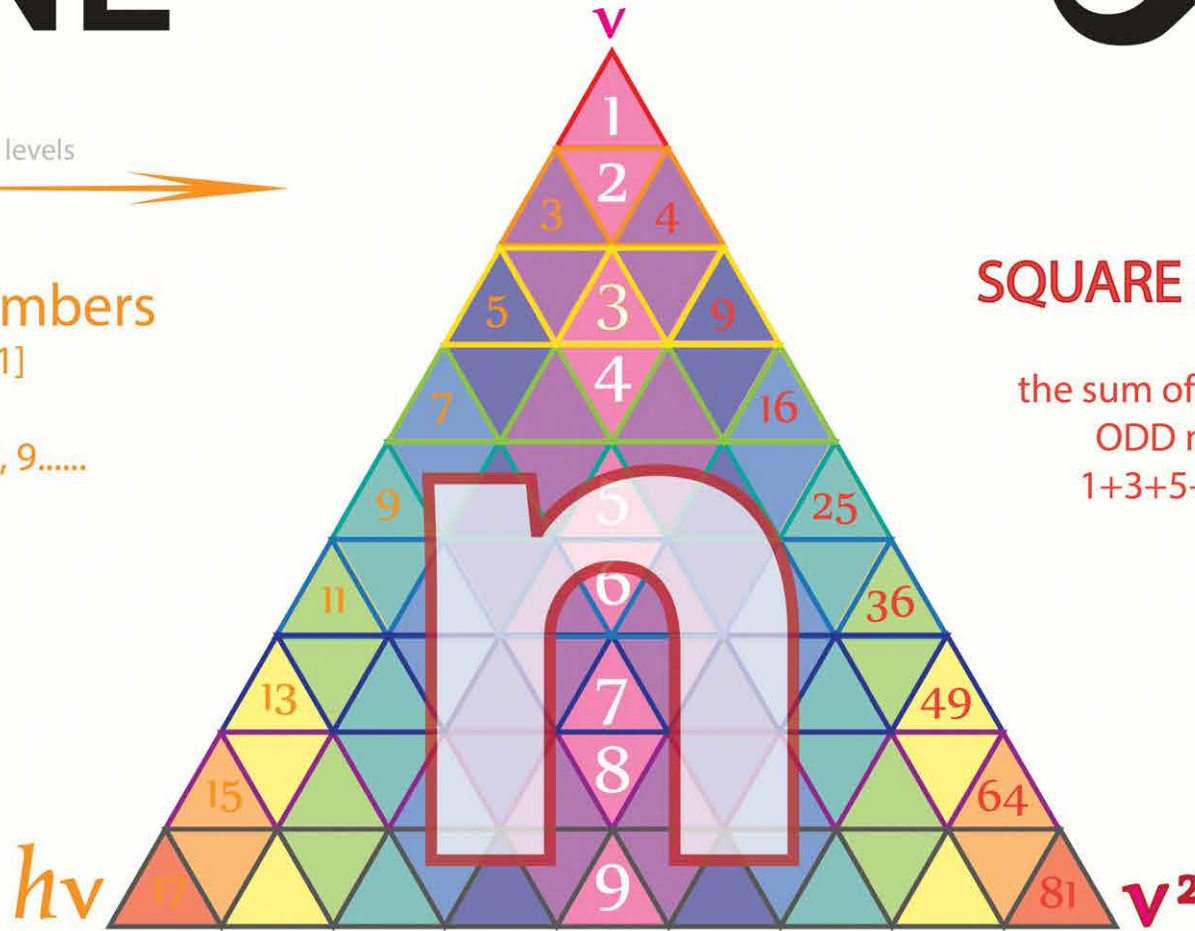
ODD numbers
[2n-1]

1, 3, 5, 7, 9.....

SQUARE numbers

the sum of consecutive
ODD numbers
1+3+5+7+9+.....

Scalar Energies



1 2 3 4 5 6 7 8 9 8 7 6 5 4 3 2 1



Linear energy momentum

NORMAL DISTRIBUTION

Basic Properties of nested scribed Equilateral Triangles

Given an equilateral triangle of side s

altitude

$$\sqrt{3/2} S$$

$$\sqrt{3/4} S^2$$

area

$$3S$$

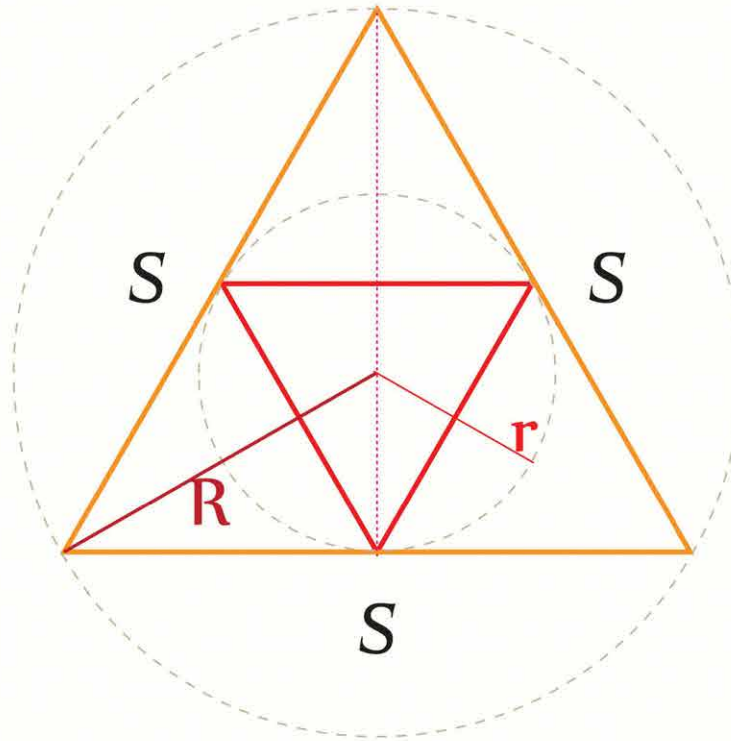
perimeter

$$\sqrt{3/6} S$$

in-radius

$$\sqrt{\pi/12} S^2$$

in-circle area



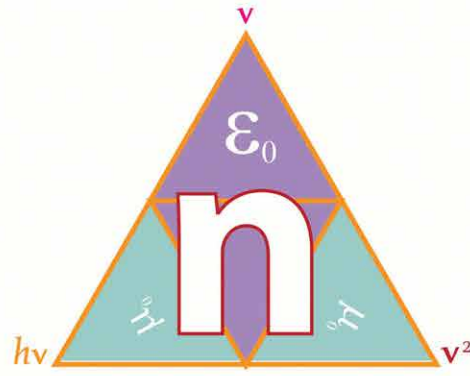
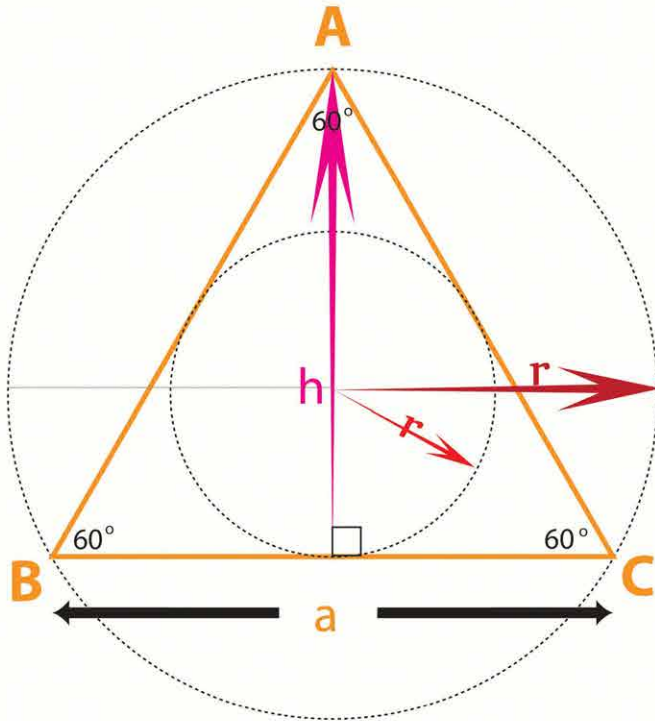
circum-radius

$$\sqrt{3/3} S$$

circum-circle area

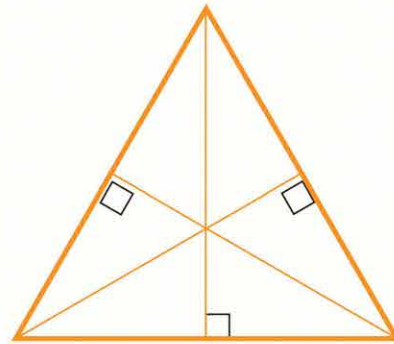
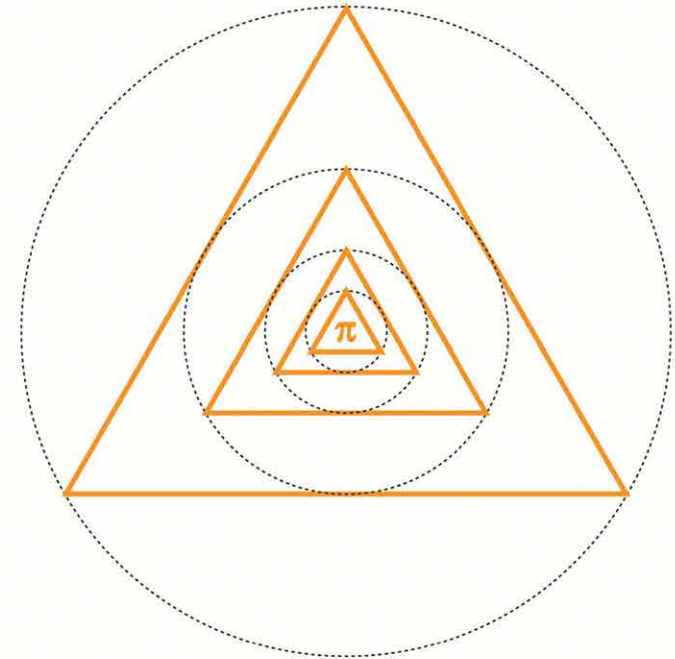
$$\sqrt{\pi/3} S^2$$

Tetryonic [equilateral] geometry



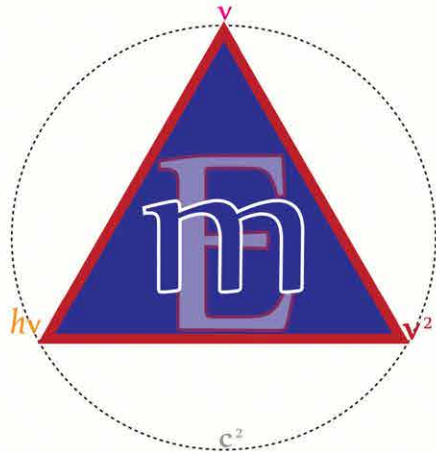
The equilateral triangle exhibits 'square symmetry'
it can always be divided into n^2 [number]
of smaller self-similar parts

**All triangles are
flat euclidean
 π radian
geometries
[180°]**



An equilateral triangle is the most symmetrical triangle,
having 3 lines of reflection and rotational symmetry of order 3 about its center

Energy



Energy per
spatial unit

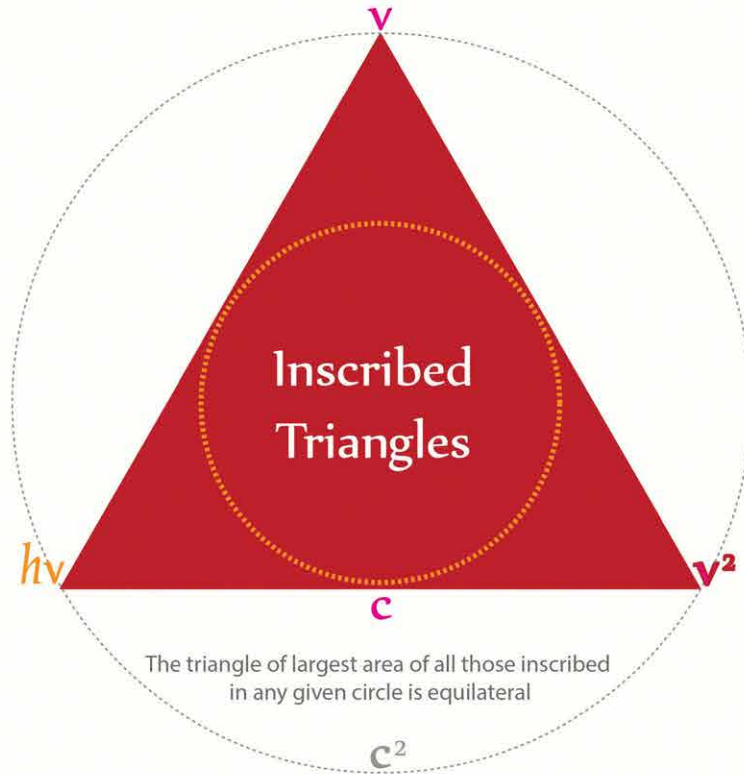
mass

$$m = \frac{E}{c^2}$$

CHARGE

Scribed equilateral geometries

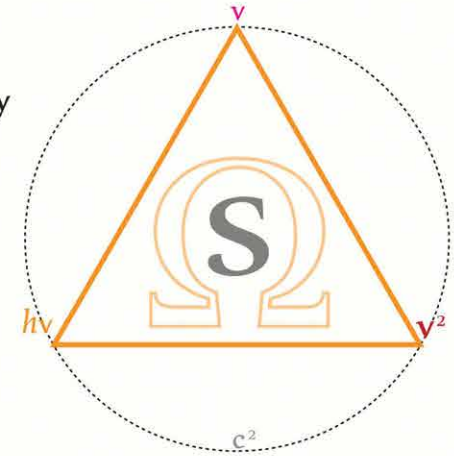
reflect space-time's geometric relationship with charged mass-energy



Inscribed
Triangles

The triangle of largest area of all those inscribed
in any given circle is equilateral

QAM



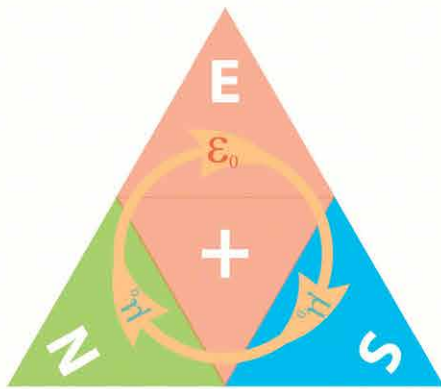
QAM per
spatial unit

seconds

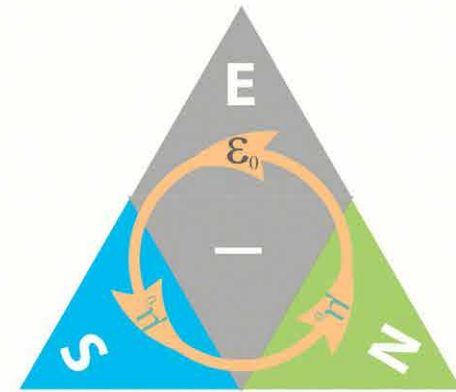
$$\frac{\Omega}{c^2} = s$$

Circumscribed Triangles

reflect Energy's relationship with Time



Positive Planck Charge



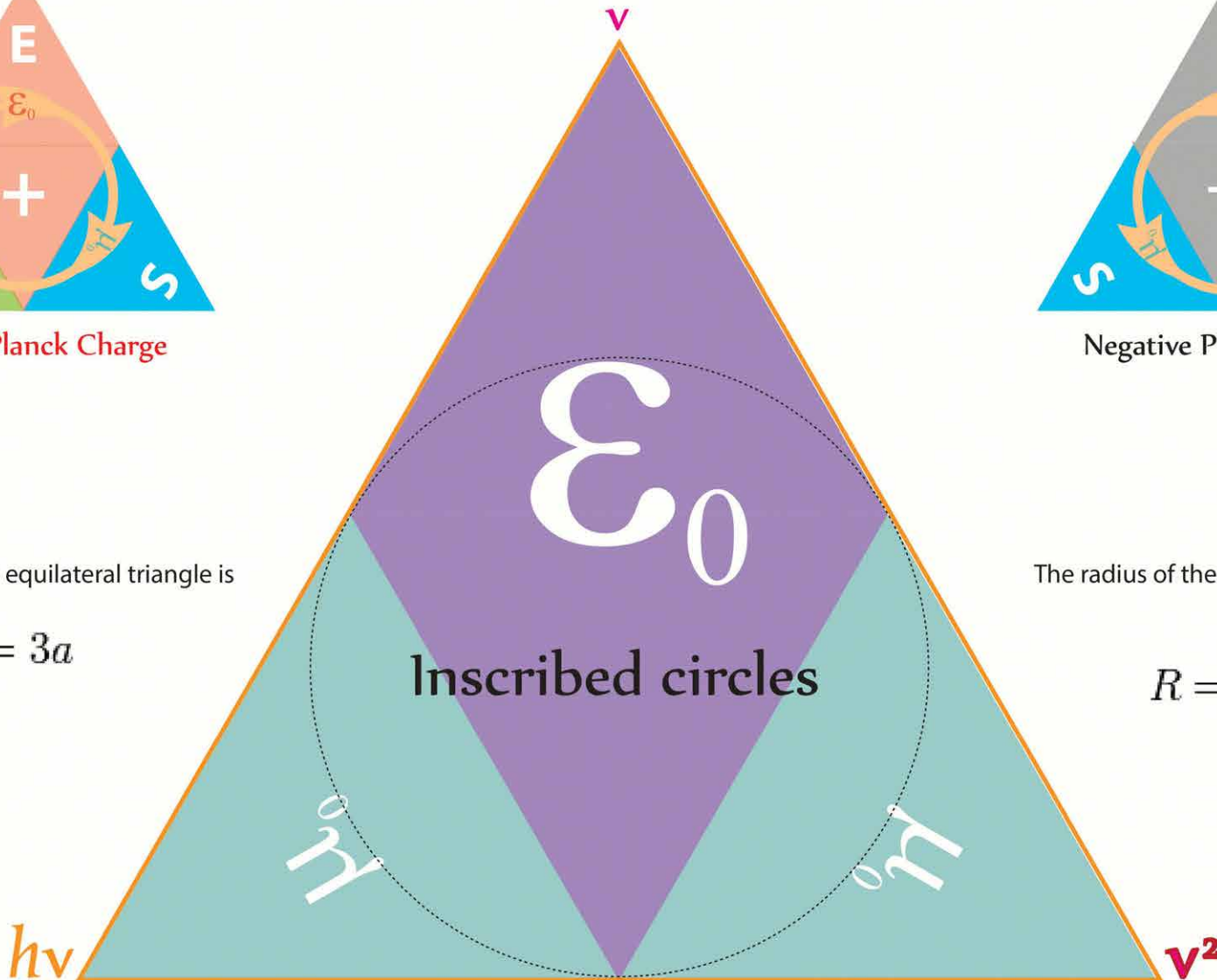
Negative Planck Charge

The perimeter of an equilateral triangle is

$$p = 3a$$

The radius of the circumscribed circle is

$$R = \frac{\sqrt{3}}{3}a$$



The equilateral triangle has the smallest area of all those circumscribed around a given circle

Circumscribed circles

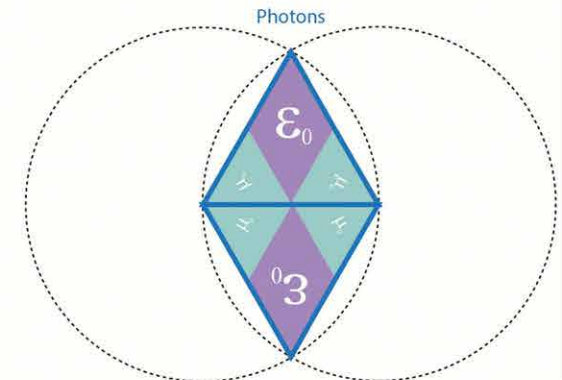
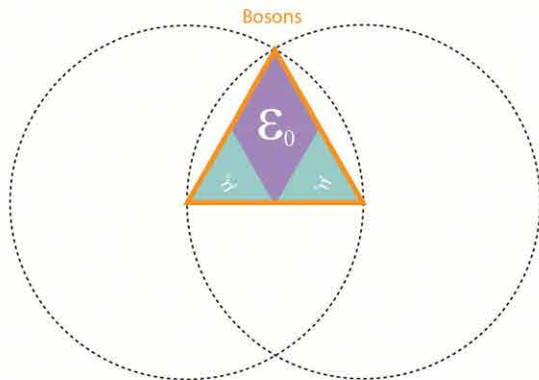
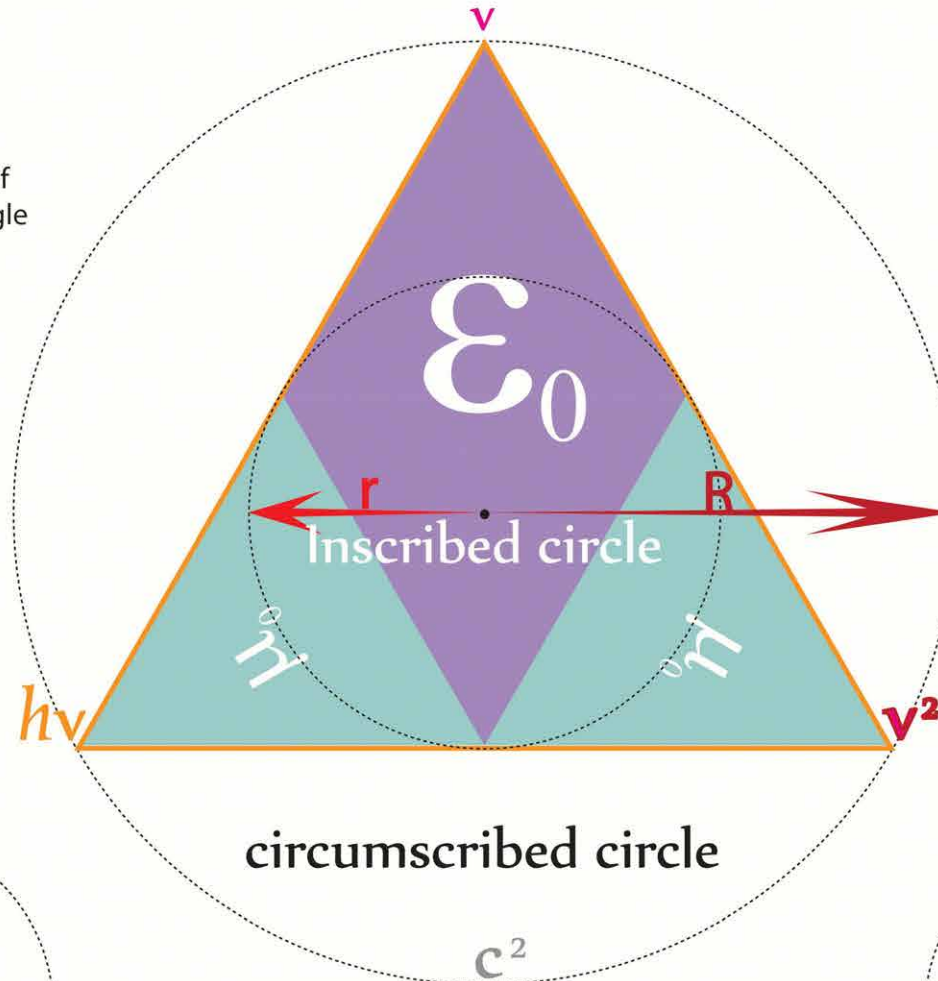
By Euler's inequality, the equilateral triangle has the smallest ratio R/r of the circumradius to the inradius of any triangle: specifically, $R/r = 2$

The ratio of the area to the square of the perimeter of an equilateral triangle

$$\frac{1}{12\sqrt{3}}$$

The ratio of the area of the incircle to the area of an equilateral triangle

$$\frac{\pi}{3\sqrt{3}}$$



Equilateral triangles and Tetrahedrons will scale at exactly the same proportion as Circles and Spheres scribing them

Charged mass-ENERGIES

Charge is the result of quantised angular momenta
[the inscribed circular flux of energy in equilateral geometries]

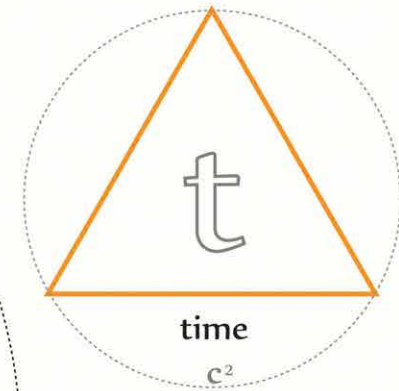
Time is a measure of changing quantised angular momenta
[the circumscribed spatial co-ordinate of equilateral energy geometries]

inscribed



charge

circumscribed

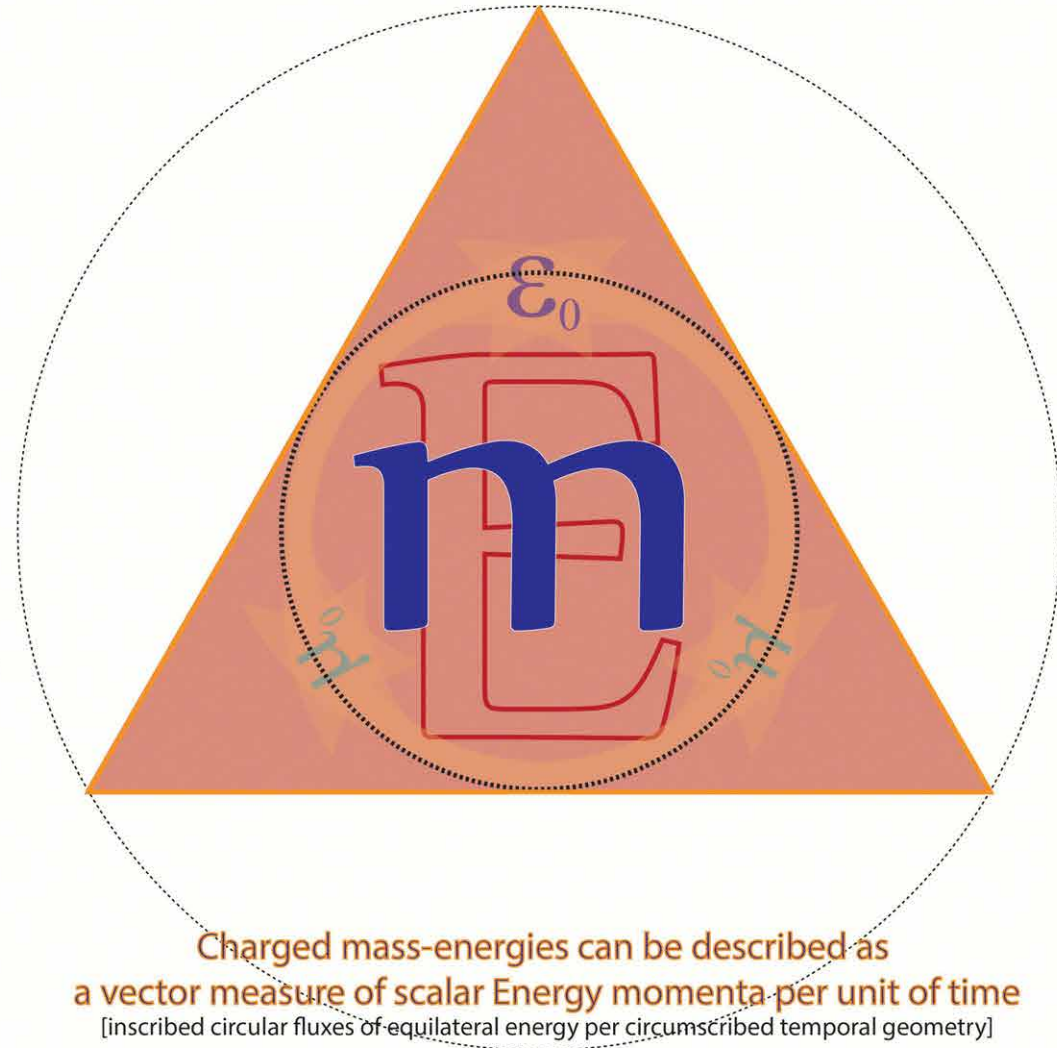


time

c^2

It is the equilateral geometry of energy not a classical vector rotation that creates QAM

Scalar EM mass is a measure of equilateral Planck energy per spatial co-ordinate system



m

Charged mass-energies can be described as a vector measure of scalar Energy momenta per unit of time
[inscribed circular fluxes of equilateral energy per circumscribed temporal geometry]

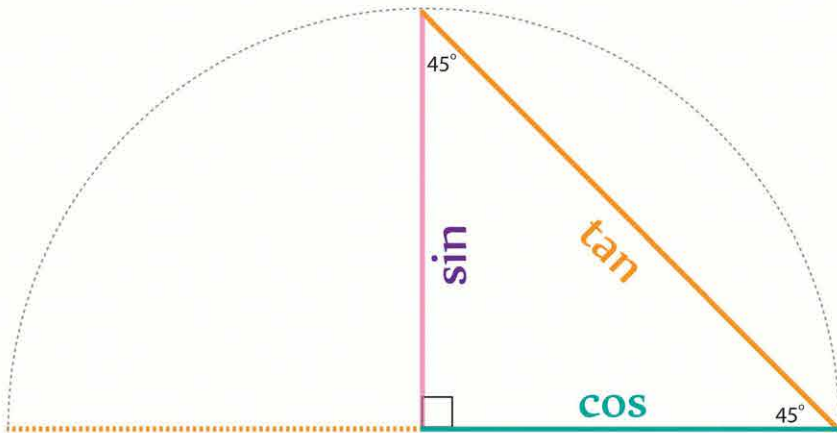
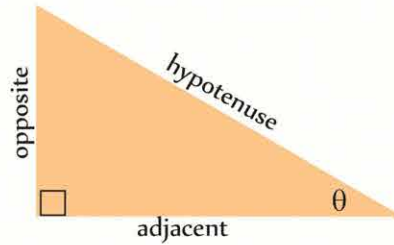
E

Trigonometric functions

$$\sin \theta = \frac{\text{opposite}}{\text{hypotenuse}}$$

$$\cos \theta = \frac{\text{adjacent}}{\text{hypotenuse}}$$

$$\tan \theta = \frac{\text{opposite}}{\text{adjacent}}$$

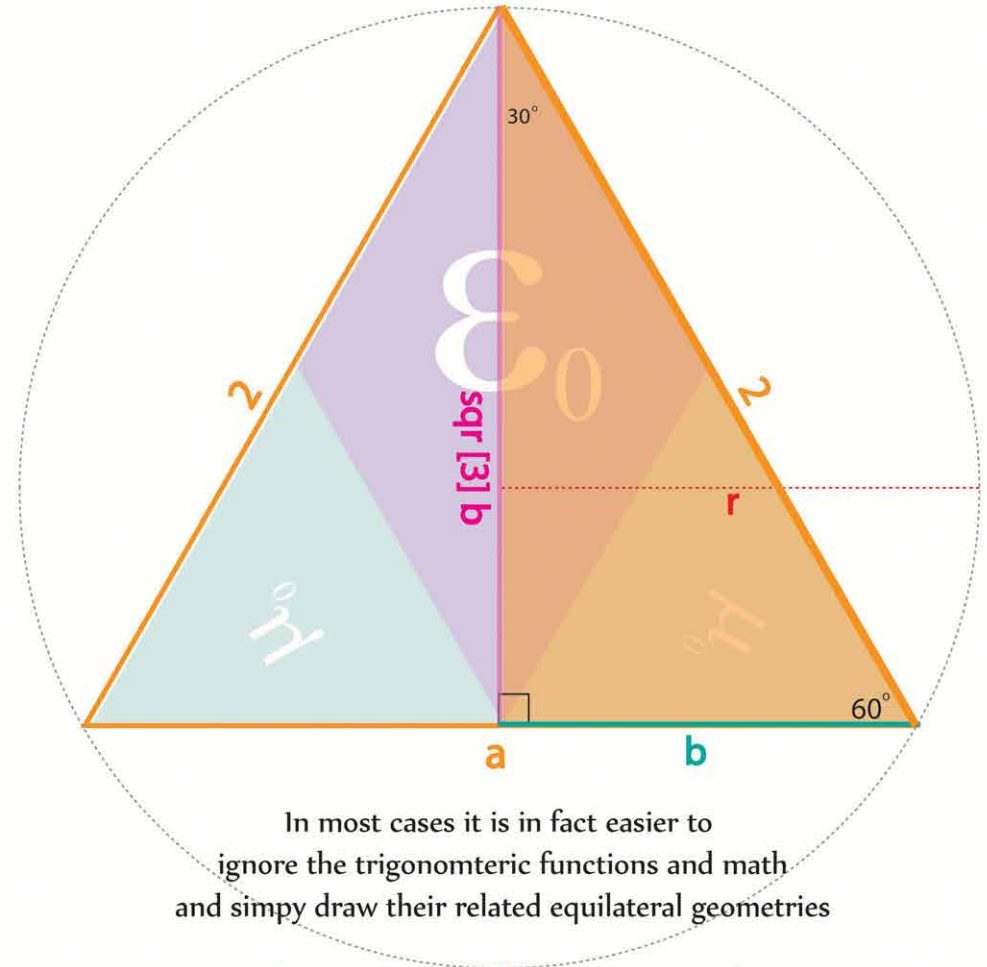


The most familiar trigonometric functions are the sine, cosine, and tangent.

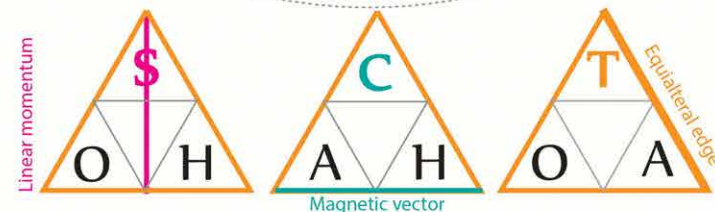
In the context of the standard unit circle with radius 1, where a triangle is formed by a ray originating at the origin and making some angle with the x-axis,

the SINE of the angle gives the length of the y-component (rise) of the triangle, the COSINE gives the length of the x-component (run), and the TANGENT function gives the slope (y-component divided by the x-component)

Standard trigonometric functions must be carefully applied to measurements of equilateral Planck mass-energy geometries in scribed circular space-time co-ordinate systems



In most cases it is in fact easier to ignore the trigonometric functions and math and simply draw their related equilateral geometries

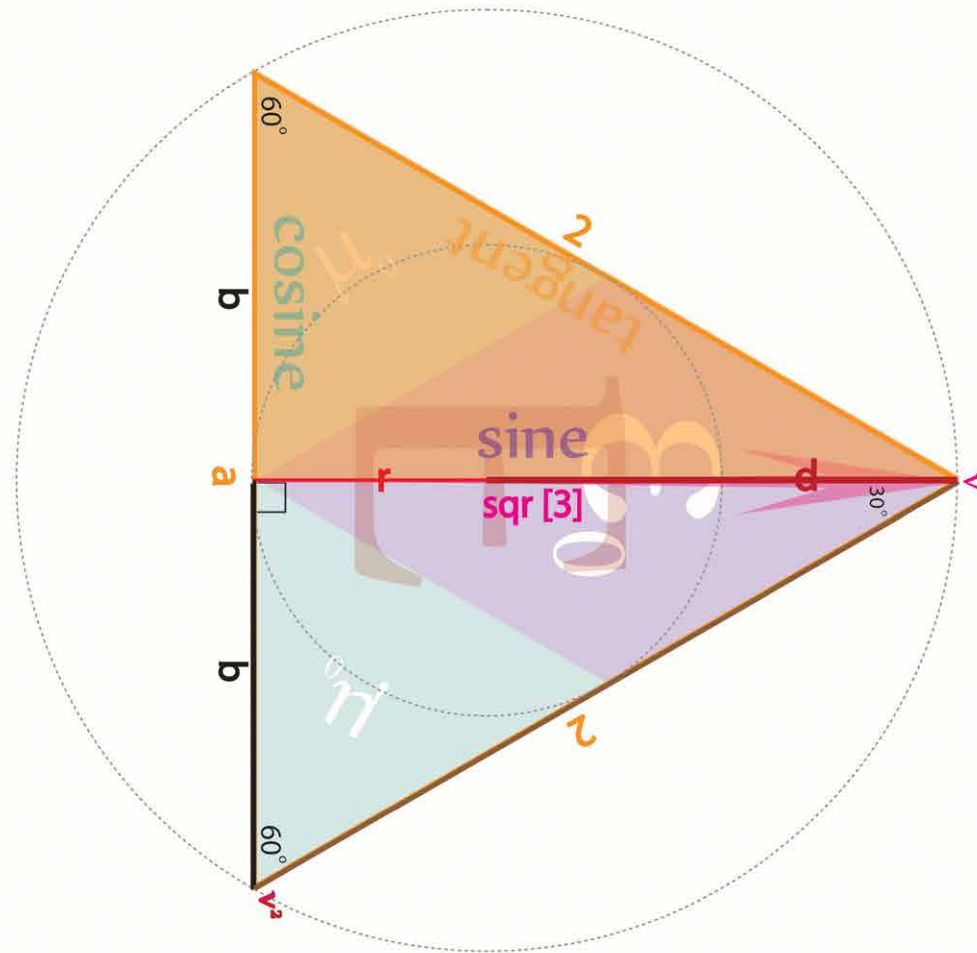


The roots of scribed equilateral triangles

Scalar equilateral energies map directly onto circular space-time co-ordinates through their square root linear momentum

r
The ratio of the circumscribed circle of an equilateral triangle to its inscribed circle is 2:1

d



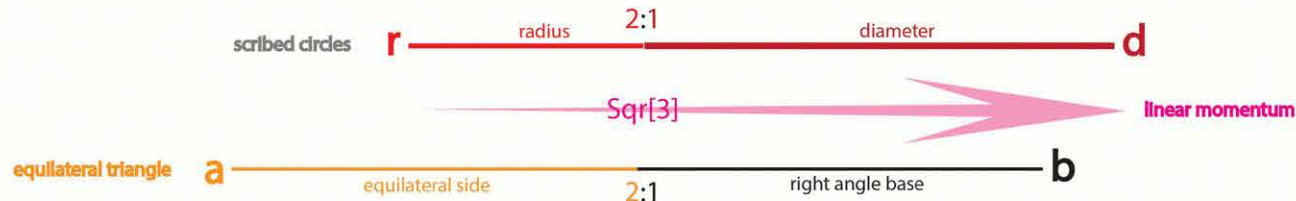
0.866 r

The ratio of the side of an equilateral triangle to the radius of its inscribed circle is $\text{sqr}[3]/2$

a

The ratio of the side of an equilateral triangle to the radius of its circumscribed circle is $\text{sqr}[3]$

1.732 d



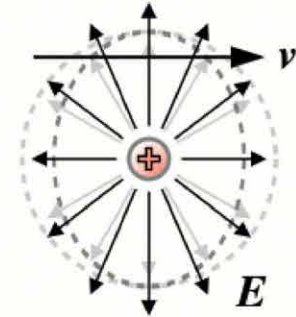
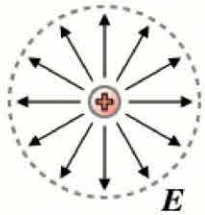
Equilateral triangles and scribed circles

$$\gamma = \frac{1}{\sqrt{1 - v^2/c^2}} = \frac{1}{\sqrt{1 - \beta^2}} = \frac{dt}{d\tau}$$

$$\gamma(\beta) = 1 + \frac{1}{2}\beta^2 + \frac{3}{8}\beta^4 + \frac{5}{16}\beta^6 + \frac{35}{128}\beta^8 + \dots$$

$$L = L' \sqrt{1 - \frac{v^2}{c^2}}$$

$$E_k = \frac{mc^2}{\sqrt{1 - (v/c)^2}} - mc^2$$

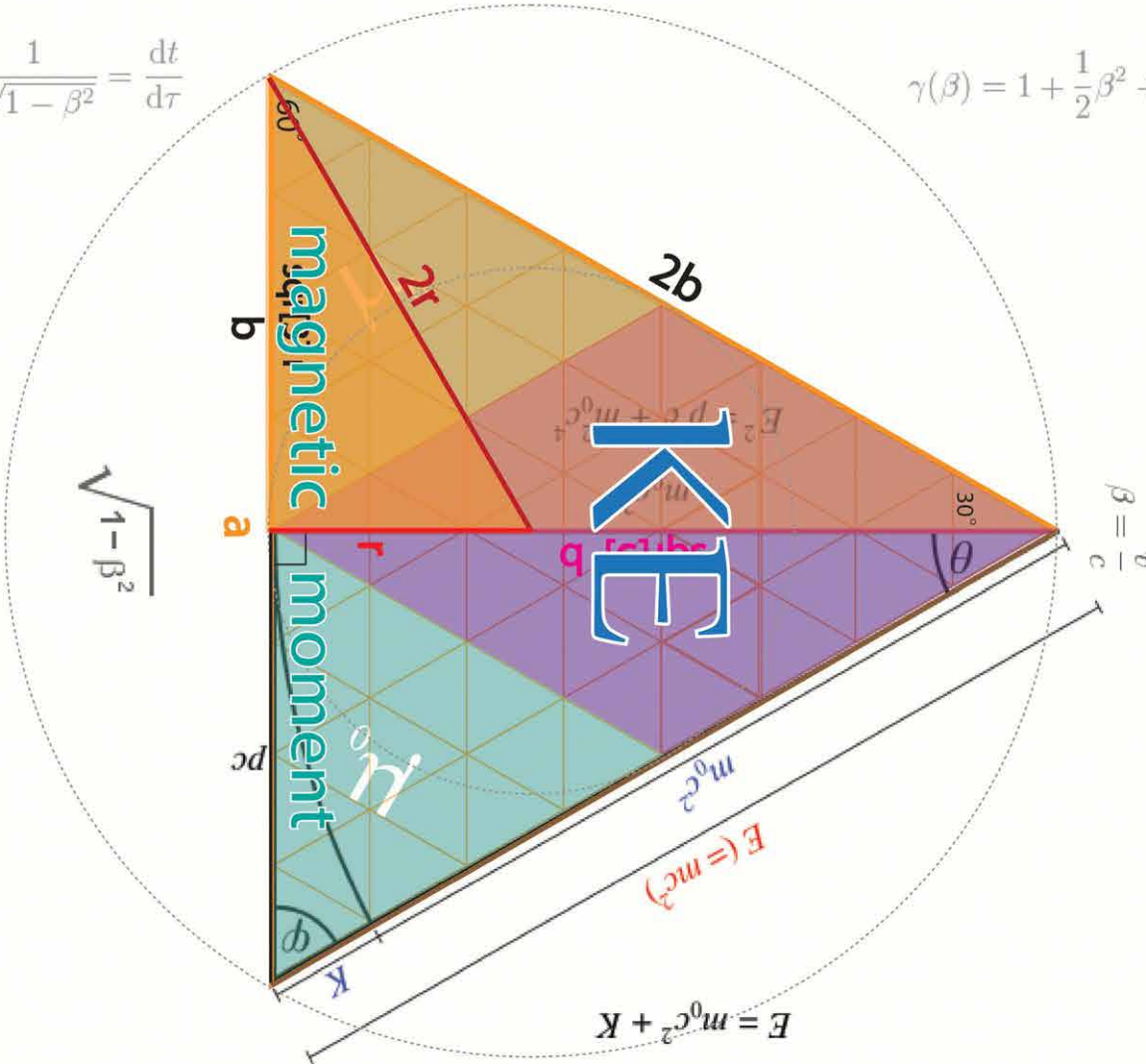


$$mc^2 \left\{ \frac{1}{\sqrt{1 - v^2/c^2}} - 1 \right\}$$

$$p = \frac{m_0 v}{\sqrt{1 - \frac{v^2}{c^2}}} = \gamma m_0 v$$

$$E = \frac{mc^2}{\sqrt{1 - \frac{v^2}{c^2}}}$$

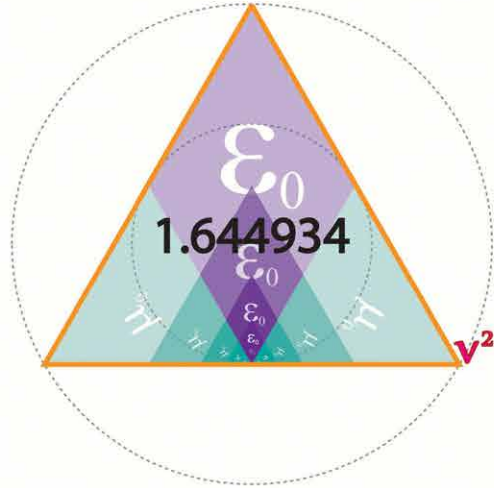
$$\sqrt{1 - \left(\frac{v}{c}\right)^2}$$



All the relativistic relationships historically attributed to circularised energies and modelled through the use of the math of right angled triangles are in fact the result of equilateral, scalar geometries

Finite sequences and series have defined first and last terms,

$$\sum a_n = a_0 + a_1 + a_2$$



$$\sum_{n=1}^{\infty} \frac{1}{n^2} = \lim_{n \rightarrow +\infty} \left(\frac{1}{1^2} + \frac{1}{2^2} + \dots + \frac{1}{n^2} \right).$$

whereas infinite sequences and series continue indefinitely

The Basel problem is a famous problem in mathematical analysis with relevance to number theory, first posed by Pietro Mengoli in 1644 and solved by Leonhard Euler in 1735.

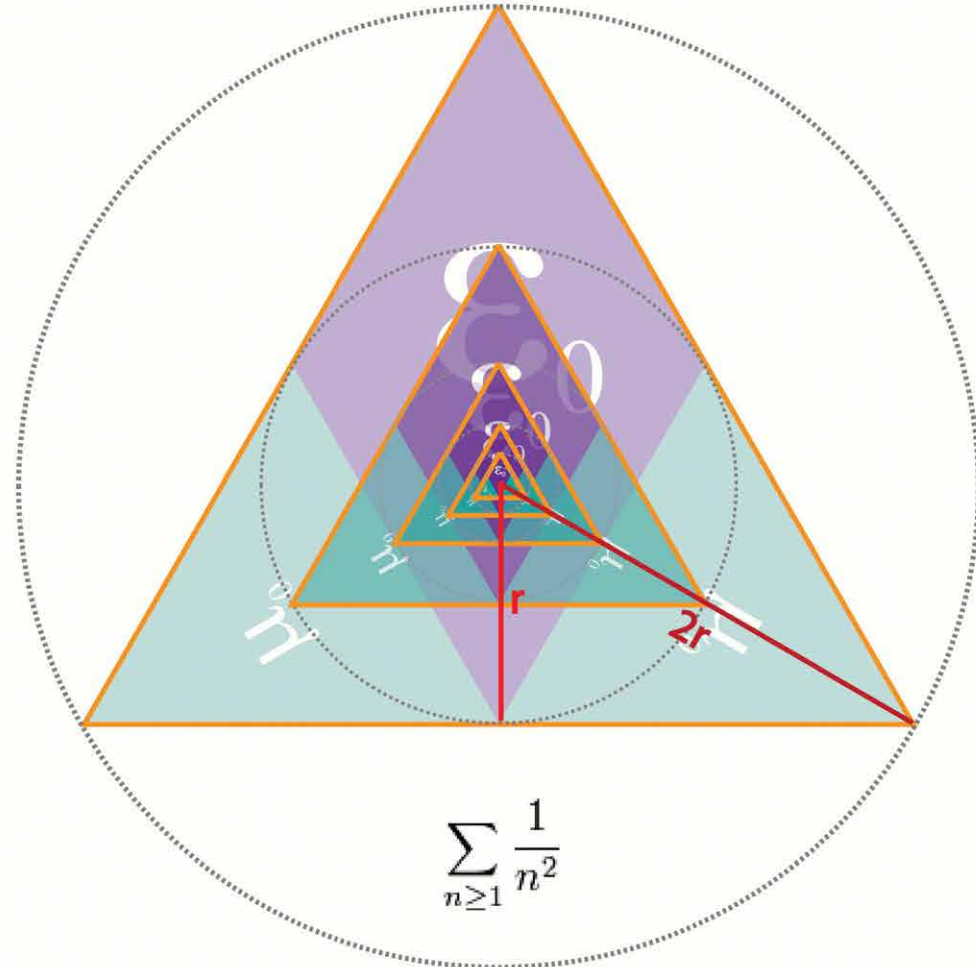
$$\frac{1}{1^2} + \frac{1}{2^2} + \frac{1}{3^2} + \frac{1}{4^2} + \frac{1}{5^2} + \dots = \frac{\pi^2}{6}$$

Tetryonics now provides a geometric solution to visualising and solving the Basel problem

$$\zeta(2) = 1 + \frac{1}{2^2} + \frac{1}{3^2} + \dots = \frac{\pi^2}{6} \approx 1.645;$$

Tetryonic Infinite Series

is a infinite sequence of square numbers, the result of adding all those terms together [or their geometric inverse]



$$\sum_{n \geq 1} \frac{1}{n^2}$$

The entire sum of the series is equal to **twice the size of the radius of the largest inscribed circle** which is equal to the largest circle circumscribing the triangular series.

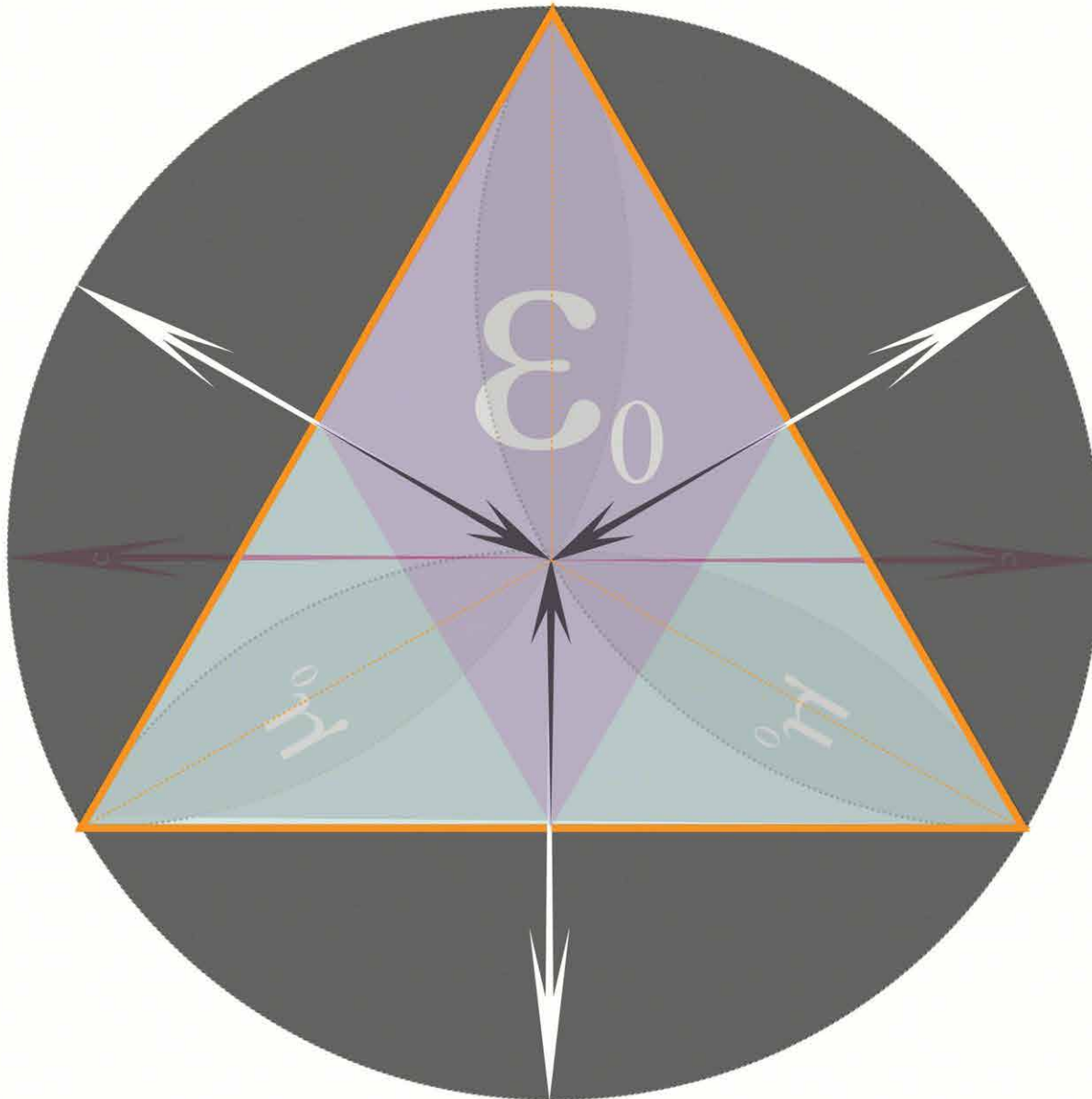
Inverting the Circle

Electric
Permittivity

$$\epsilon_0$$

Magnetic
Permeability

$$\mu_0$$



$$c^2$$

2D spatial
co-ordinates

$$\frac{1}{c^2}$$

ElectroMagnetic
fields

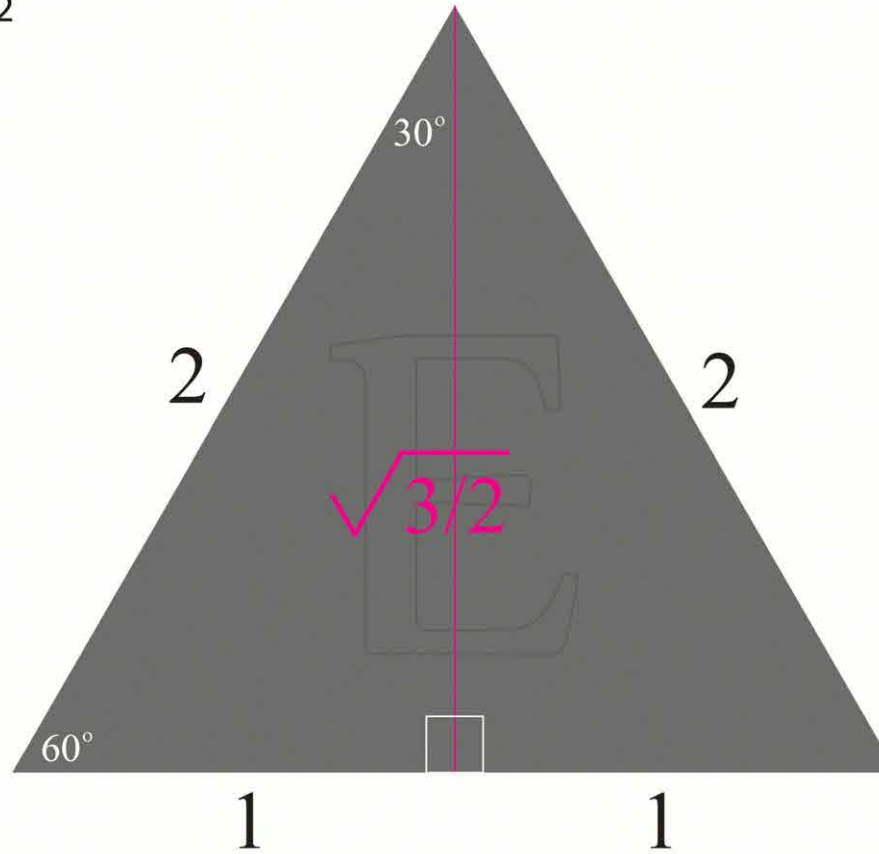
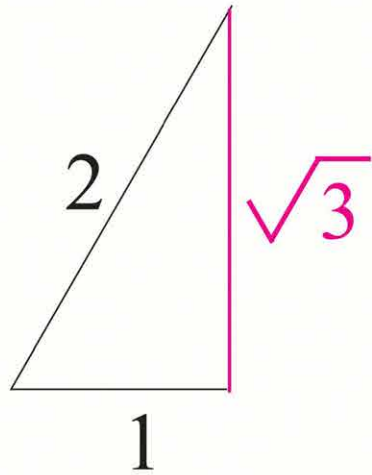
Irrational numbers

an irrational number cannot be represented as a simple fraction.

Irrational numbers are those real numbers that cannot be represented as terminating or repeating decimals

$\sin(x) = \sqrt{3}/2$

0.866025403.....



Pythagoras' theorem
and irrational numbers expressed in terms of right-angled triangles in Physics
offer a 'half truth' regarding the equilateral geometry of Energy

Leibniz

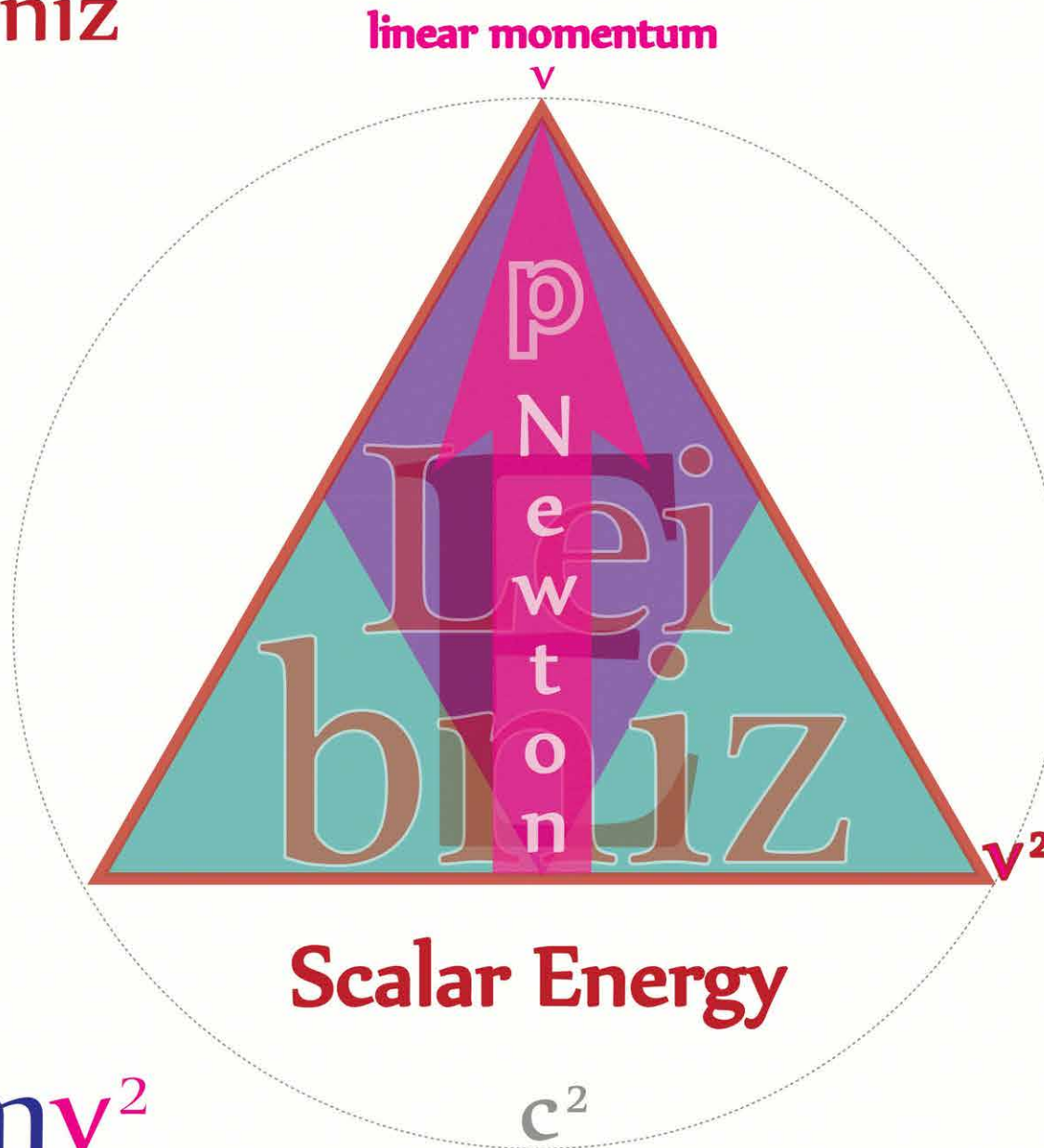
Newton

Newton focused his work on linear momentum which he developed into his famous laws of motion

Newton and Leibniz disagreed about what the world is made of and how its physics shaped our scientific concepts of force, energy, and momentum

Tetryonics reveals the physical relationships they both described mathematically as geometric properties of equilateral Planck energy momenta

Leibniz introduced the concept of vis viva (living force) which attempted to quantify life force



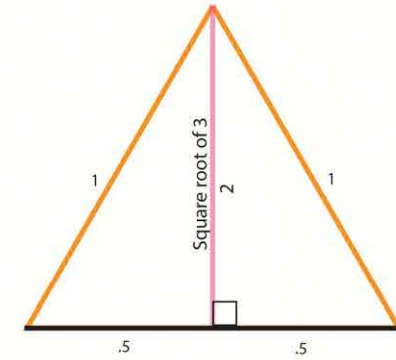
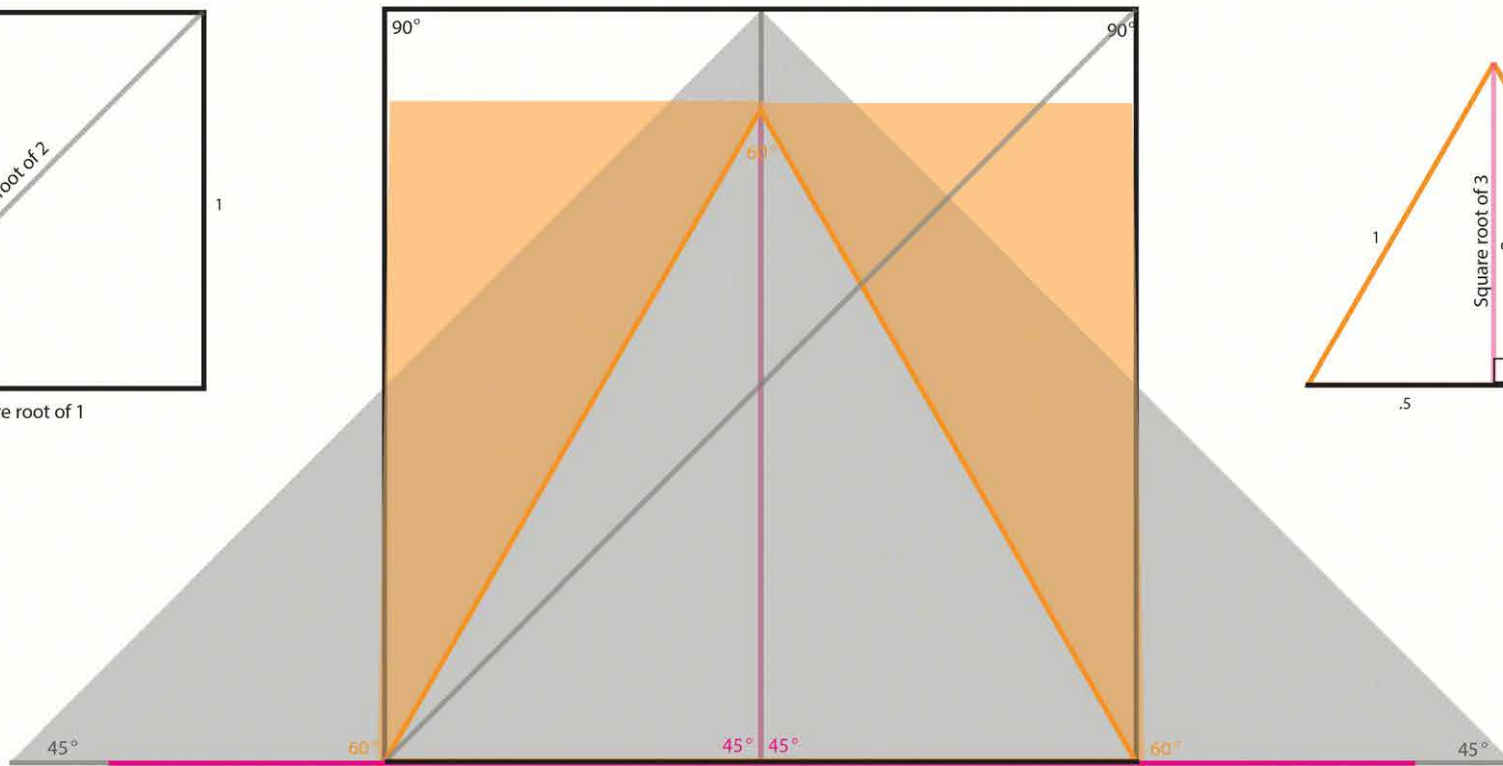
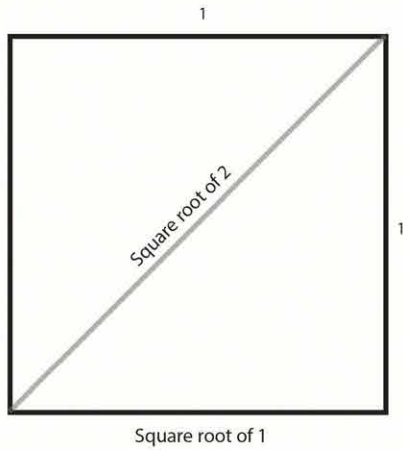
$$E = mv^2$$

$$c^2$$

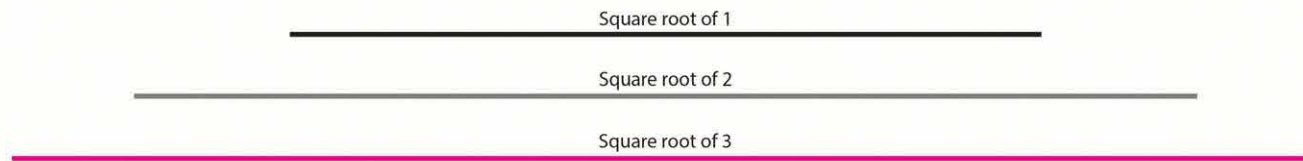
$$p = mv$$

Geometric Square Roots

In geometrical terms, the square root function maps the area of a square to its side length.



"In mathematics, as in any scientific research, we find two tendencies present. On the one hand, the tendency toward abstraction seeks to crystallize the logical relations inherent in the maze of material that is being studied, and to correlate the material in a systematic and orderly manner. On the other hand, the tendency toward intuitive understanding fosters a more immediate grasp of the objects one studies, a live rapport with them, so to speak, which stresses the concrete meaning of their relations"



"As to geometry, in particular, the abstract tendency has here led to the magnificent systematic theories of Algebraic Geometry, of Riemannian Geometry, and of Topology; these theories make extensive use of abstract reasoning and symbolic calculation in the sense of algebra.

Notwithstanding this, it is still as true today as it ever was that intuitive understanding plays a major role in geometry. And such concrete intuition is of great value not only for the research worker, but also for anyone who wishes to study and appreciate the results of research in geometry"

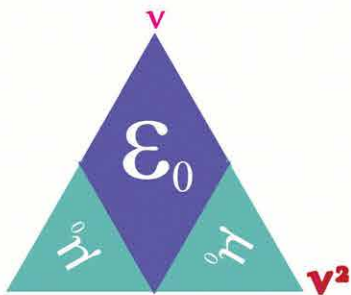
David Hilbert [Geometry and the Imagination]

Square Roots in Physics

In mathematics, a square root of a number a is a number $[n]$ such that $[n]^2 = a$, or, in other words, a number $[n]$ whose square (the result of multiplying the number by itself, or $[n \times n]$) is a .

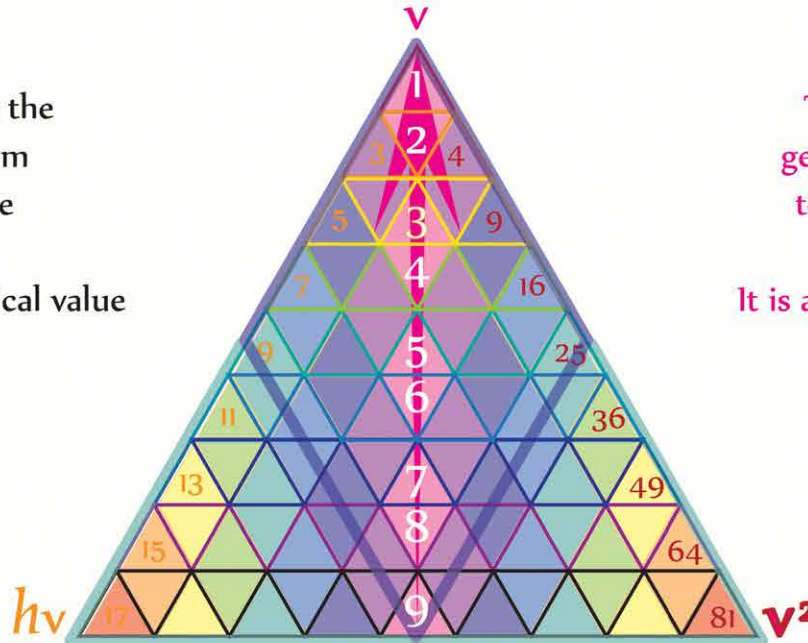
Modern calculators use the Square Root Algorithm to calculate the value

It is an approximate numerical value



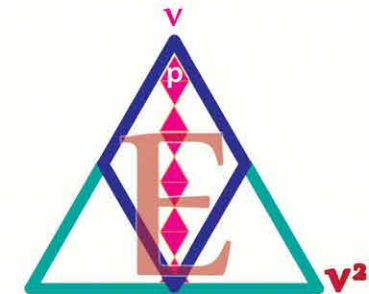
$$E = mv^2$$

In classical geometry, the square root function maps the area of a square to its side length.



Tetryonics uses the geometric Square Root to calculate the value

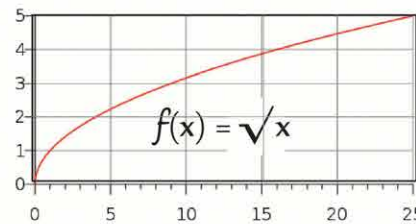
It is an exact geometric value



$$p^2 = E$$

In physics, the square root function maps ENERGY $[E]$ to momentum $[mv]$

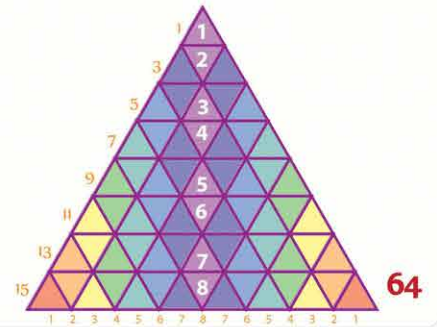
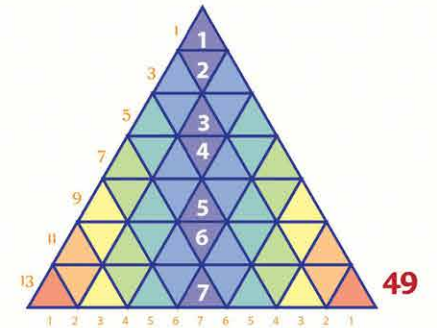
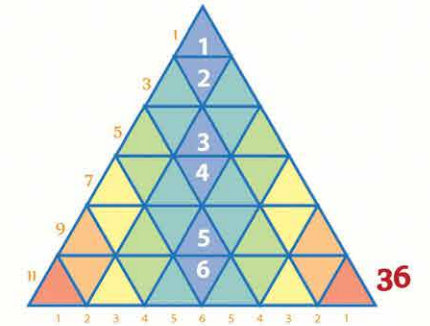
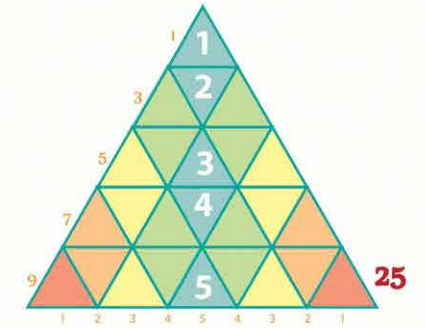
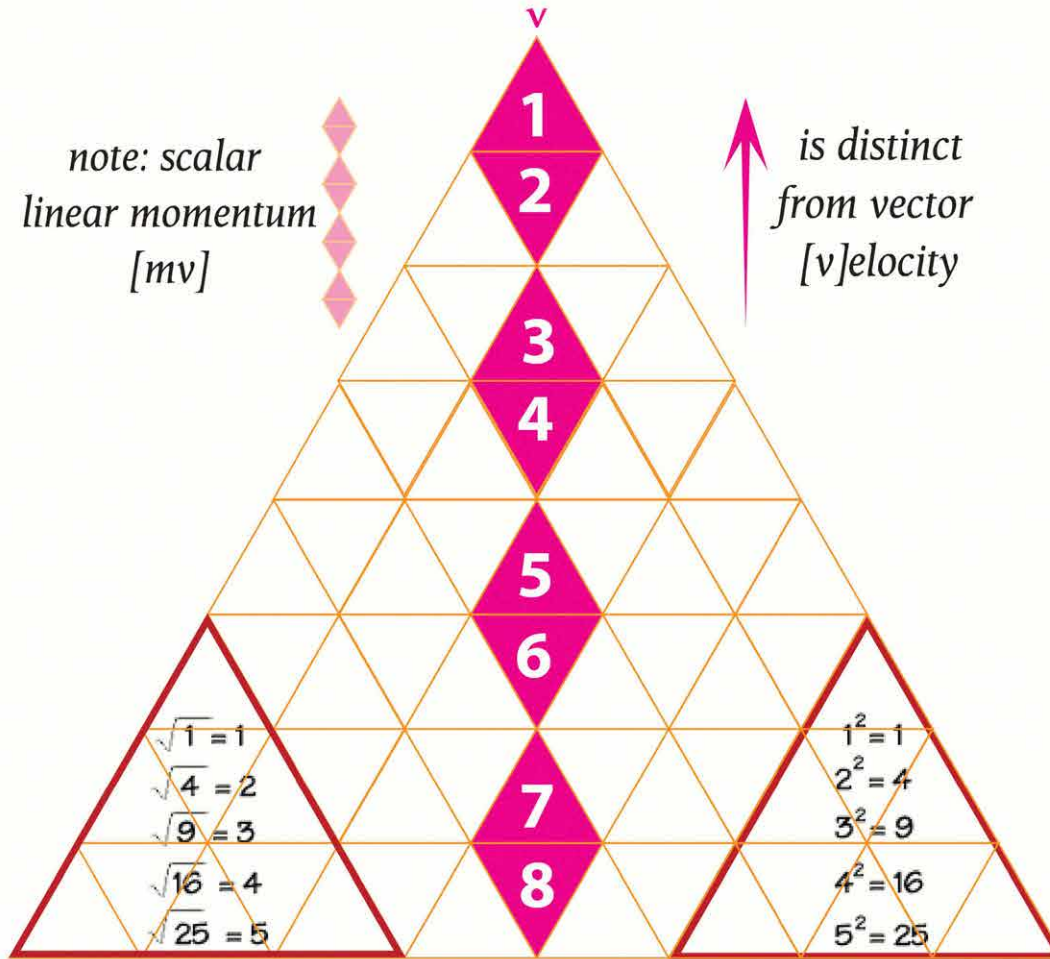
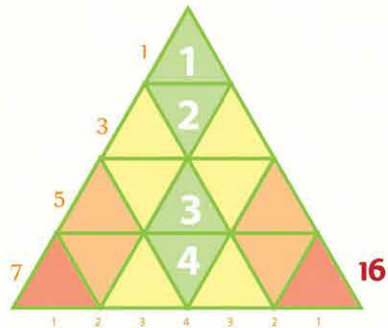
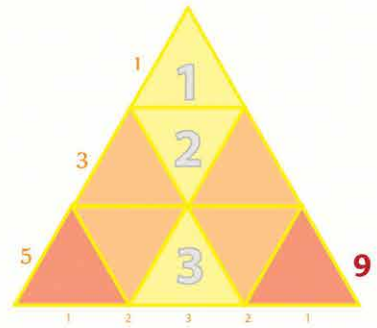
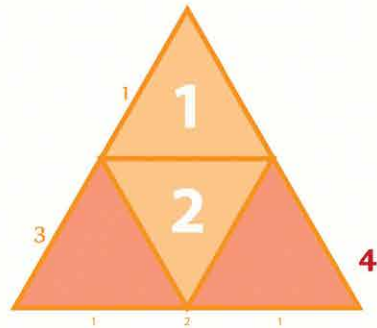
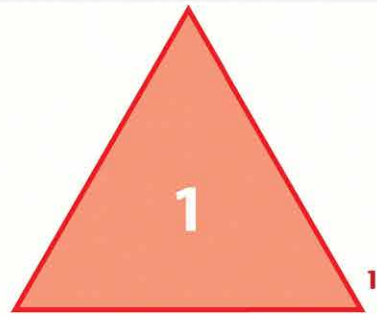
$$p = \sqrt{E}$$



Geometry can easily map irrational numbers

The Square roots of n

Historically, any number raised to the power of 2 has been modeled using a polygon—the square
That's why we call raising a number to the second power "squaring the number."

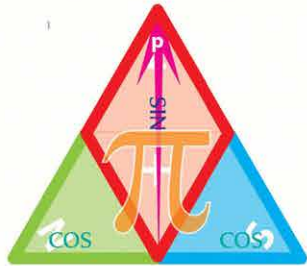


[In physics square numbers are in fact equilateral geometries]

The perfect squares are squares of whole numbers.

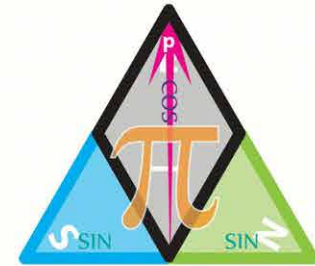
Here are the first eight perfect squares

The Square root of Negative 1



Positive fields are out of phase with Negative fields

Magnetic fields are out of phase with Electric fields

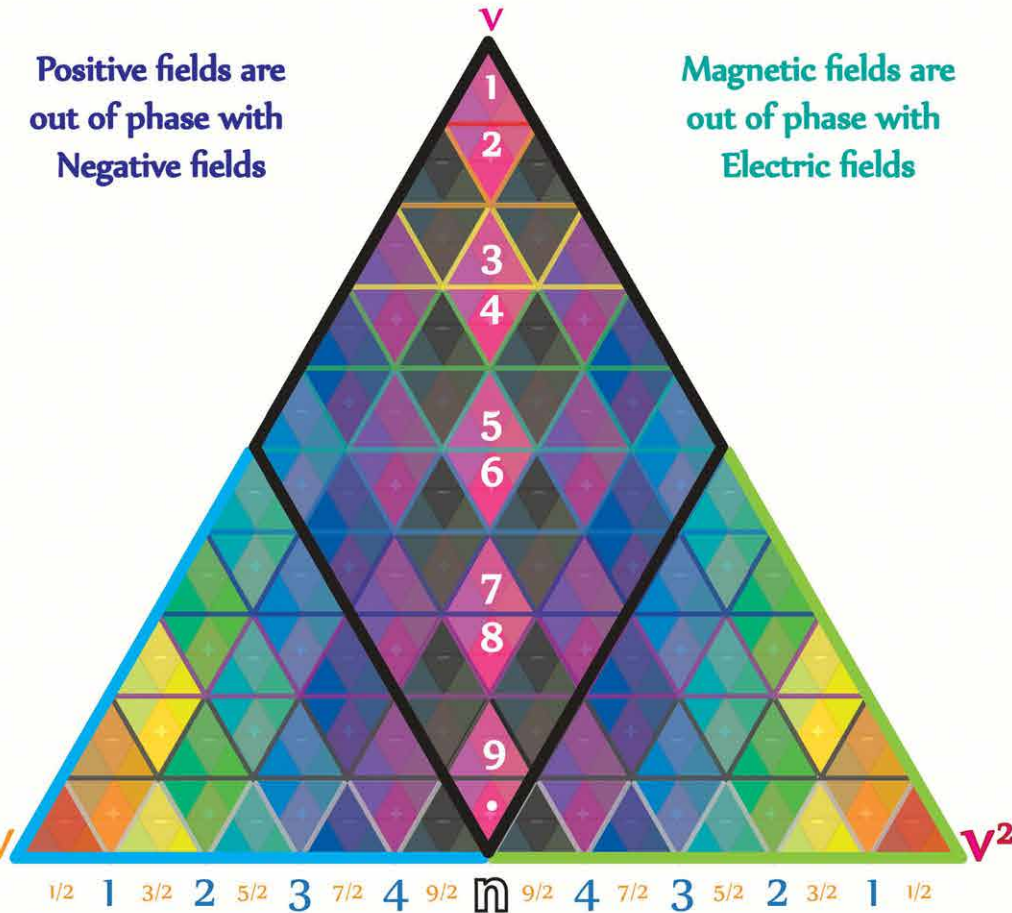


Euler's Formula

Euler's formula is often considered to be the basis of the complex number system. In deriving this formula, Euler established a relationship between the trigonometric functions, sine and cosine, and e raised to a power

$$e^{ix} = \cos(x) + i\sin(x)$$

a mathematical description of EM-Energy waveforms

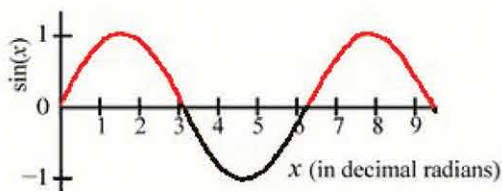


$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots \quad hv$$

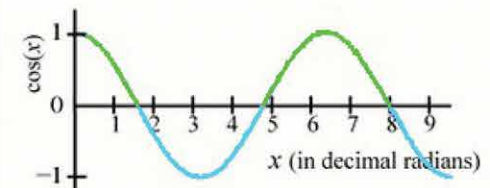
$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots$$

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \frac{x^5}{5!} + \dots$$

$$\sin x + \cos x = 1 + x - \frac{x^2}{2!} - \frac{x^3}{3!} + \frac{x^4}{4!} + \frac{x^5}{5!} + \dots$$



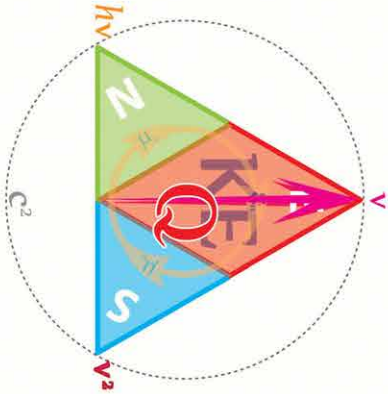
$$e^{i\pi} = -1 \quad \text{[Diagram: A diamond with a blue pi symbol and 'e' and 'i' on the sides]} \quad e^{i\pi} + 1 = 0$$



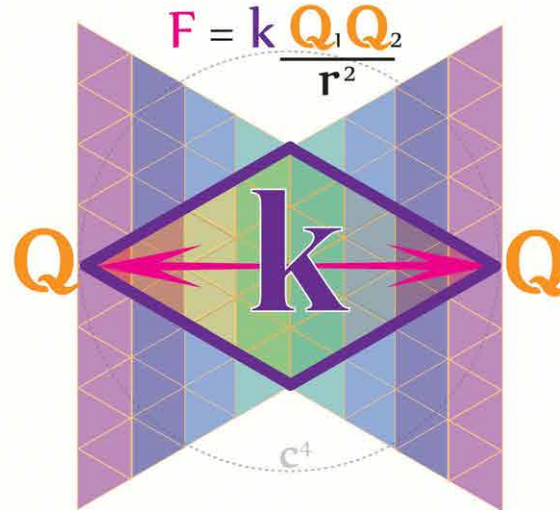
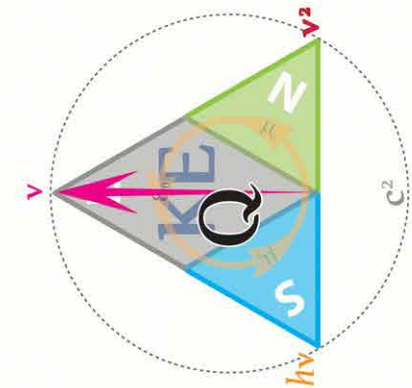
Geometric means

The geometric mean of two numbers, is the square root of their product

geometric square root
of positive one

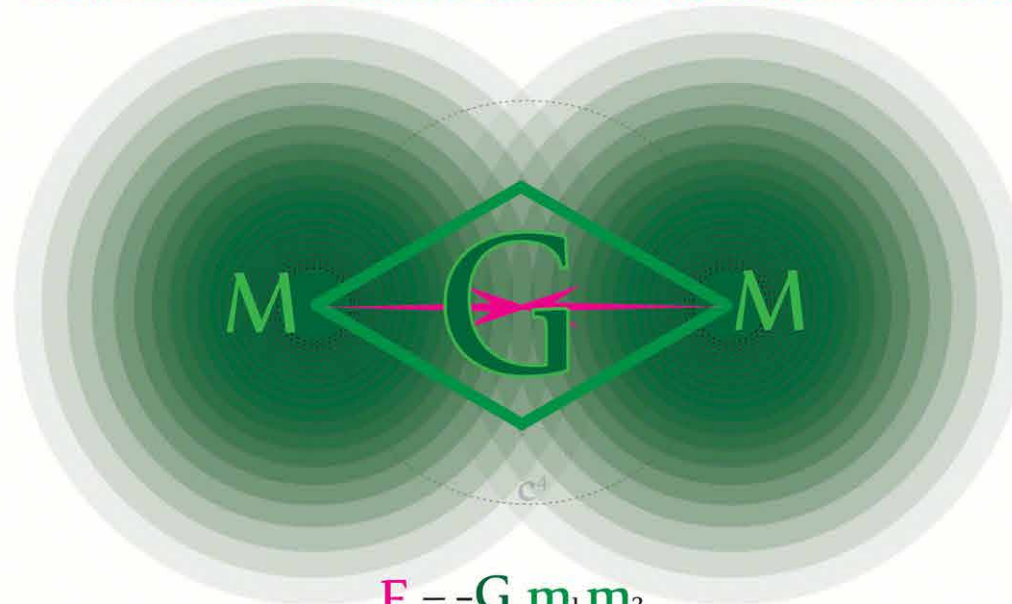


geometric square root
of negative one



In physics, the geometric mean of two superpositioned fields produces a vector square root Force

It is generally stated that
the geometric mean applies
only to positive numbers.

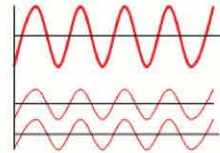


$$F = -G \frac{m_1 m_2}{r^2}$$

In Tetryonic geometry
the geometric mean applies
to positive & negative fields.

Superpositioning

When two or more waves traverse the same space, the net amplitude at each point is the sum of the amplitudes of the individual waves.

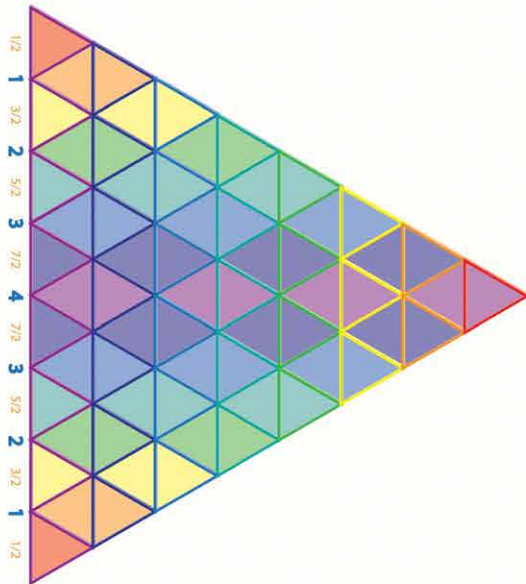


constructive interference

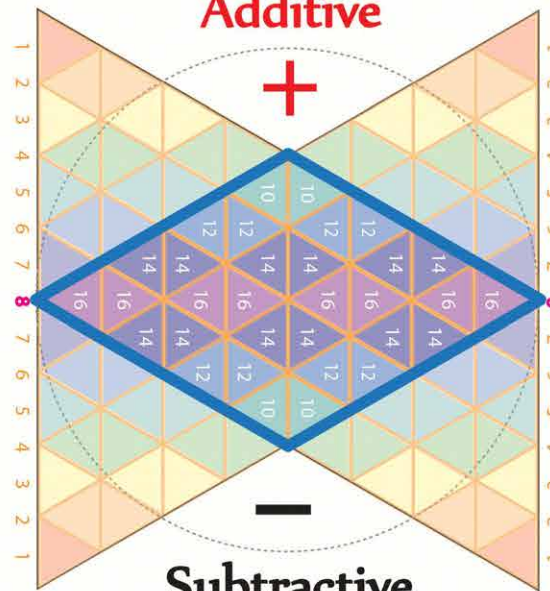
In phase

Additive

+

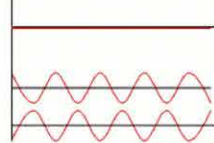


destructive interference

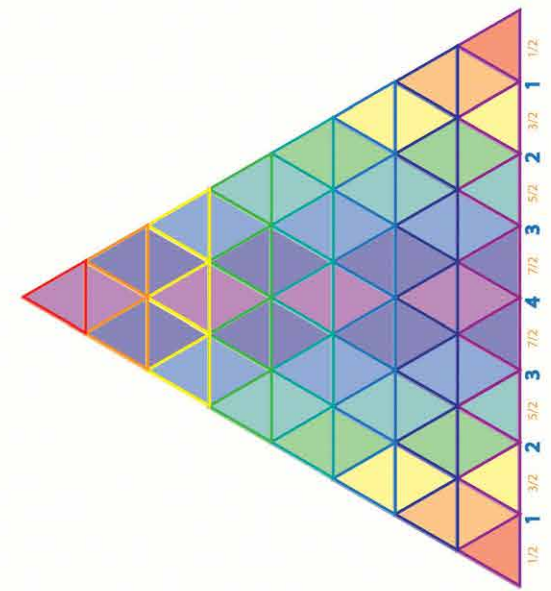


Subtractive

Out of phase



When two or more waves traverse the same space, if the summed variation has a smaller amplitude than the constituent component variations.



The lines of Force

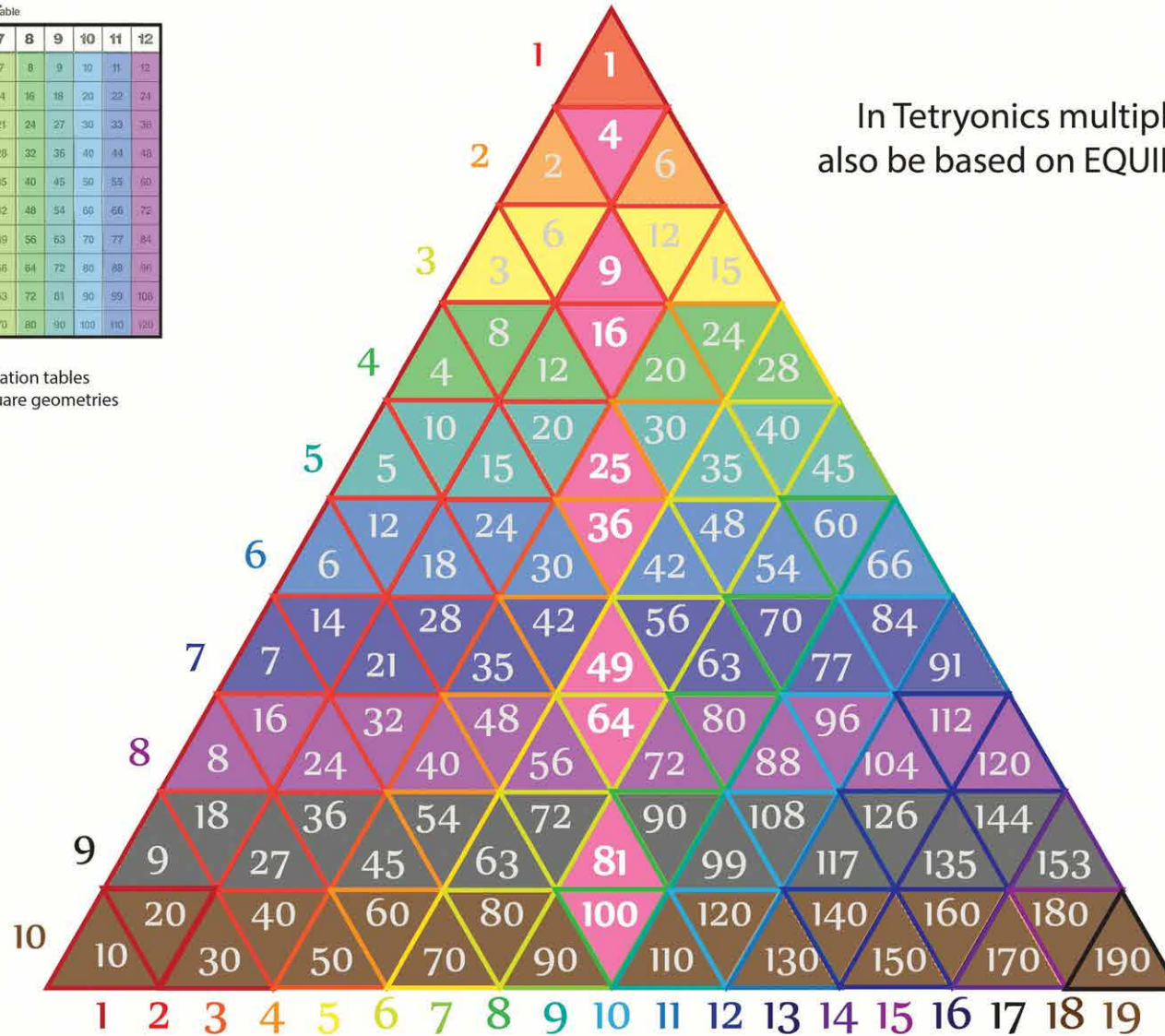
Tetryonic Multiplication table

A multiplication table is a mathematical grid used to define a multiplication operation and its results

Multiplication Table

	1	2	3	4	5	6	7	8	9	10	11	12
1	1	2	3	4	5	6	7	8	9	10	11	12
2	2	4	6	8	10	12	14	16	18	20	22	24
3	3	6	9	12	15	18	21	24	27	30	33	36
4	4	8	12	16	20	24	28	32	36	40	44	48
5	5	10	15	20	25	30	35	40	45	50	55	60
6	6	12	18	24	30	36	42	48	54	60	66	72
7	7	14	21	28	35	42	49	56	63	70	77	84
8	8	16	24	32	40	48	56	64	72	80	88	96
9	9	18	27	36	45	54	63	72	81	90	99	108
10	10	20	30	40	50	60	70	80	90	100	110	120

Historically Multiplication tables have been based on Square geometries

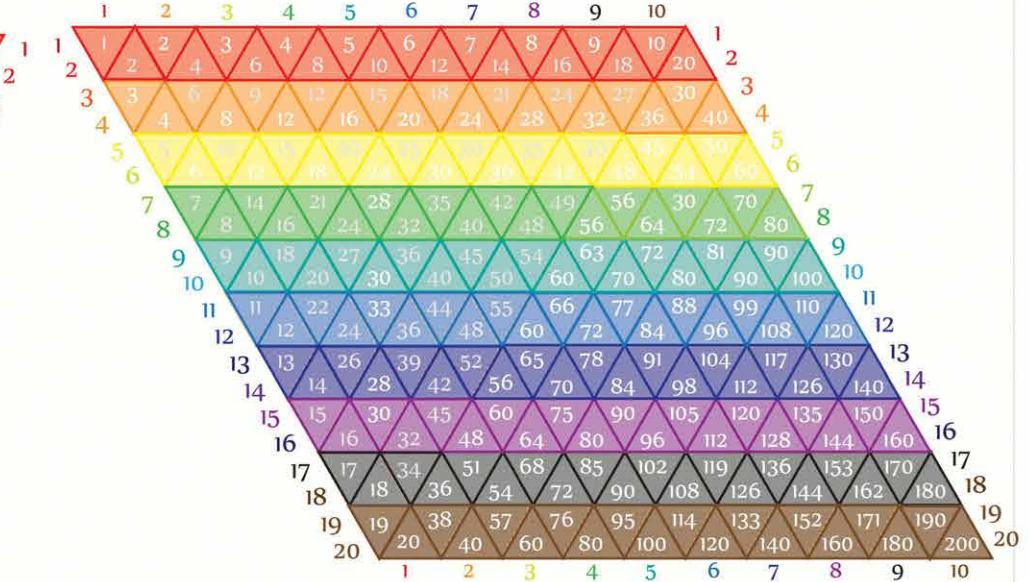
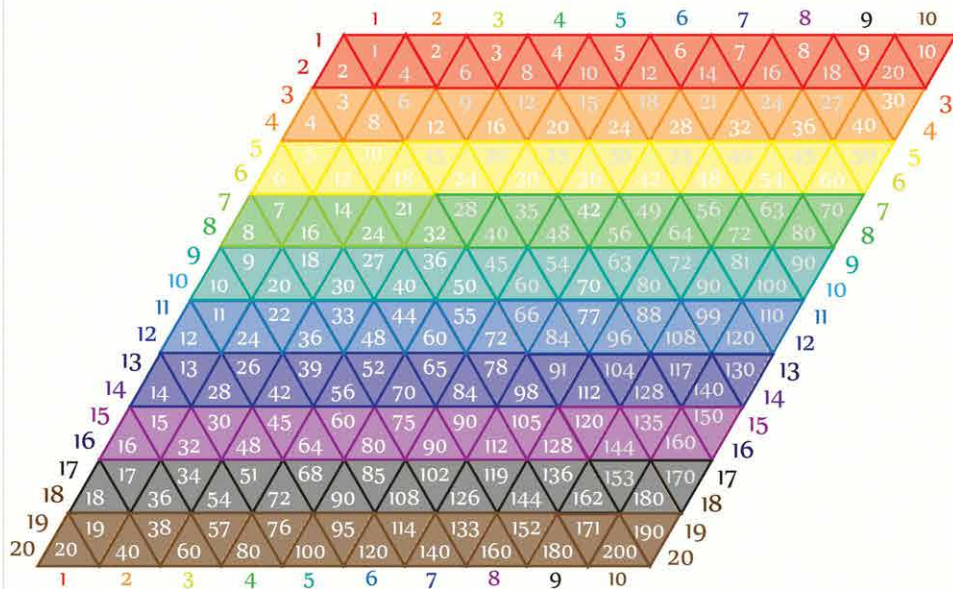
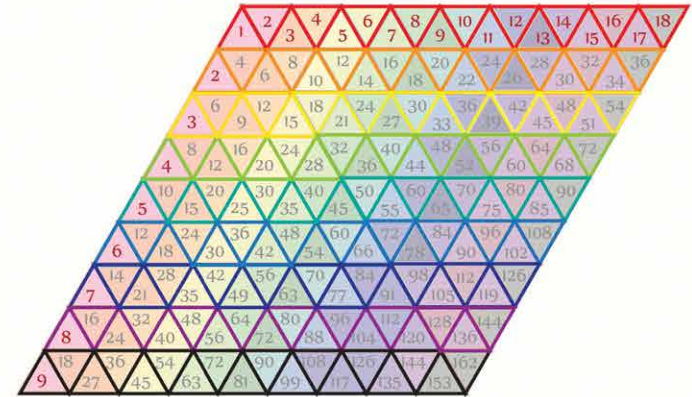
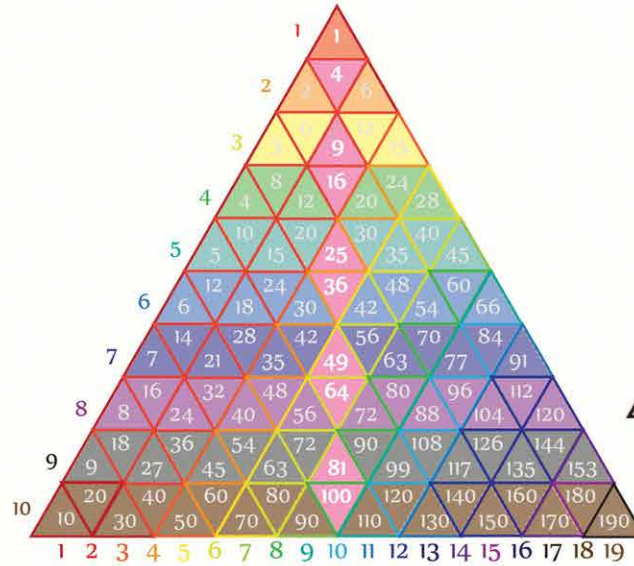


In Tetryonics multiplication tables can also be based on EQUILATERAL geometries

The integer multiplicators are colour coded

Rhombic Multiplication Tables

1	2	3	4	5	6	7	8	9	10
2	4	6	8	10	12	14	16	18	20
3	6	9	12	15	18	21	24	27	30
4	8	12	16	20	24	28	32	36	40
5	10	15	20	25	30	35	40	45	50
6	12	18	24	30	36	42	48	54	60
7	14	21	28	35	42	49	56	63	70
8	16	24	32	40	48	56	64	72	80
9	18	27	36	45	54	63	72	81	90
10	20	30	40	50	60	70	80	90	100



Photonic Root Tables

Tetryonic multiplication table can take a number of geometric forms

Square root median

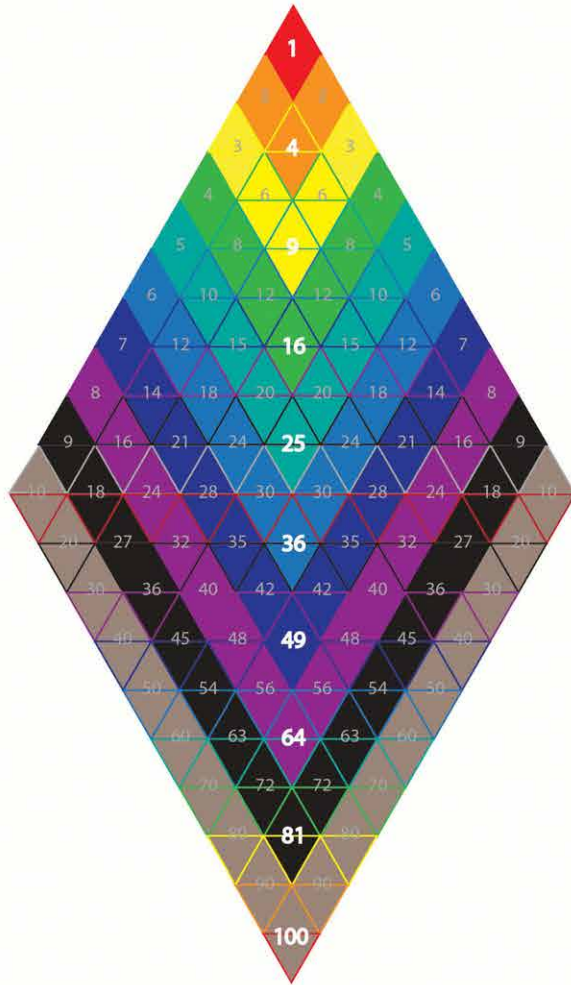
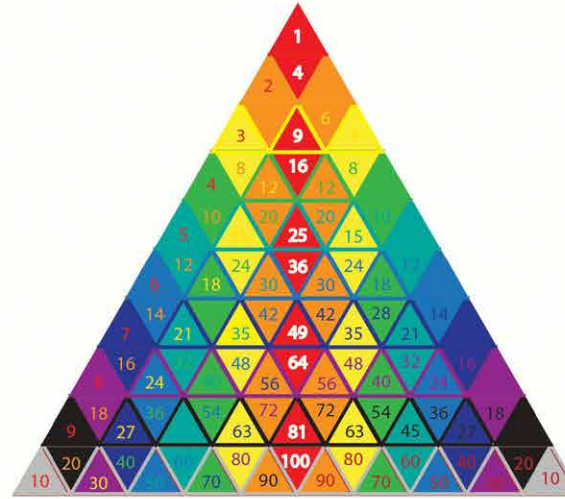


Table read diagonally

Integer median



1	2	3	4	5	6	7	8	9	10
2	4	6	8	10	12	14	16	18	20
3	6	9	12	15	18	21	24	27	30
4	8	12	16	20	24	28	32	36	40
5	10	15	20	25	30	35	40	45	50
6	12	18	24	30	36	42	48	54	60
7	14	21	28	35	42	49	56	63	70
8	16	24	32	40	48	56	64	72	80
9	18	27	36	45	54	63	72	81	90
10	20	30	40	50	60	70	80	90	100

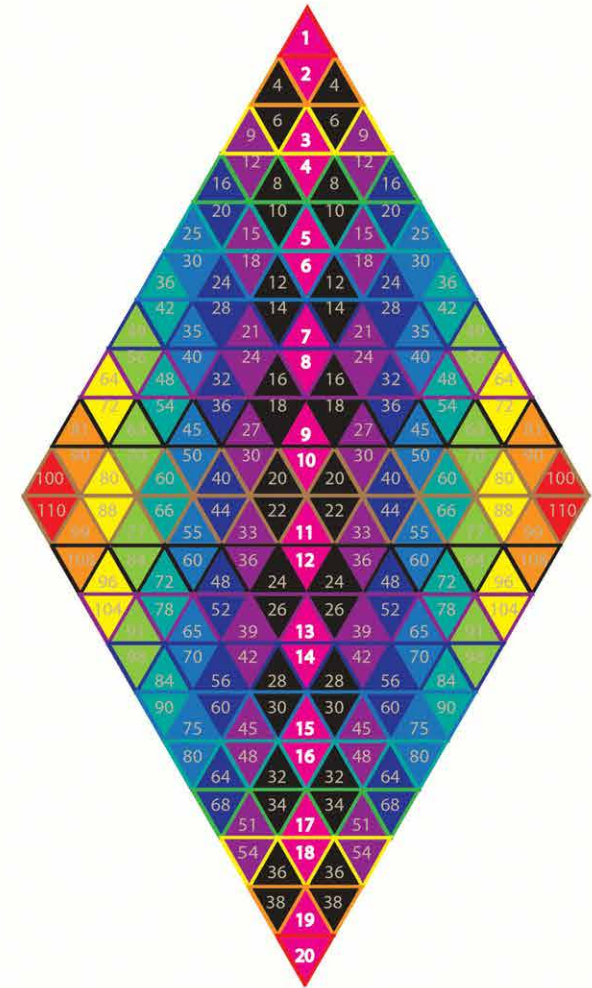
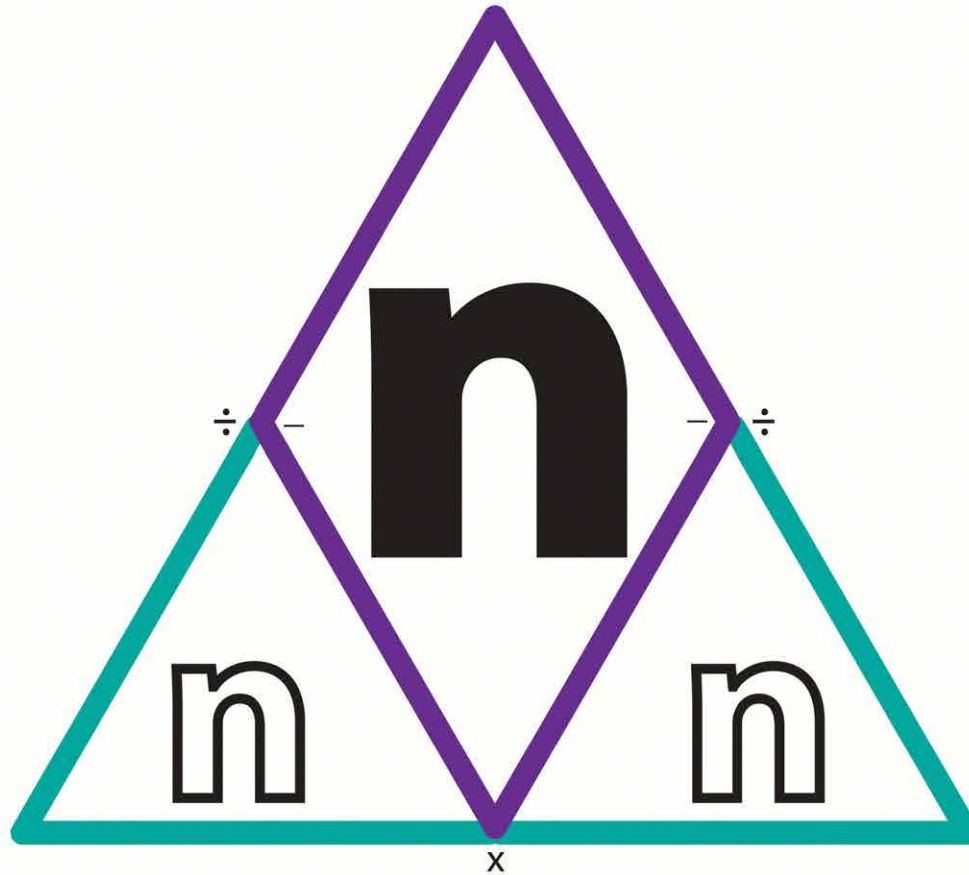


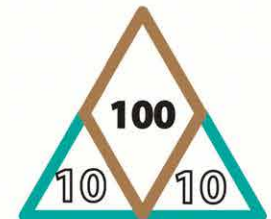
Table read from centre to outside edge then down

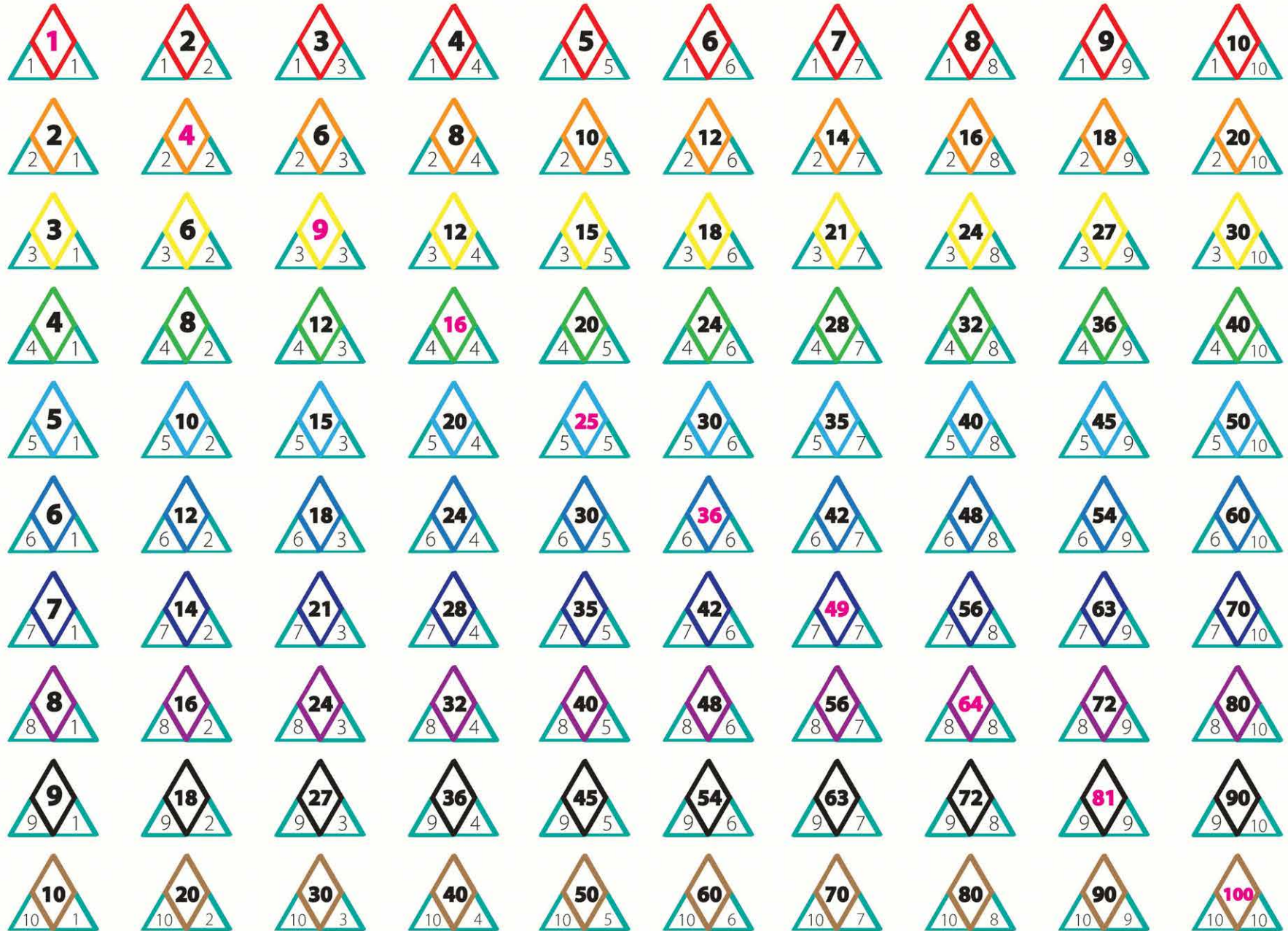


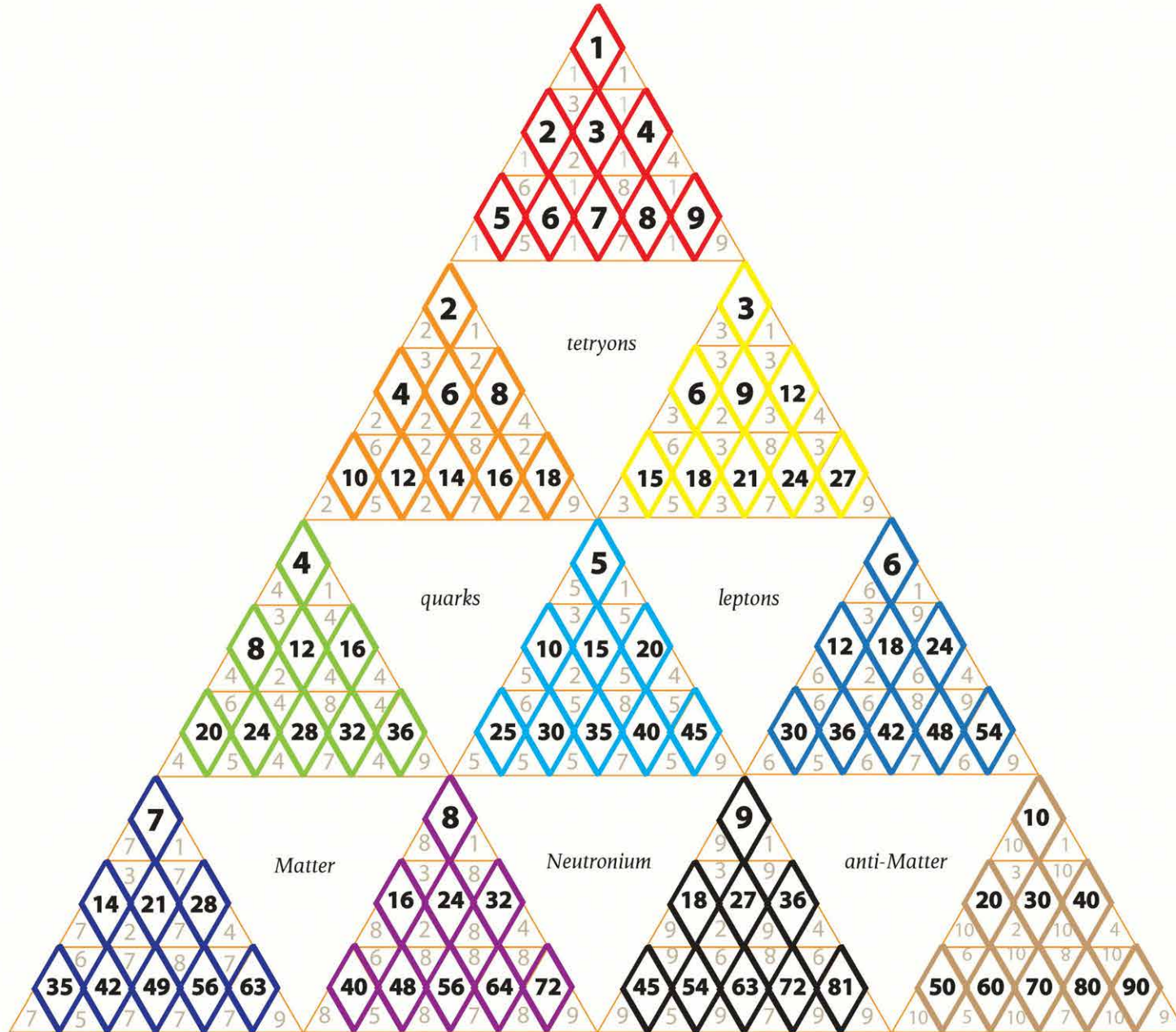
Divide [division] tables
Minus [subtraction] tables



Times [multiplication] tables
Plus [addition] tables

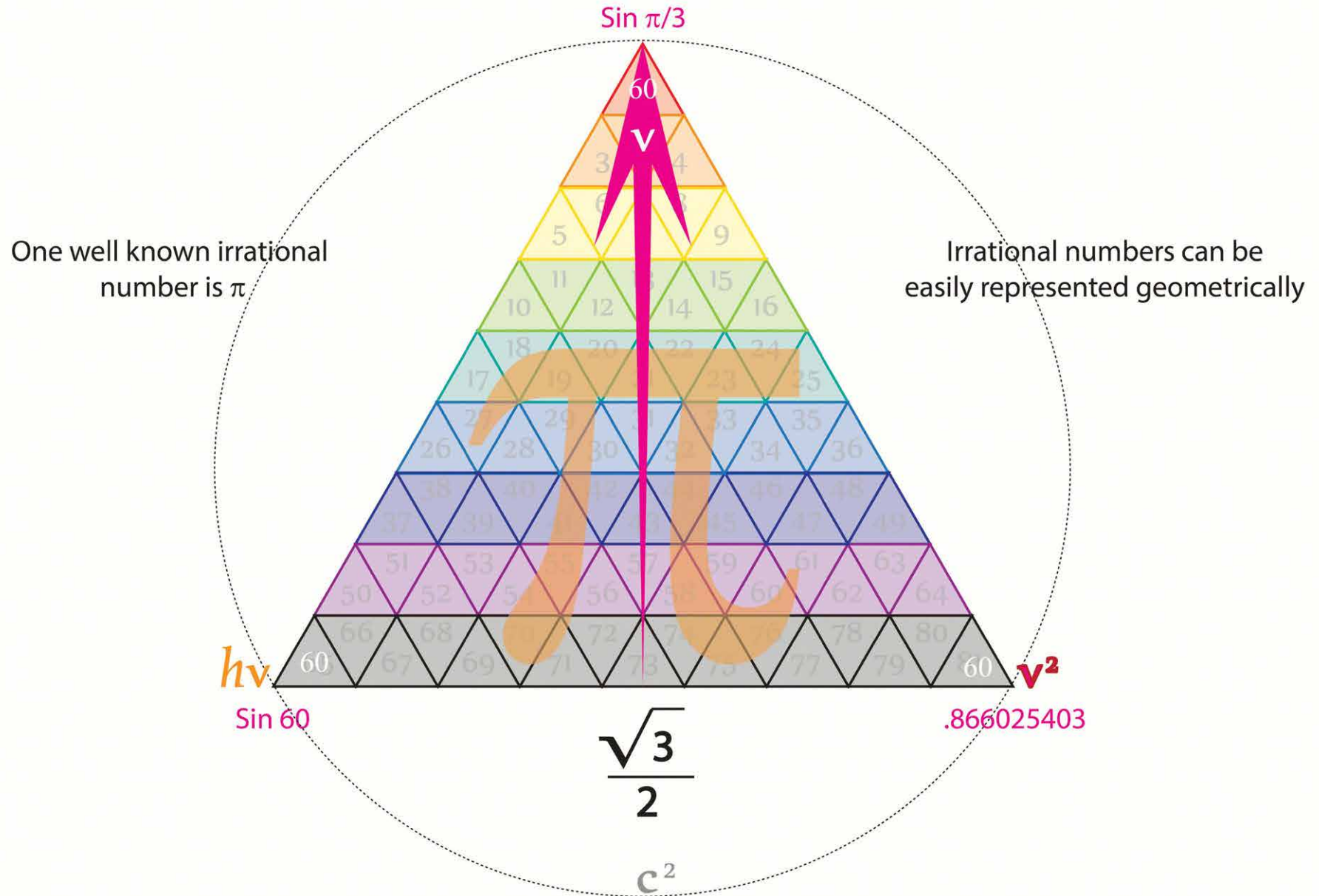






Irrational Numbers

An irrational number is defined to be any number that is the part of the real number system that cannot be written as a complete ratio of two integers



Exponentials & Logarithms

e and the Natural Log are inverse functions of each other:

e^x is the amount of continuous GROWTH after a certain amount of time.
 Natural Log (ln) is the amount of TIME of continuous growth to reach a certain level

1
 10
 100
 1,000

0
 1
 2
 3

10,000 = 10^4

$\log(10,000) = 4$

e

ln

How much growth after x units of time
 (and 100% continuous growth)

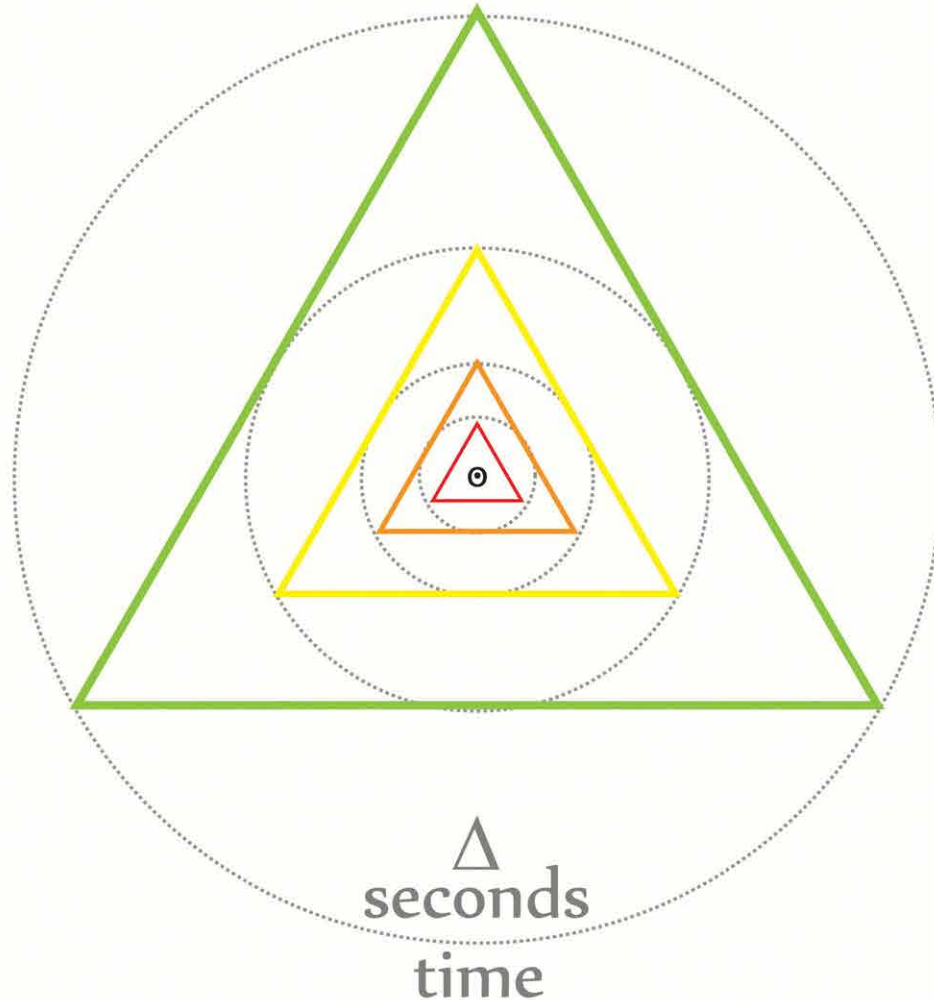
ln(x) lets us plug in continuous growth
 and get the time it would take.

$$e^x = \lim_{n \rightarrow \infty} (1 + x/n)^n,$$

$$\ln(x) = \lim_{n \rightarrow \infty} n(x^{1/n} - 1).$$

GROWTH

PERIOD



Exponential growth

$$\text{growth} = e = \lim_{n \rightarrow \infty} \left(1 + \frac{r}{n}\right)^n$$

e represents the idea that all continually growing systems are scaled versions of a common rate

GEOMETRIC

3.141592654

π

Pi is the ratio between circumference and diameter shared by all circles.

It is a fundamental ratio inherent in all circles and therefore impacts any calculation of circumference, area, volume, and surface areas

Pi radians are equally important and show all quantised equilateral energy geometries are related to their scribed circles

GROWTH

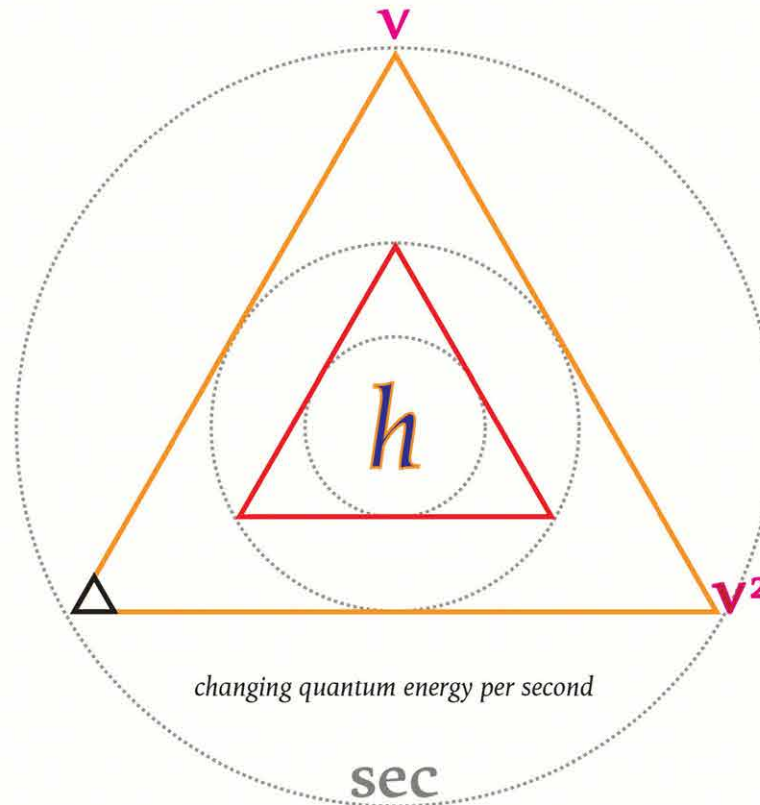
2.718281828

e

e is the base rate of growth shared by all continually growing processes.

e lets you take a simple growth rate (where all the change happens all at once at the end of a period of time - ie quantised growth)

e shows up whenever systems grow exponentially and continuously..... radioactive decay, interest calculations and populations



tetryons

EM fields

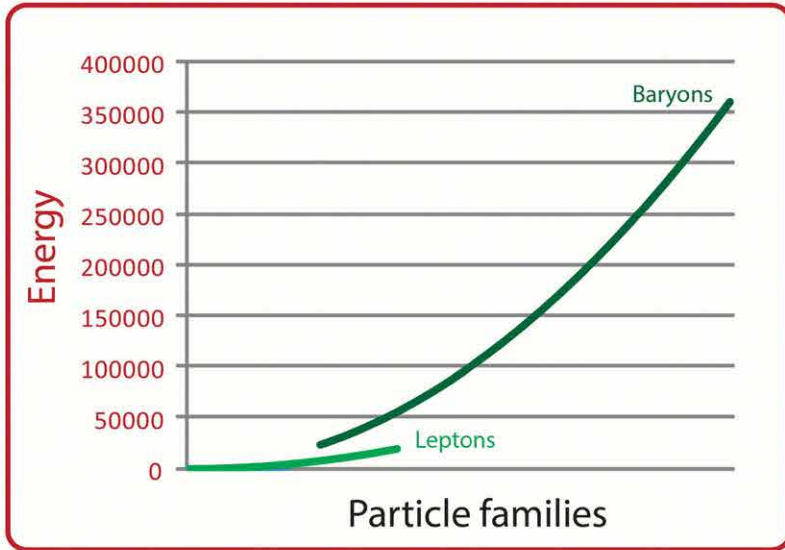
quarks

leptons

***e* can be applied to the equilateral energy geometries of physical systems only where the rate of increase is a integer factor of a squared number**

Baryons

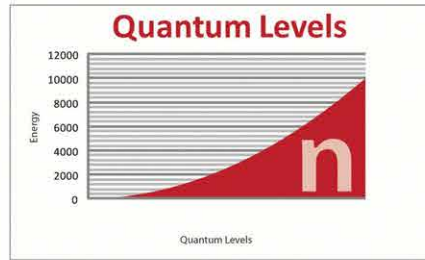
Nuclear Energy levels



The emission and absorption of bosons and Photons within sub-atomic nuclei

Increase and decrease in integer amounts according to the charged Tetryonic topologies of the particles involved

Exponential energy levels



Radioactive decays follow exponential curves determined by the Tetryonic topology of the sub-atomic particle families

$$36\pi \left[\left[\begin{matrix} \text{EM Field} \\ \epsilon_0 \mu_0 \end{matrix} \right] \cdot \left[\begin{matrix} \text{Planck quanta} \\ m \Omega v^2 \end{matrix} \right] \right]$$

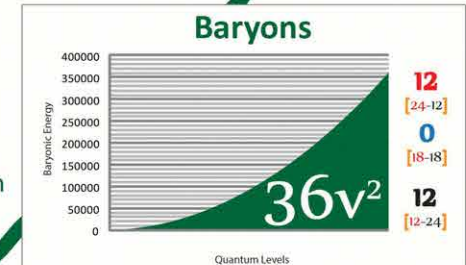
Baryons ElectroMagnetic mass velocity

$$12\pi \left[\left[\begin{matrix} \text{EM Field} \\ \epsilon_0 \mu_0 \end{matrix} \right] \cdot \left[\begin{matrix} \text{Planck quanta} \\ m \Omega v^2 \end{matrix} \right] \right]$$

quarks leptons ElectroMagnetic mass velocity

$$4\pi \left[\left[\begin{matrix} \text{EM Field} \\ \epsilon_0 \mu_0 \end{matrix} \right] \cdot \left[\begin{matrix} \text{Planck quanta} \\ m \Omega v^2 \end{matrix} \right] \right]$$

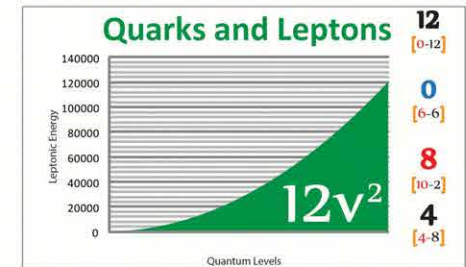
tetryons ElectroMagnetic mass velocity



Proton
Neutron

antiNeutron
antiProton

12
[12-0]

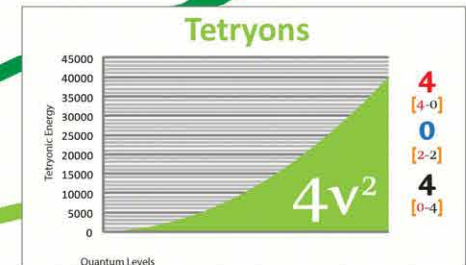


Electron
Positron

Neutrino

Up
Down
Strange
Charmed
Top
Bottom

12
[0-12]



Positive
Negative
Neutral

4
[4-0]

Series addition & the Riemann Zeta Function

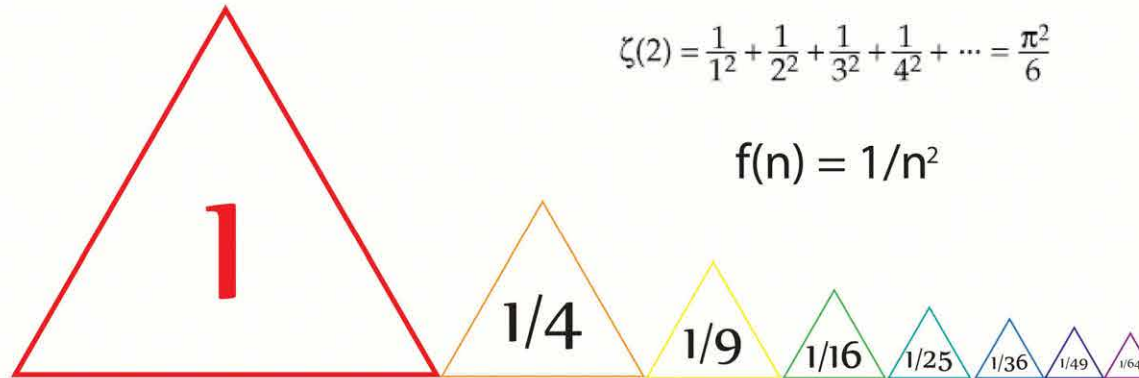
The second series addition of the Riemann Zeta function is where $x=2$: $(\pi^2)/6=1+1/2^2+1/3^2+1/4^2+\dots$
 (the sum of the reciprocals of the squares)

$$\zeta(s) = \sum_n \frac{1}{n^s}$$

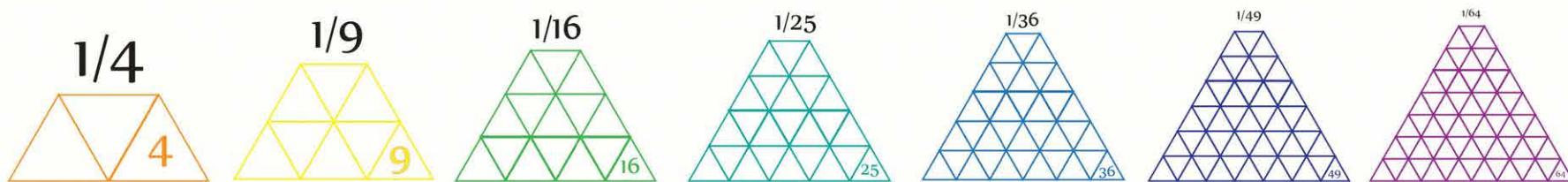
$$\zeta(2) = \frac{1}{1^2} + \frac{1}{2^2} + \frac{1}{3^2} + \frac{1}{4^2} + \dots = \frac{\pi^2}{6}$$

$$\sum_{n=1}^{\infty} \frac{1}{n^x}$$

$$f(n) = 1/n^2$$



In mathematics, the Riemann zeta function, is a prominent function of great significance in number theory. It is named after German mathematician Bernhard Riemann. It is so important because of its relation to the distribution of prime numbers. It also has applications in other areas such as physics, probability theory, and applied statistics



The mystery of prime numbers

Question: which natural numbers are prime? how are they distributed among natural numbers?

Primes are basic building blocks for natural numbers:

- any natural number is a product of prime numbers
- a prime number is only divisible by itself and by 1:
 (it cannot be further simplified)

We don't know how to predict where the prime numbers are:

"Prime numbers grow like weeds among the natural numbers, seeming to obey no other law than that of chance but also exhibit stunning regularity" (Don Zagier, number theorist)

Adding the odd numbers in order produces the square numbers

Apart from 2, all primes are odd numbers;
the difference between two consecutive squares being odd,
every prime can be expressed as the difference between two squares

SPECTRAL LINES

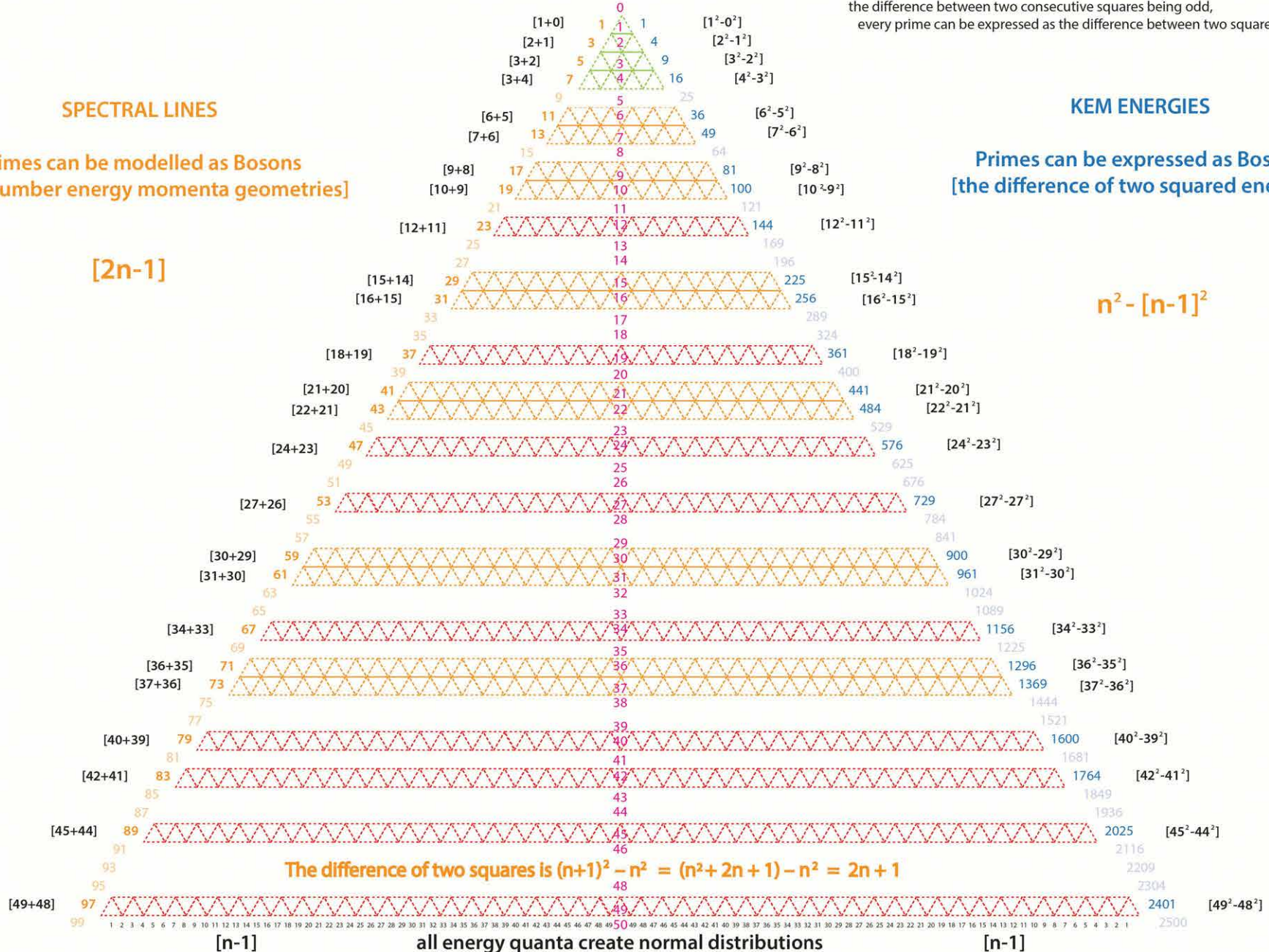
KEM ENERGIES

Primes can be modelled as Bosons
[ODD number energy momenta geometries]

Primes can be expressed as Bosons
[the difference of two squared energies]

$[2n-1]$

$n^2 - [n-1]^2$



The difference of two squares is $(n+1)^2 - n^2 = (n^2 + 2n + 1) - n^2 = 2n + 1$

all energy quanta create normal distributions

Prime number

A twin prime is a prime number that differs from another prime number by two, for example the twin prime pair (41, 43). Sometimes the term twin prime is used for a pair of twin primes; an alternative name for this is prime twin or prime pair.

Twin primes appear despite the general tendency of gaps between adjacent primes to become larger as the numbers themselves get larger due to the prime number theorem (the "average gap" between primes less than n is $\log(n)$).

$$p_2 - p_1 = 2$$

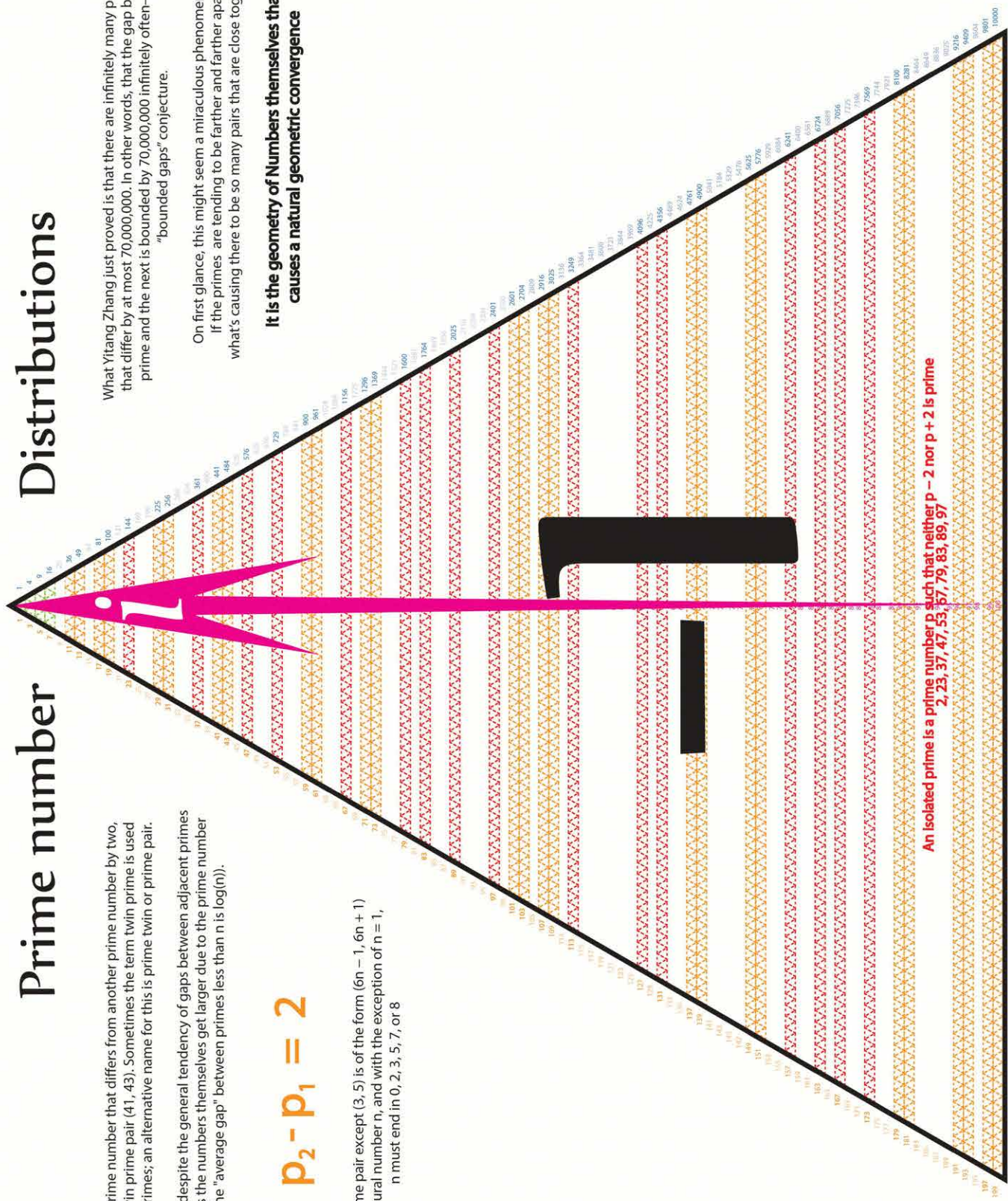
Every twin prime pair except (3, 5) is of the form $(6n - 1, 6n + 1)$ for some natural number n , and with the exception of $n = 1$, n must end in 0, 2, 3, 5, 7, or 8

Distributions

What Yitang Zhang just proved is that there are infinitely many pairs of primes that differ by at most 70,000,000. In other words, that the gap between one prime and the next is bounded by 70,000,000 infinitely often—thus, the "bounded gaps" conjecture.

On first glance, this might seem a miraculous phenomenon. If the primes are tending to be farther and farther apart, what's causing there to be so many pairs that are close together?

It is the geometry of Numbers themselves that causes a natural geometric convergence

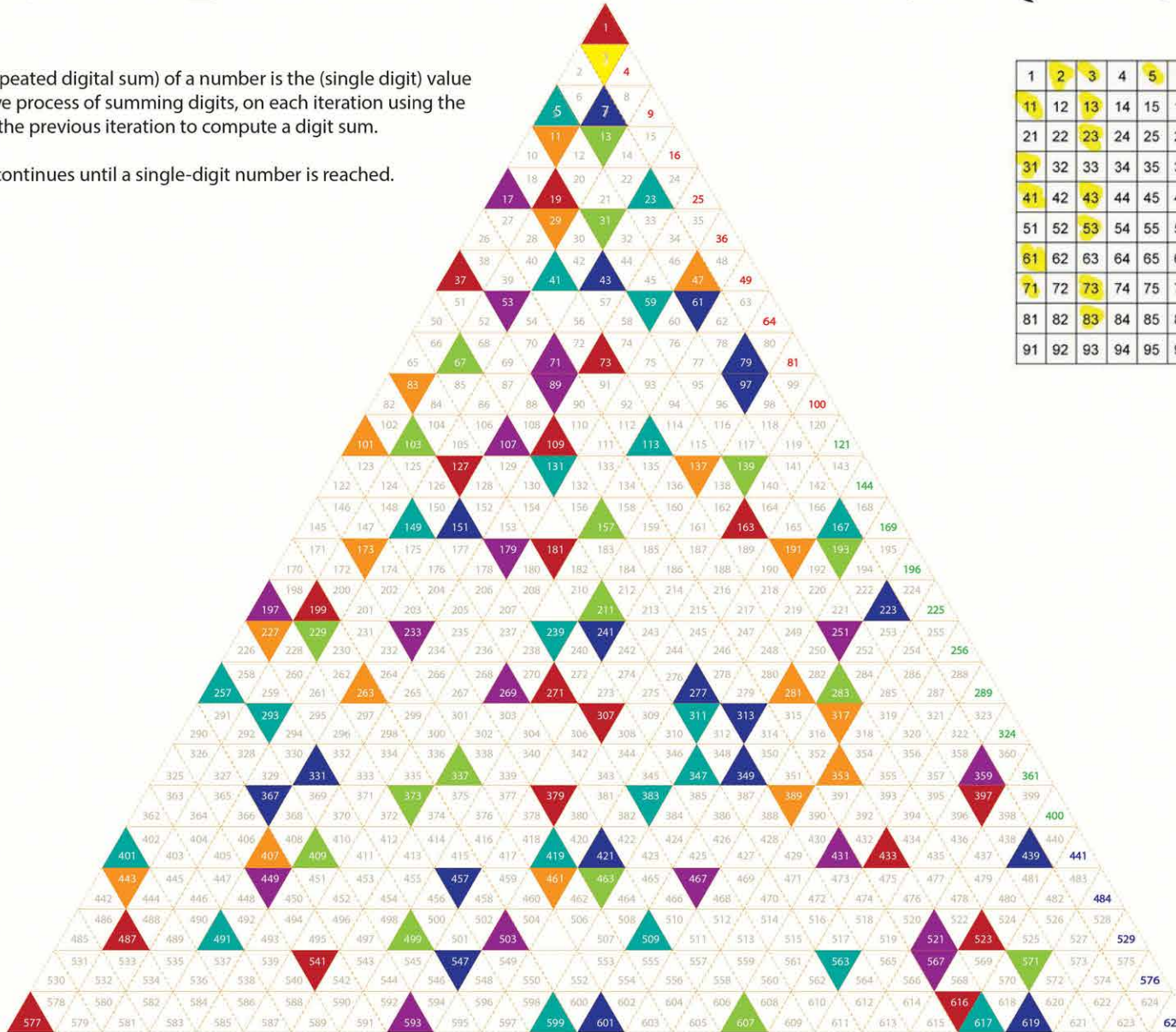


An isolated prime is a prime number p such that neither $p - 2$ nor $p + 2$ is prime
 2, 23, 37, 47, 53, 67, 79, 83, 89, 97

The Digital roots of Prime numbers

The digital root (also repeated digital sum) of a number is the (single digit) value obtained by an iterative process of summing digits, on each iteration using the result from the previous iteration to compute a digit sum.

The process continues until a single-digit number is reached.



1	2	3	4	5	6	7	8	9	10
11	12	13	14	15	16	17	18	19	20
21	22	23	24	25	26	27	28	29	30
31	32	33	34	35	36	37	38	39	40
41	42	43	44	45	46	47	48	49	50
51	52	53	54	55	56	57	58	59	60
61	62	63	64	65	66	67	68	69	70
71	72	73	74	75	76	77	78	79	80
81	82	83	84	85	86	87	88	89	90
91	92	93	94	95	96	97	98	99	100

Archimedes is given credit for the first calculus.

Archimedes infinite series

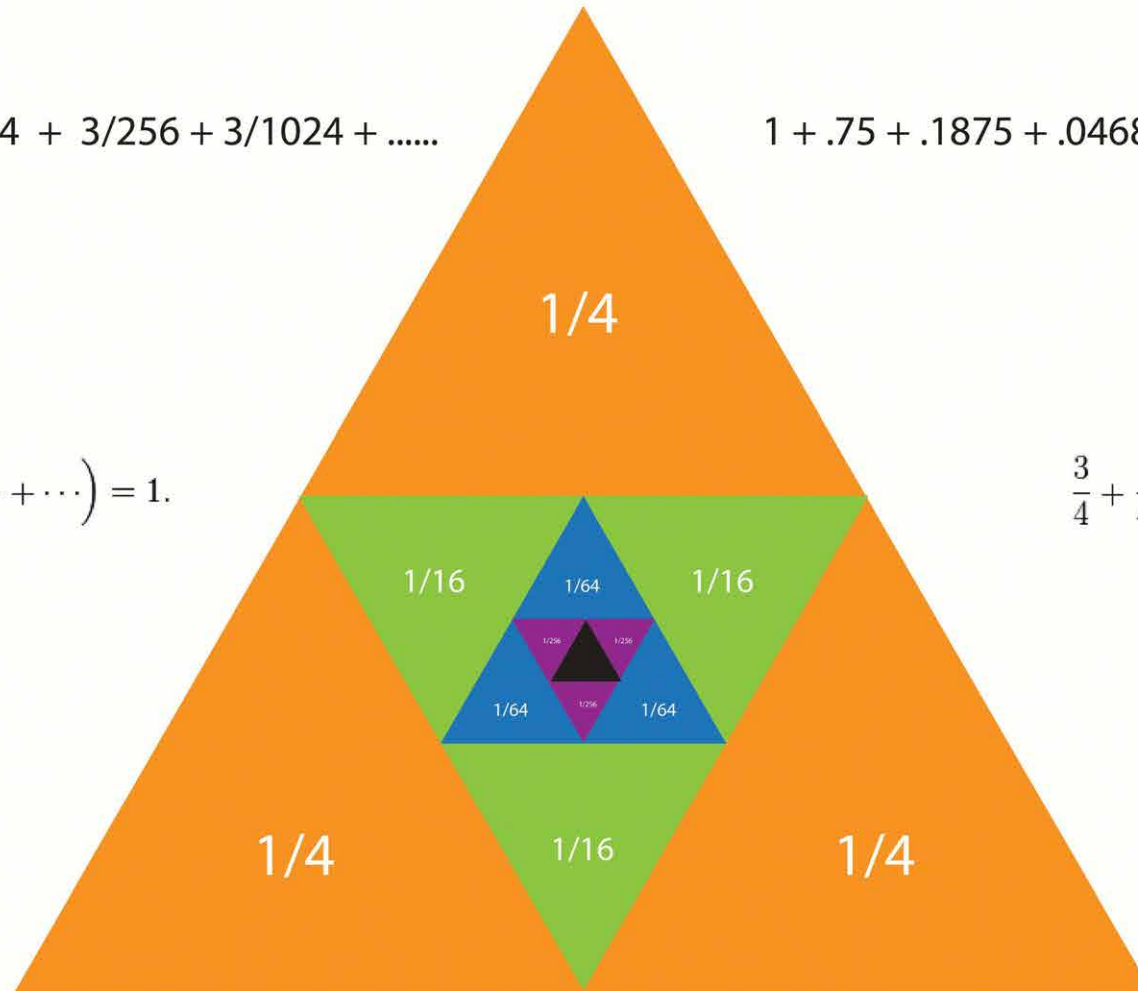
Today's calculus was published by Newton.

$$1 + 3/4 + 3/16 + 3/64 + 3/256 + 3/1024 + \dots$$

$$1 + .75 + .1875 + .046875 + .01171875 + \dots$$

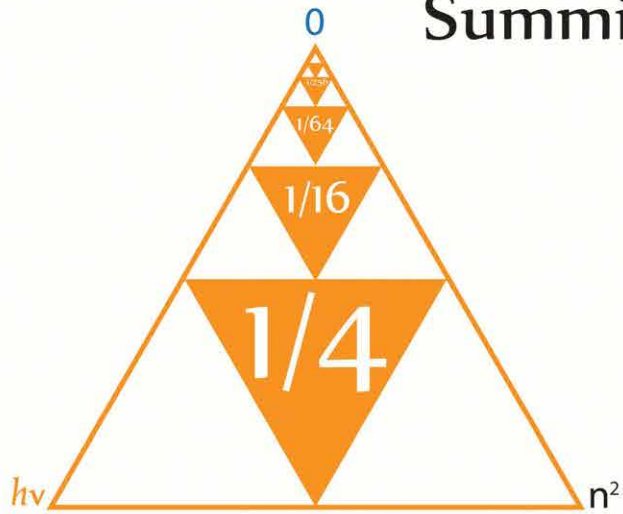
$$3 \left(\frac{1}{4} + \frac{1}{4^2} + \frac{1}{4^3} + \frac{1}{4^4} + \dots \right) = 1.$$

$$\frac{3}{4} + \frac{3}{4^2} + \frac{3}{4^3} + \frac{3}{4^4} + \dots = 1.$$



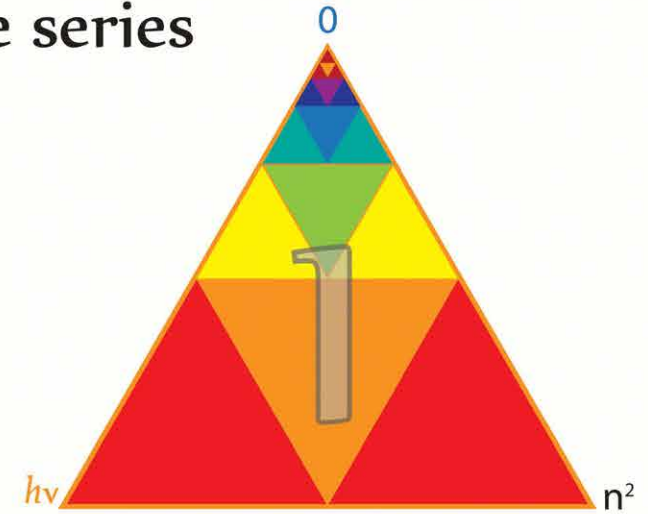
Nested convergent infinite series

Summing a convergent infinite series



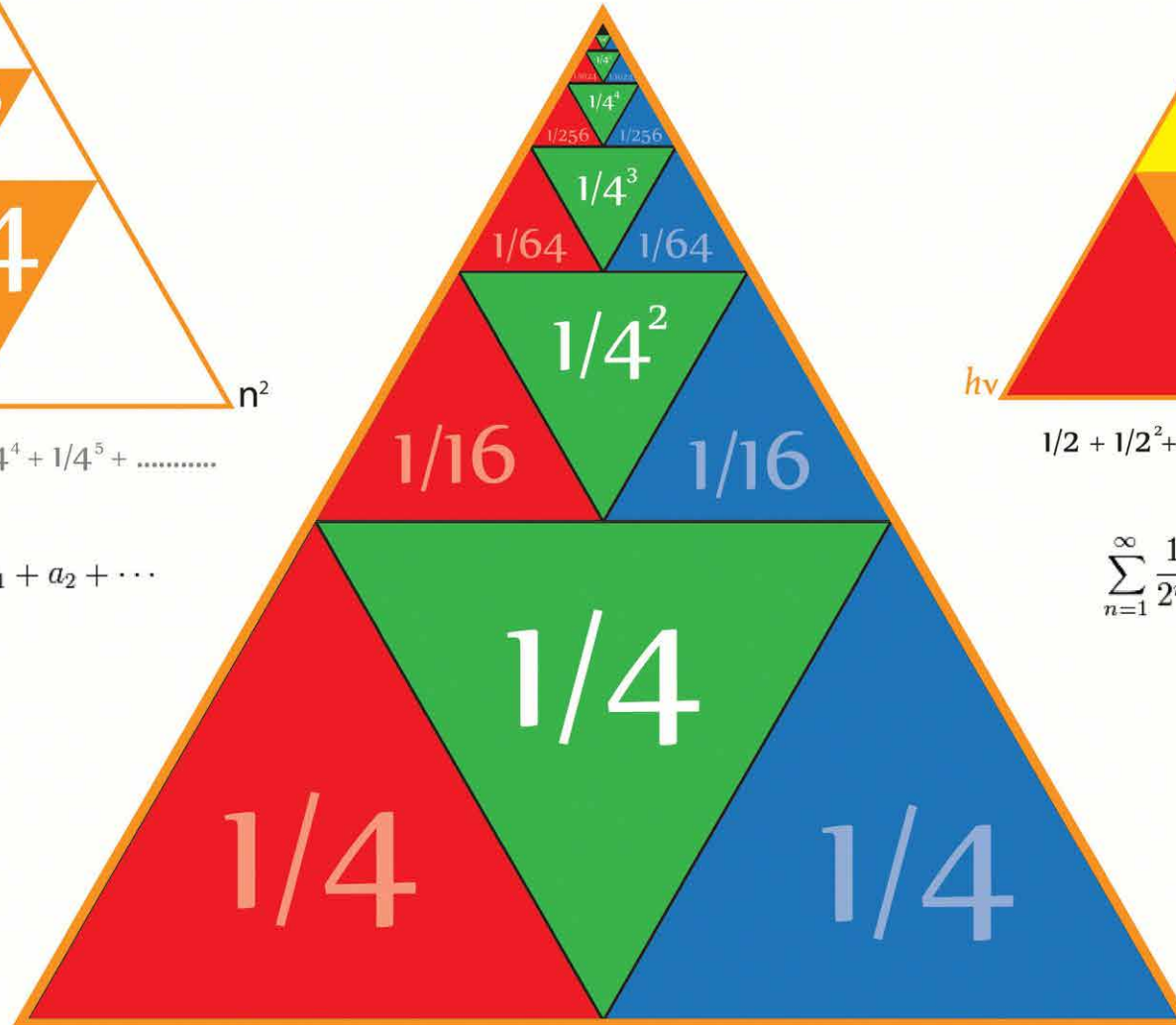
$$1/4 + 1/4^2 + 1/4^3 + 1/4^4 + 1/4^5 + \dots$$

$$\sum_{n=0}^{\infty} a_n = a_0 + a_1 + a_2 + \dots$$



$$1/2 + 1/2^2 + 1/2^3 + 1/2^4 + 1/2^5 + \dots$$

$$\sum_{n=1}^{\infty} \frac{1}{2^n} = \frac{1}{2} + \frac{1}{4} + \frac{1}{8} + \dots$$



$$\text{ODDS} = 2n-1$$

$$\sum_1^n 2n-1 = n^2$$

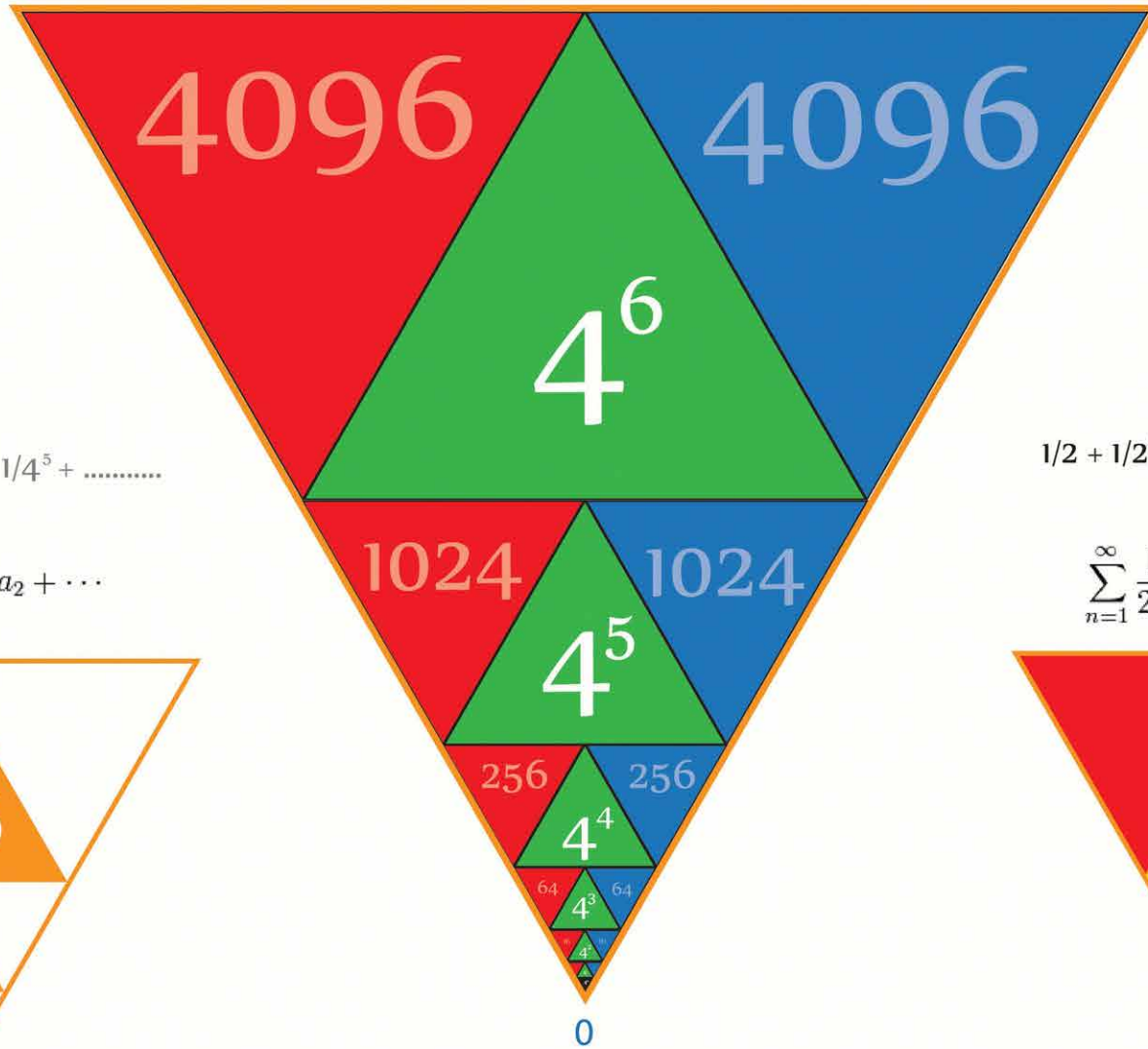
Summing the dissimilar coloured equilateral triangles gives unity

$$1/3$$

$$1/3$$

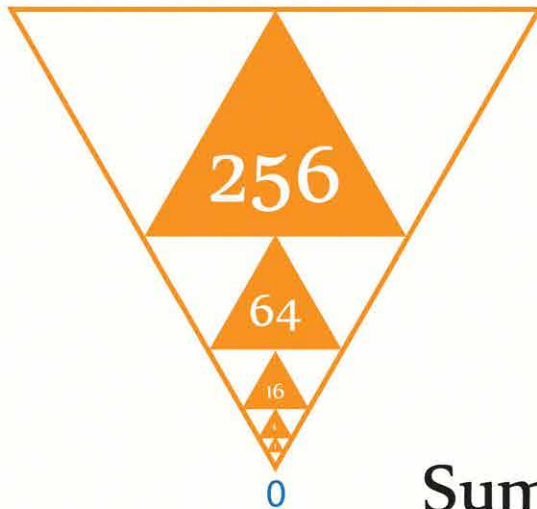
$$1/3$$

$\frac{1}{3}$ $\frac{1}{3}$ $\frac{1}{3}$
 Summing the dissimilar coloured equilateral triangles gives unity



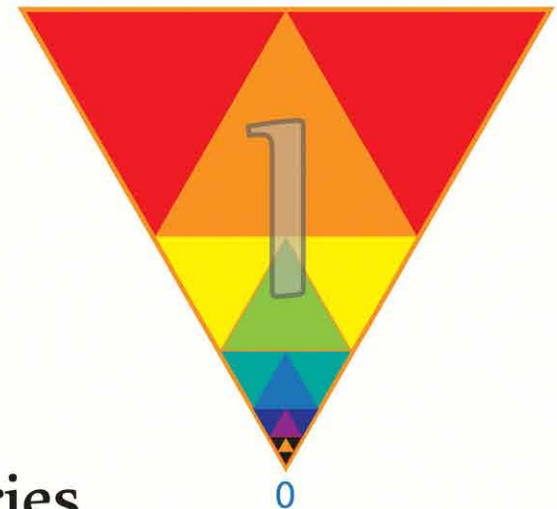
$$1/4 + 1/4^2 + 1/4^3 + 1/4^4 + 1/4^5 + \dots$$

$$\sum_{n=0}^{\infty} a_n = a_0 + a_1 + a_2 + \dots$$



$$1/2 + 1/2^2 + 1/2^3 + 1/2^4 + 1/2^5 + \dots$$

$$\sum_{n=1}^{\infty} \frac{1}{2^n} = \frac{1}{2} + \frac{1}{4} + \frac{1}{8} + \dots$$



Summing a divergent infinite series

Pietro Mengoli



(1626 – June 7, 1686)

The Basel Problem

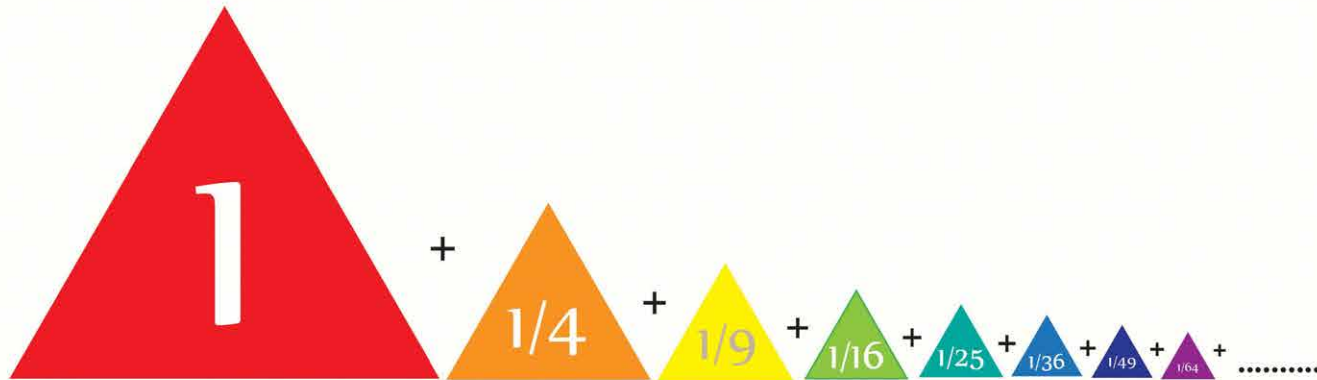
The Basel problem is a famous problem in mathematical analysis with relevance to number theory, first posed by Pietro Mengoli in 1644 and solved by Leonhard Euler in 1735.

$$\zeta(2) = \frac{1}{1^2} + \frac{1}{2^2} + \frac{1}{3^2} + \frac{1}{4^2} + \dots = \frac{\pi^2}{6} \approx 1.644934$$

Leonhard Euler



(15 April 1707 – 18 Sept 1783)



The Basel problem asks for the precise summation of the reciprocals of the squares of the natural numbers, i.e. the precise sum of the infinite series

$$f(n) = 1/n^2$$



Integrals of mass-energy

is a means of finding scalar areas using summation and limits.

Integration is a micro adding of **CONTINUOUS** quantities.

$$\int_n^{\infty} f(x)$$

Integration is a special case of summation.

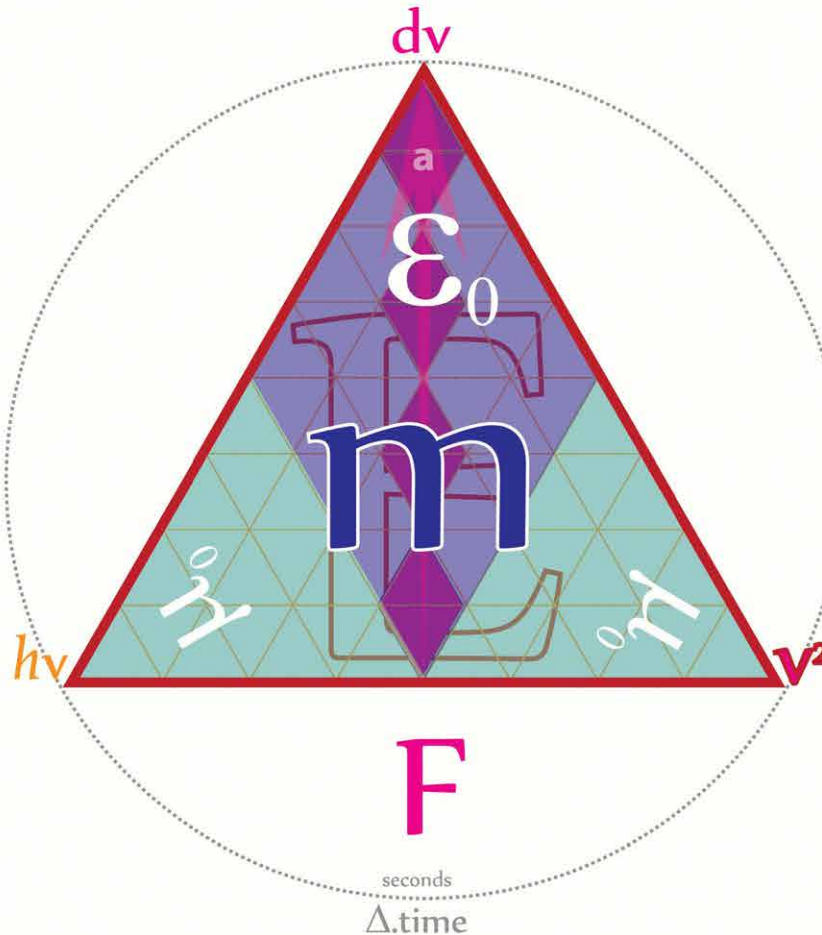
Integration is defined as the limit of a summation as the number of elements approaches infinity while a part of their respective value approaches zero.

Summation is the finite sum of multiple, fixed values.

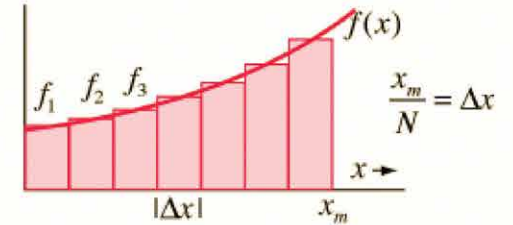
$$\sum_n^{\infty} x$$

Summation is a macro adding of **DISCRETE** quantities.

The summation of equilateral energy momenta quanta with respect to their linear vector components



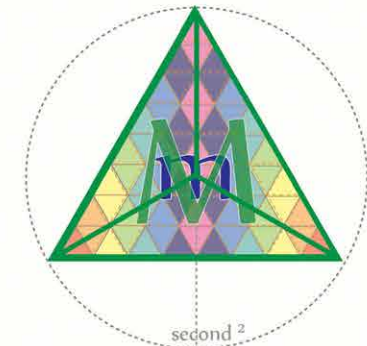
Integrating the energy quanta contained within equilateral charge geometry gives the variable Force required to achieve changes in motion [Energy, work, acceleration]



The Integral of the continuous area under the curve is the summation of an infinite number of discrete rectangular measurements made to a specified limit

An integration isn't a simple summation, but the limit of a sequence of summations

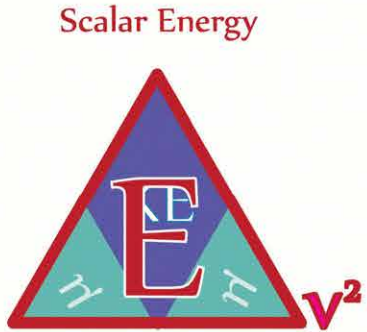
All Planck energies are discrete equilateral geometries



mass is the surface integral of EM energy geometries per unit of time

"The calculus of infinitesimals"

The fundamental theorem of calculus simply states that the sum of infinitesimal changes in a quantity over time adds up to the net change in the quantity.

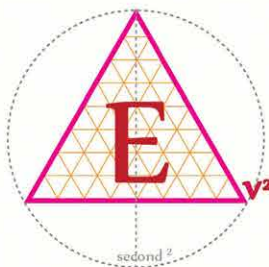


$$E = mv^2$$

Gottfried Wilhelm von Leibniz



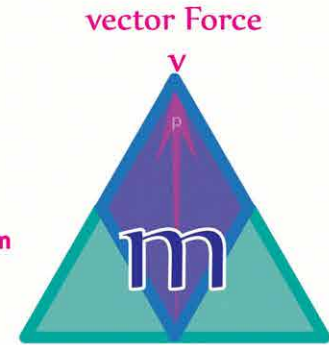
(July 1, 1646 – November 14, 1716)



The founders of calculus thought of the integral as an infinite sum of rectangles of infinitesimal width

Leibniz's vis viva
(Latin for living force)
is mv^2 ,
[2 x kinetic energy]

Much of Newton's work
centred around momentum
and changes to it
[mass. velocity]

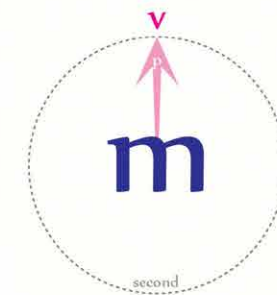


$$F = m[dv/dt]$$

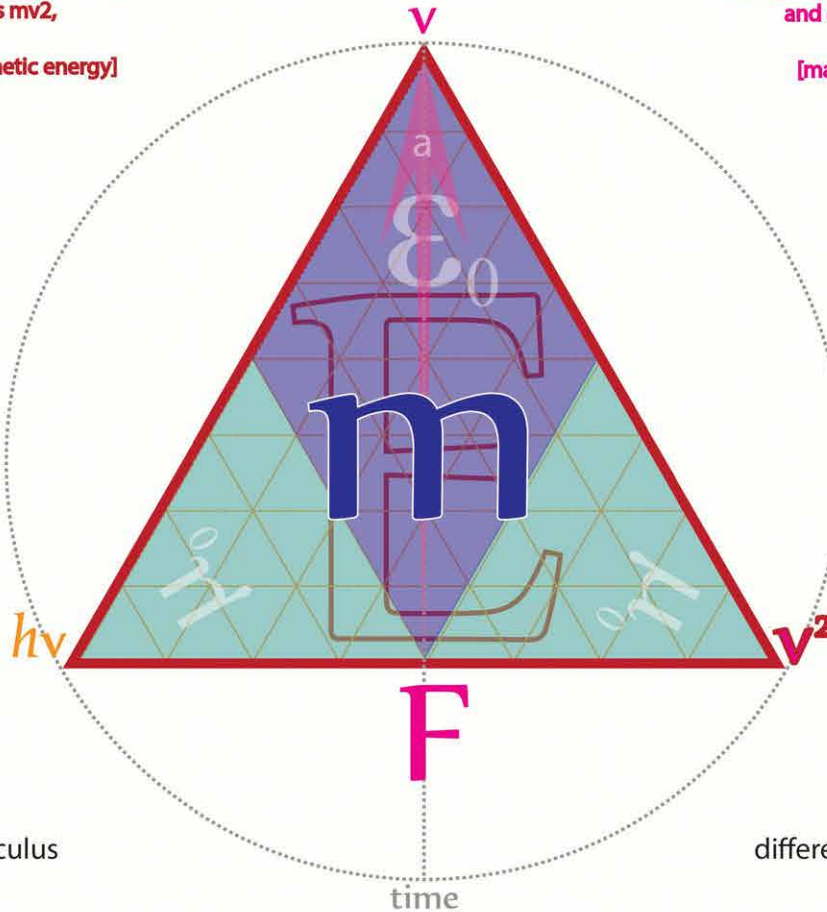
Sir Isaac Newton



(1643-1727)



In calculus, a branch of mathematics, the derivative is a measure of how a function changes as its input changes



integral calculus

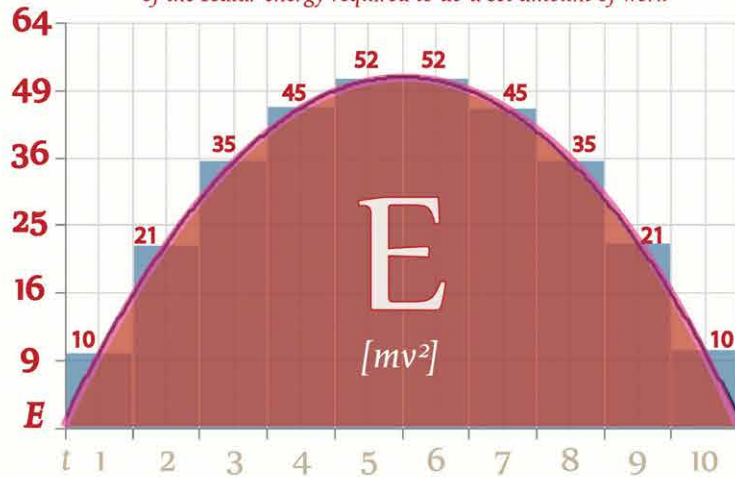
differential calculus

time

The fundamental theorem of calculus is a theorem that links the concept of the integral with the derivative of a function.

Leibniz scalar energies

linear momentum is the square root vector force
of the scalar energy required to do a set amount of work



Energy momentum geometries

$$E = p^2$$

Energy momentum

$$kg \left[\frac{m}{s} \right]^2$$

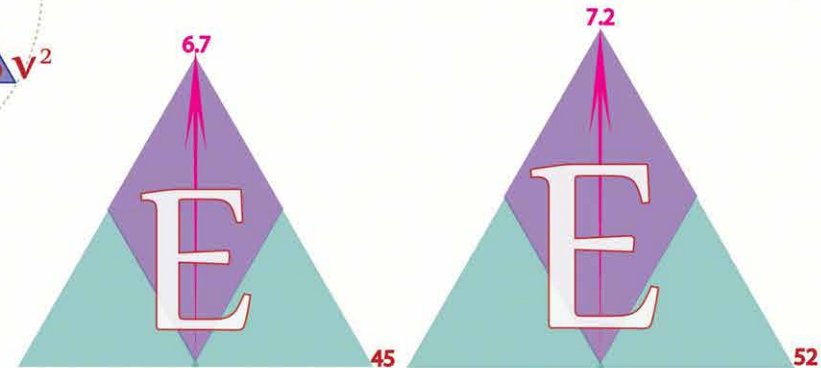
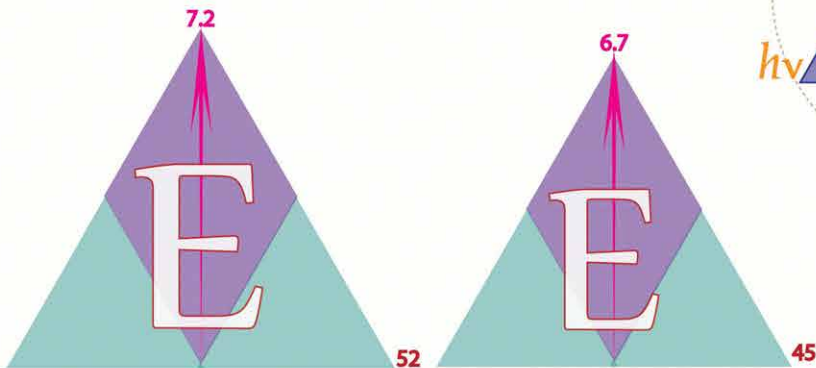
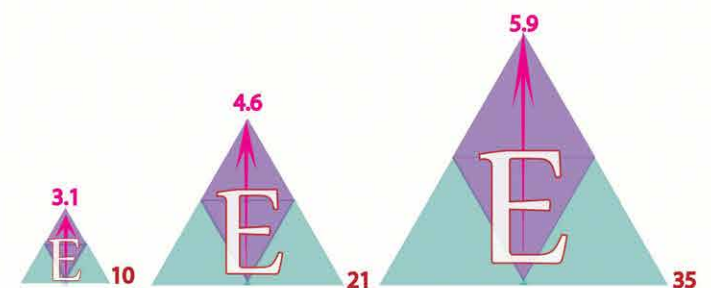
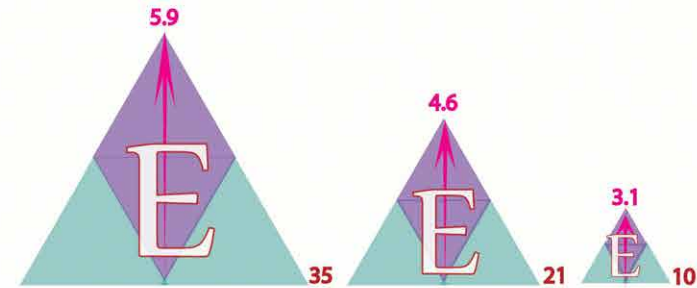
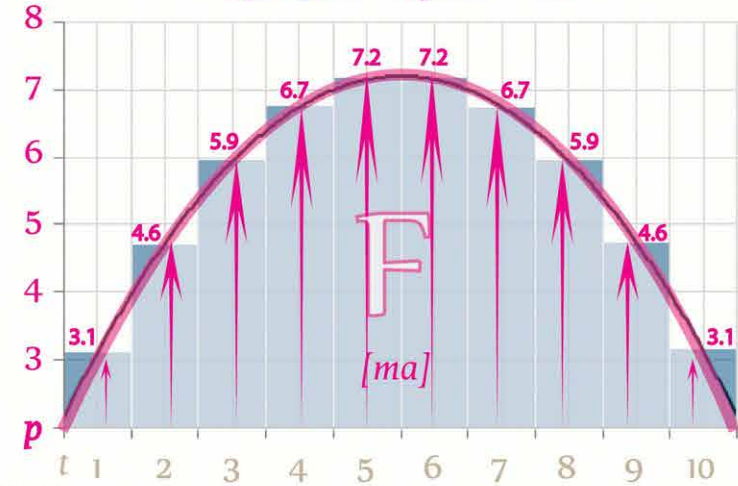
print out this page

then cut out the 10
Planck energy momenta triangles
shown

slice fine lines along the pink linear momentum arrows
with a razor blade or similar as highlighted
under the Newtonian acceleration curve

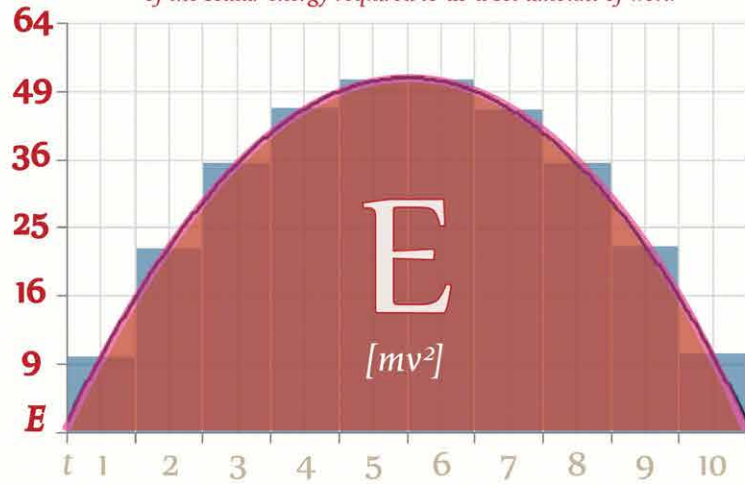
Newton linear momentum

$$d[mv]/dt = dp/dt = ma$$



slide the cut-out triangles
into the slots created
rotate the assembled model
to show the real force momenta
geometry at work

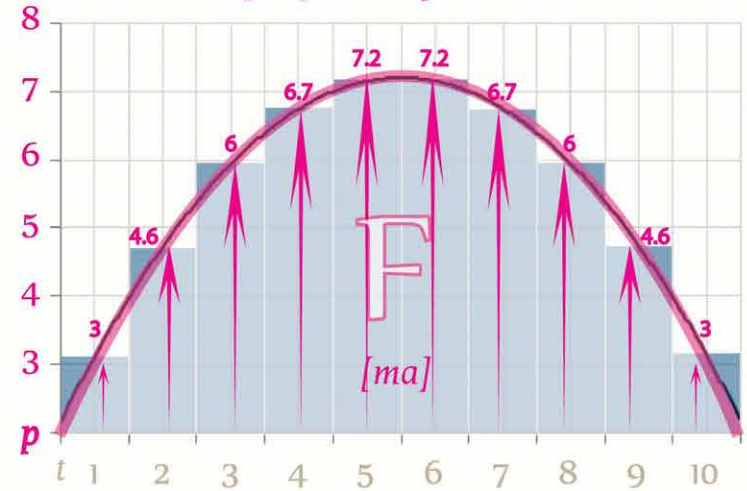
linear momentum is the square root vector force
of the scalar energy required to do a set amount of work



p
linear momentum
 $\text{kg} \frac{\text{m}}{\text{s}}$

print out this page

$$d[mv]/dt = dp/dt = ma$$



Leibniz
scalar energies

$$E = mv^2$$

mass-energy momenta
relationship

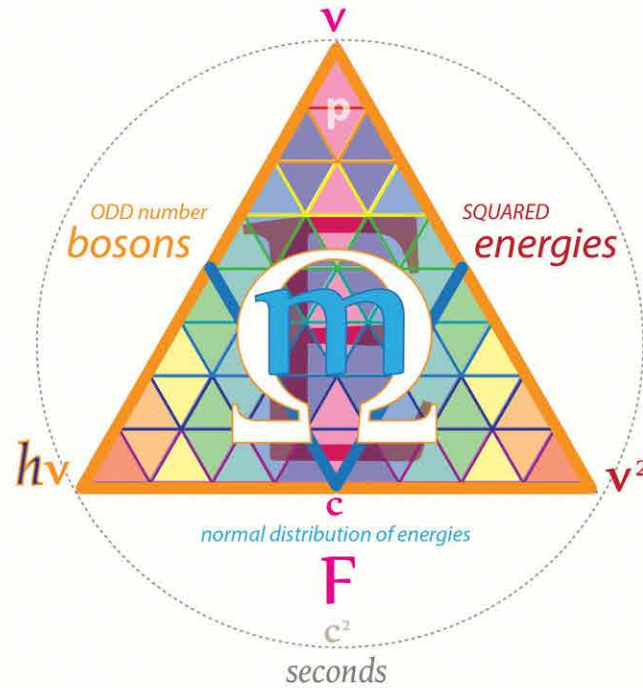
square root equilateral energy
is linear momentum

Newton
linear momentum

$$F = ma$$

mass is a scalar constant relating Force to acceleration

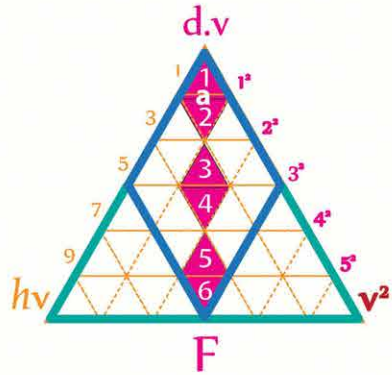
$$F = m \frac{\Delta v}{\Delta t}$$



Planck quanta and their vector linear momentum
lie at 90 degrees to the angle use in the graphs of motion in calculus

Differentiation

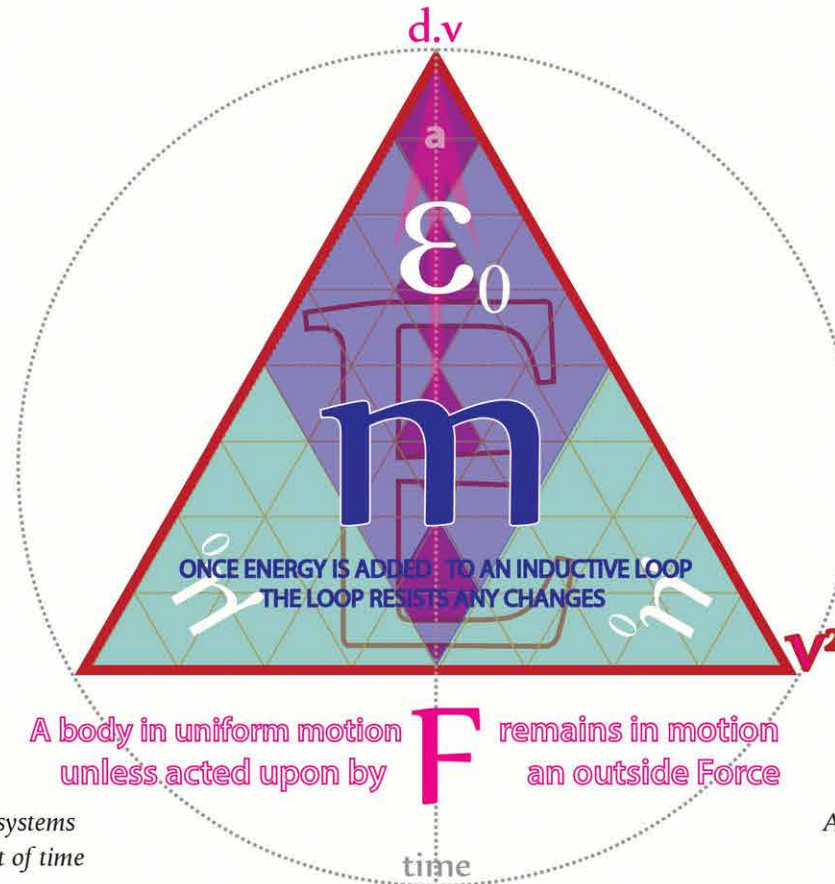
Differentiation is concerned with things like speeds and accelerations, slopes and curves etc. These are Rates of Change, they are things that are defined locally.



An increase in a force opposing an object's vector velocity results in **DECELERATION**

A linear measure of Forces acting on physical systems resulting in changes to distance covered per unit of time

$$v = \frac{\Delta d}{\Delta t} = m/s$$

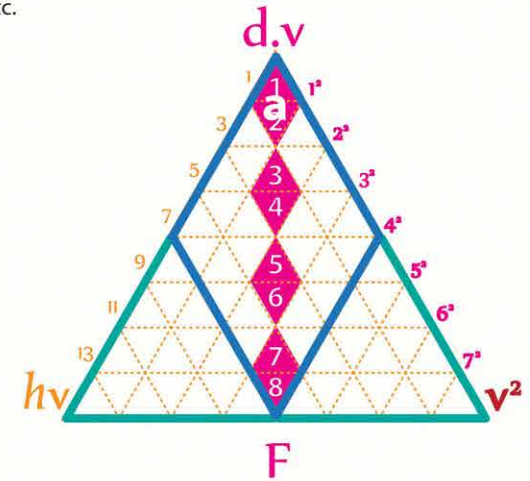


A body in uniform motion **F** remains in motion unless acted upon by an outside Force

In physics, the derivative of the displacement of a moving body with respect to time is the velocity of the body, and the derivative of velocity with respect to time is acceleration.

$$\sum F = \frac{dp}{dt} = m \frac{dv}{dt} + v \frac{dm}{dt}$$

Newton's second law of motion states that the derivative of the momentum of a body equals the force applied to the body.



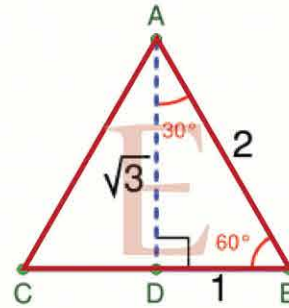
An increase in a force in line with an object's vector velocity results in **ACCELERATION**

A scalar measure of Forces acting on physical systems resulting in changes to their rate of motion

$$a = \frac{\Delta v}{\Delta t} = m/s^2$$

Visualising the geometric half-truths of relativistic physics

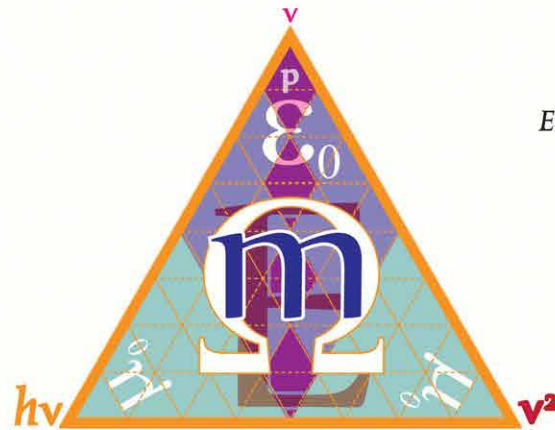
The source of all the physical relationships of mass-energy momenta and the constants in Physics is the Equilateral Triangle (and all texts must be corrected)



Energy geometries within Physics including Special Relativity with its Lorentz corrections have historically been incorrectly illustrated through the geometry of right angled triangles

Physics is geometry, one cannot be separated from the other

Equilateral geometries lead to a intuitive understandings of Physics, Chemistry, Electrodynamics and Gravitation along with all the other aspects of Nature.



F

$$\sum \mathbf{F} = \frac{d\mathbf{P}}{dt} = m \frac{dv}{dt} = m\mathbf{a}$$

$$\mathbf{F} = m\mathbf{a}$$

$$mv^2 = E = hv^2$$

ENERGY

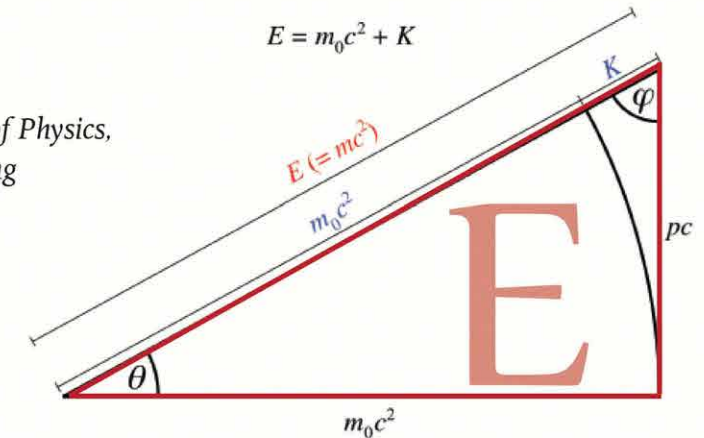
6.629432673 e-34 J

$$\left[\frac{\text{Planck quanta}}{\text{mass velocity}} m \Omega v^2 \right]$$

7.376238634 e-51 kg

momentum

$$p^2 = mv^2$$



$$E = m_0 c^2 + K$$

$$E^2 = p^2 c^2 + m_0^2 c^4$$

Generalizing, we see that the square of the total energy, mass, or distance in spacetime is the sum of the components squared.

We can see an origin of distance in spacetime relating to velocity in pc in which Energy is subject to Lorentz corrections [v/c]

$$E = pc$$

Additionally, EM mass can be directly related tot the Energy content of a body by the velocity of Energy

$$E = mc^2$$

Velocity

In physics, velocity is the measurement of the rate and direction of change in the position of an object.

It is a vector physical quantity; both magnitude and direction are required to define it.

The scalar absolute value (magnitude) of velocity is speed, a quantity that is measured in metres per second (m/s or ms⁻¹) when using the SI (metric) system.

v Velocity $\frac{m}{s}$



is a 2D radial Space-time MEASUREMENT

$$\frac{m}{s}$$

Speed is the scalar value of the Distance traveled per unit of Time

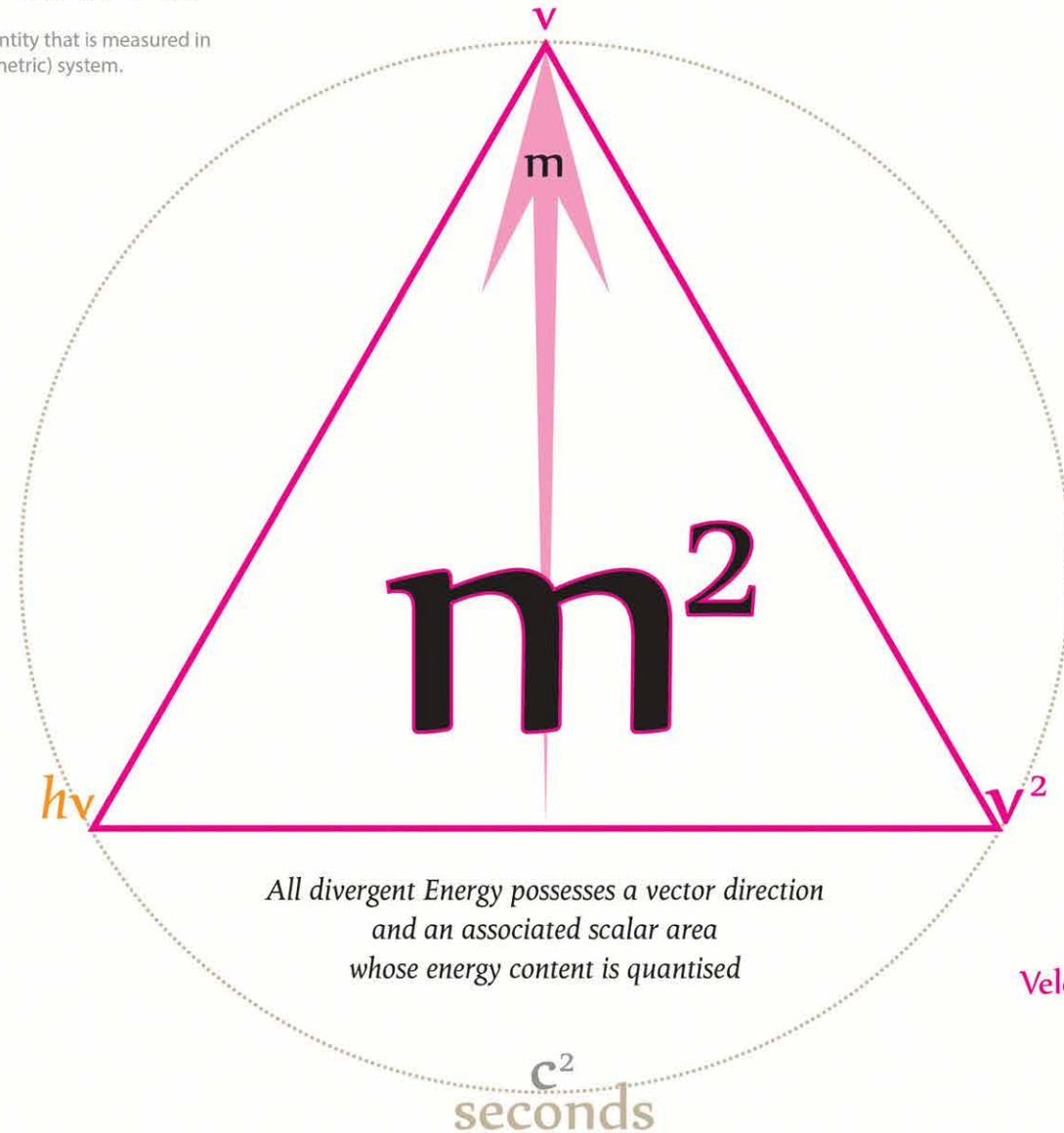
$$\bar{v} = \frac{\Delta x}{\Delta t}$$

Velocity is the vector value of the Distance traveled per unit of Time

$$\vec{\frac{m}{s}}$$

Velocity squared is the scalar value of the Distance traveled per unit of Time squared (Energy of a given spatial volume)

$$\frac{m^2}{s^2}$$



All divergent Energy possesses a vector direction and an associated scalar area whose energy content is quantised

Velocity squared

$$\frac{m^2}{s^2}$$

Acceleration

In physics, acceleration is the rate of change of velocity over time [dt]

In one dimension, acceleration is the rate at which something speeds up or slows down.

However, since velocity is a vector, acceleration describes the rate of change of both the magnitude and the direction of velocity.

Acceleration has the dimensions [Length]/[Time Squared]

In SI units, acceleration is measured in meters per second squared (m/s²).

$$a = \frac{\Delta y}{\Delta x} = \frac{\Delta v}{\Delta t}$$

In classical mechanics, for a body with constant mass, the acceleration of the body is proportional to the net force acting on it (Newton's second law)

$$F=ma \longrightarrow a=F/m$$

$$\text{Force} \quad \text{kg} \frac{\text{m}}{\text{s}^2}$$

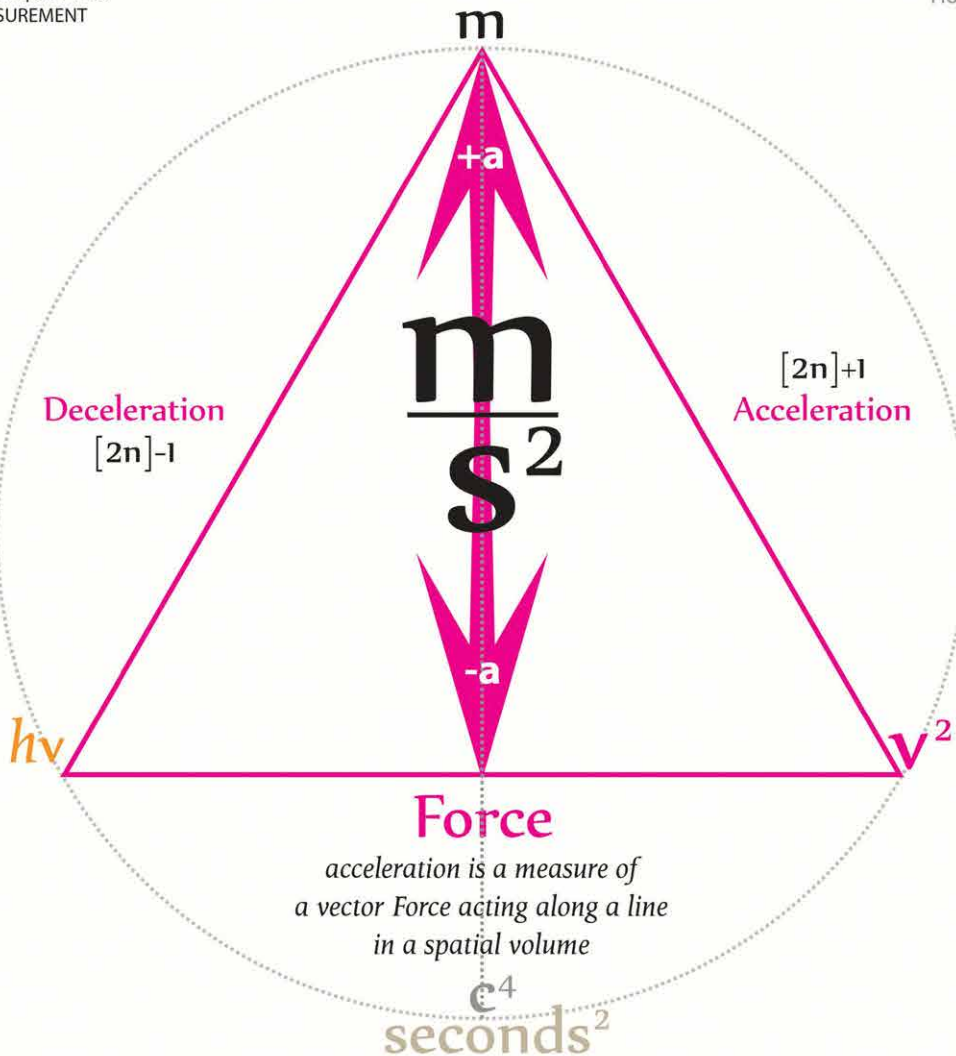
Additionally, for a mass with constant velocity, (ie in an inertial frame) the energy of motion is expressed as its momentum (acceleration causes changes in Energy-momentum)

$$p = \text{kg} \frac{\text{m}}{\text{s}}$$



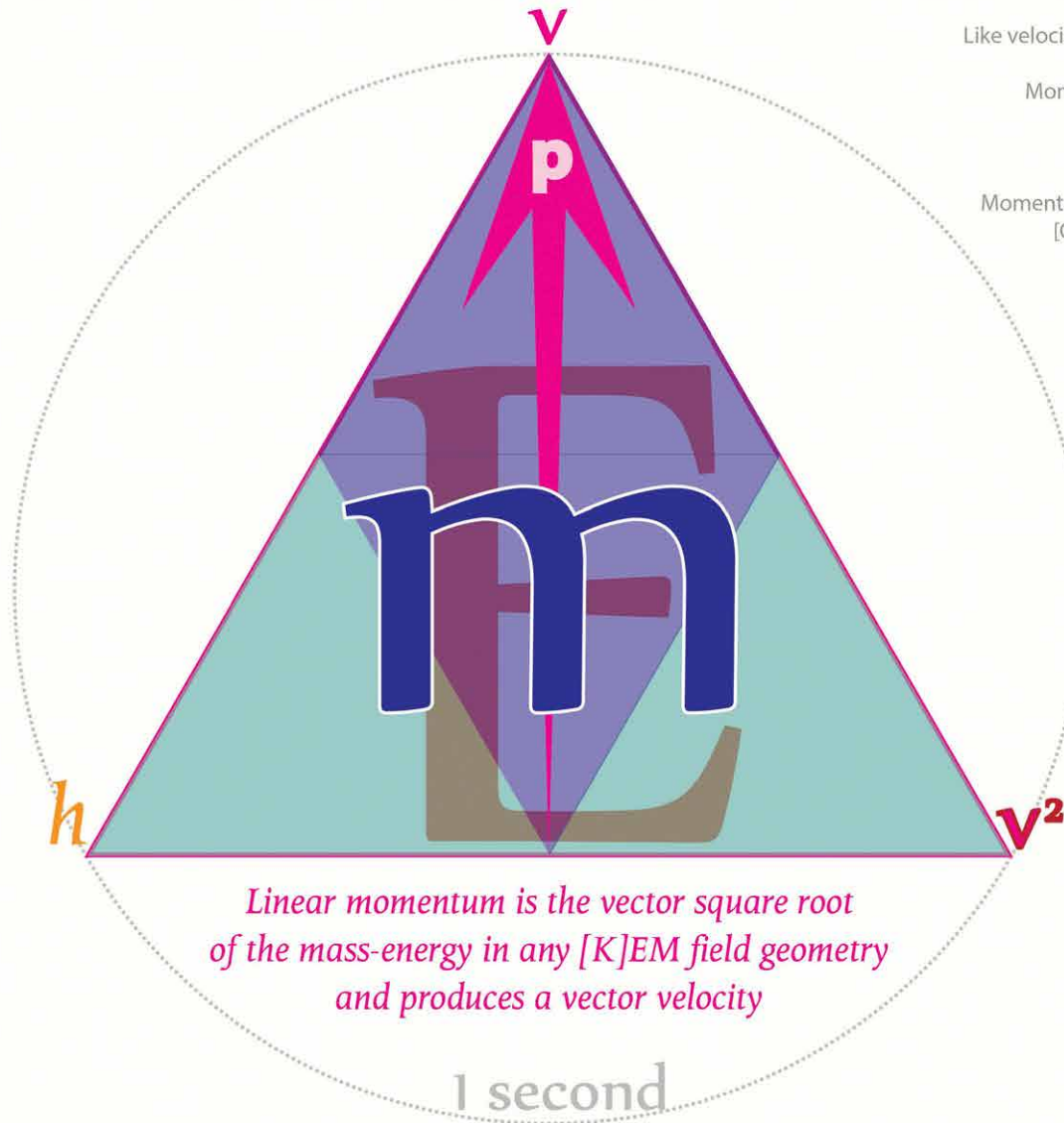
is a 3D
Spherical Space-time
MEASUREMENT

a Acceleration $\frac{\text{m}}{\text{s}^2}$



Momentum

$\text{kg} \frac{\text{m}}{\text{s}}$ linear momentum **p**



In classical mechanics, momentum (pl. momenta; SI unit kg·m/s, or, equivalently, N·s) is the product of the mass and velocity of an object (p).

Like velocity, momentum is a vector quantity, possessing a direction as well as a magnitude.

Momentum is a conserved quantity (law of conservation of linear momentum), meaning that if a closed system is not affected by external forces, its total momentum cannot change.

Momentum should be referred to in its specific forms to distinguish it in its various forms [Quantised Angular, Linear, Rotational and quantum/nuclear momentum]

$$p = \frac{h\nu^2}{v} = mv$$

Although originally expressed in Newton's Second Law, the conservation of momentum also holds in special relativity and, with appropriate definitions, a (generalized) momentum conservation law holds in electrodynamics, quantum mechanics, quantum field theory, and general relativity.

In relativistic mechanics, non-relativistic momentum is further multiplied by the Lorentz factor.

$$p^2 = E = mv^2$$

Energy can be expressed as the square of linear momentum

$$\text{kg} \frac{\text{m}^2}{\text{s}^2}$$

equilateral Planck energy momenta

$$m\Omega v^2$$

Energy-momentum relationship

The total number of equilateral Planck quanta [quantised mass-energy momenta] is directly related to the square of its linear momentum [mass-velocity]

Quantum Mechanics

$$h = \frac{E}{v^2}$$

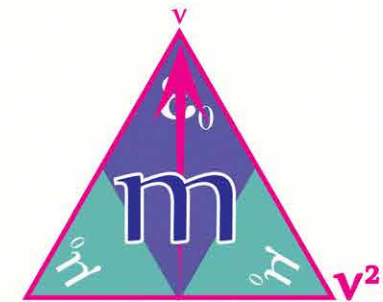


Quantised energy
equilateral momenta

$$hv^2$$

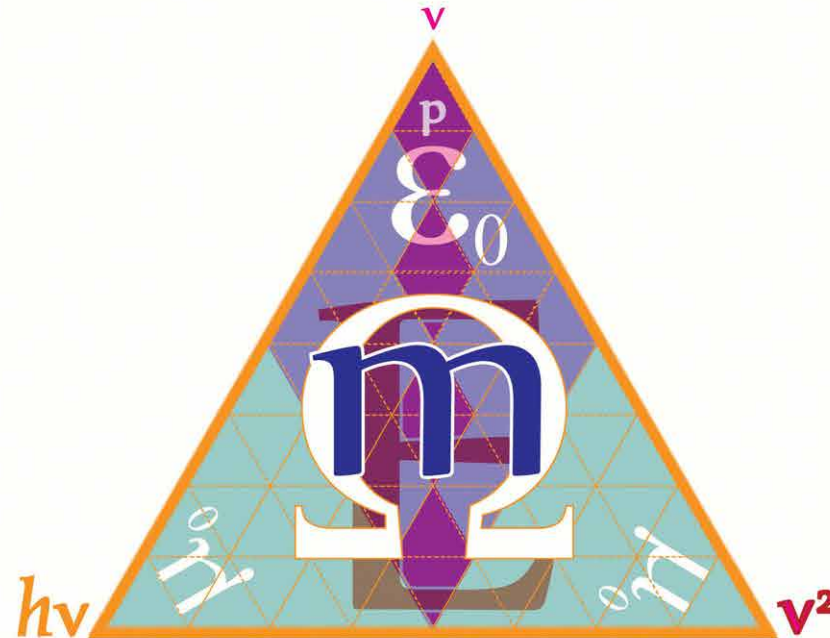
Newtonian physics

$$m = \frac{E}{v^2}$$



Scalar energy
linear momentum

$$pv$$

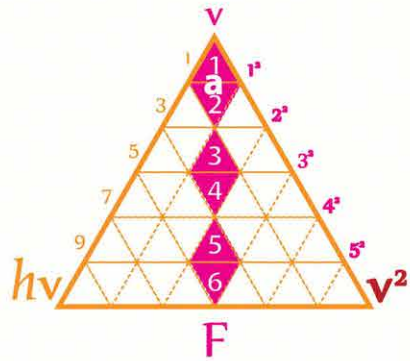


Quantised Energy momenta is related to
Scalar mass energy momenta through
the equilateral geometry of Planck's constant

$$m_{\Omega}v^2 = E = mv^2$$

Inertial resistance to Force

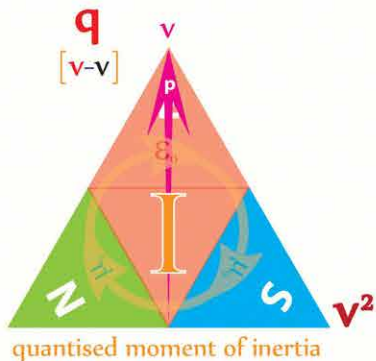
Inertia is the resistance of any physical object to a change in its state of motion.



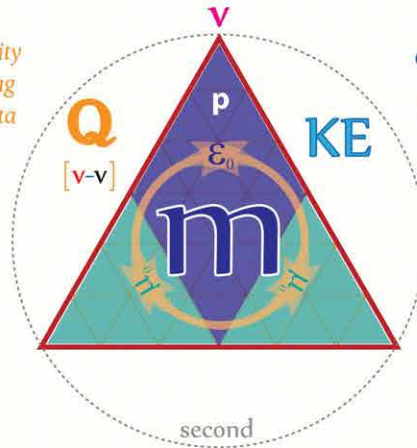
$$E = mc^2$$

The total intrinsic momenta of all energy waveforms is the sum of their constituent Quantised Angular momenta (mass-energy momenta)

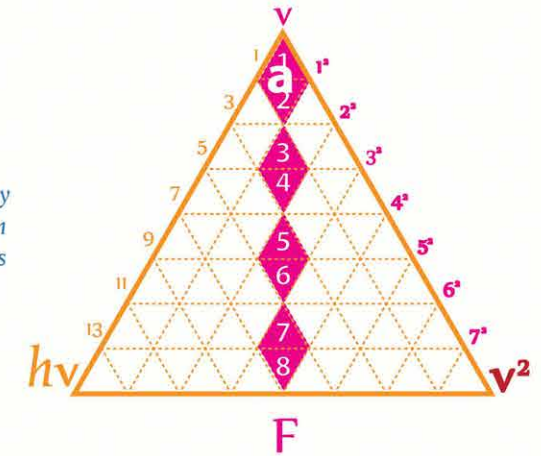
$$M_0 = m/c^2$$



Changes to mass-velocity require a corresponding change to boson quanta



Changes to mass-velocity produces a change in an object's Kinetic Energies



$$KEM = Mv^2$$

Matter in motion has Kinetic Energies in addition to invariant rest mass-Energy

$$KE = RE - \text{rest Matter}$$

Any change in motion results in changes to the Charge geometries creating in turn proportional changes to KEM mass and momenta components

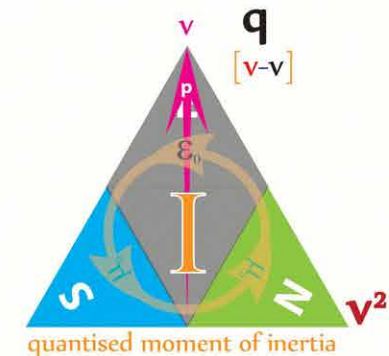
$$F = ma$$

The 'inductive resistance' of Charge quanta fields to changes in their mass-energy momenta content is what we term Inertia

Any change to an object's velocity results in a corresponding change to its mass-Energy momenta which is reflected by its inertia

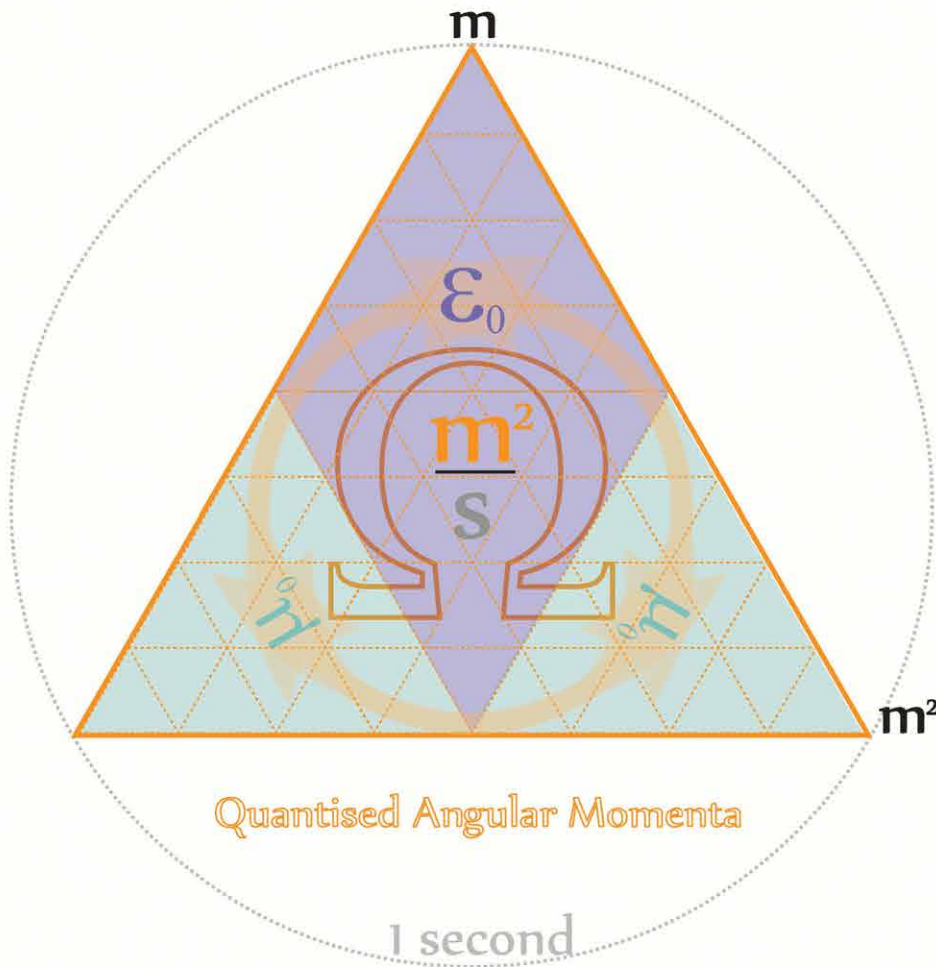
$$p^2 = E = mv^2$$

Inertial mass can be related to Charge through inductive Planck quanta



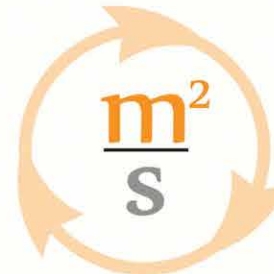
Quantised Angular momentum

As it is a physical [equilateral] geometry QAM is conservative in any system where there are no external Forces and serves as the foundational geometric source for all the conservation laws of physics



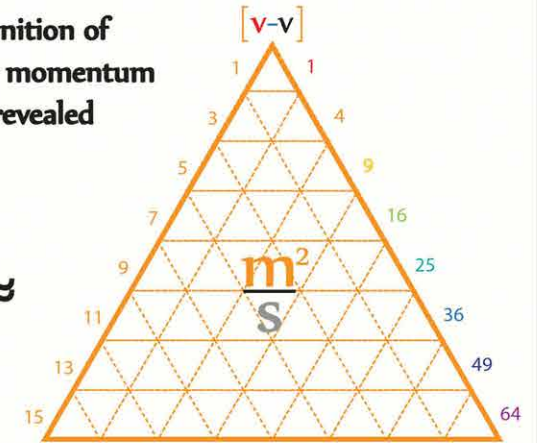
Angular momentum is sometimes described as the rotational analog of linear momentum, in Tetryonics it is revealed to be the equilateral geometry of quantised mass-energy momenta within any defined space-time co-ordinate system

A major re-definition of quantised angular momentum in physics is revealed



classical rotational angular momentum

≈



Quantised Angular momentum

In quantum mechanics, angular momentum is quantised – that is, it cannot vary continuously, but only in ODD number "quantum steps" between the allowed SQUARE nuclear Energy levels

In physics, angular momentum, moment of momentum, or rotational momentum is a conserved vector quantity that can be used to describe the overall state of a physical system.

When applied to specific mass-Energy-Matter systems QAM reveals the true quantum geometry and nature of Energy in our universe

$$h \text{ kg } \frac{m^2}{s}$$



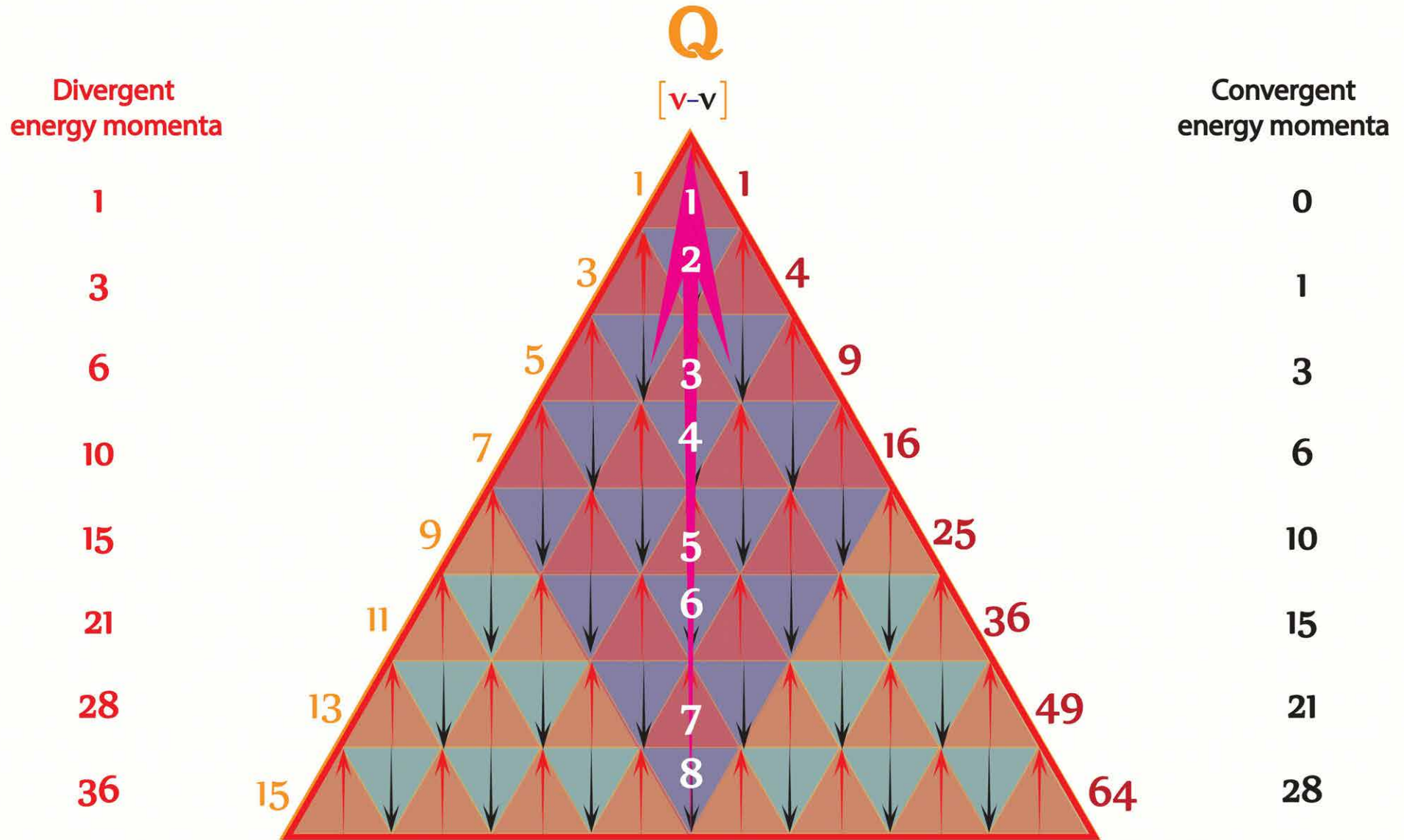
Planck's Constant

$$m \Omega \text{ mass x QAM}$$

Normally viewed as an expression of rotational momentum Quantised Angular Momentum [QAM] is in fact a result of the equilateral geometric quantization of mass-energy

Charged geometries

All charge geometries are nett divergent



All charge geometries are comprised of finite equilateral energy momenta quanta

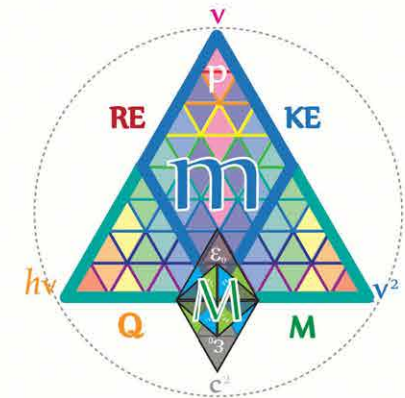
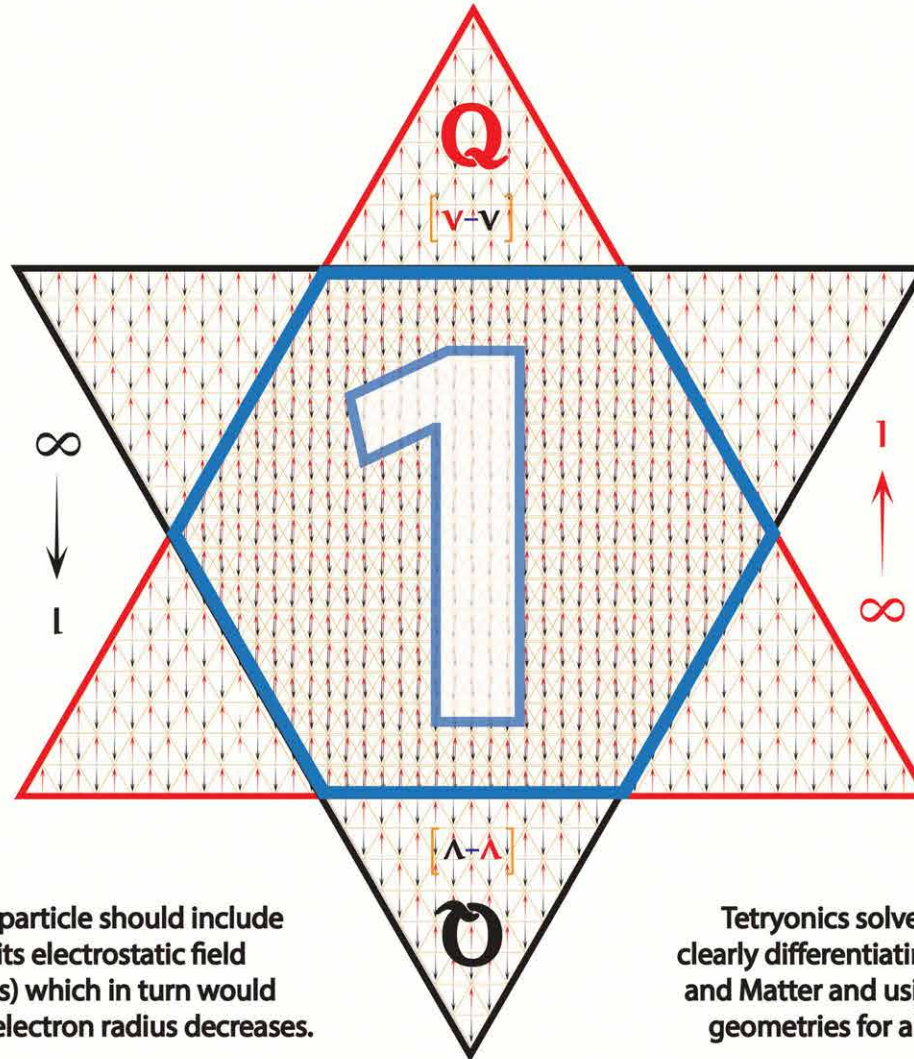
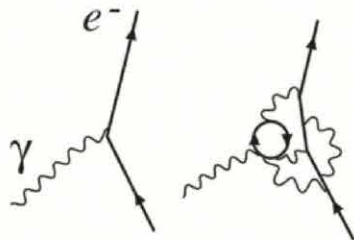
Renormalisation



Renormalization was first developed in quantum electrodynamics (QED) to make sense of infinite integrals in perturbation theory. The problem of infinities first arose in the classical electrodynamics of point particles in the 19th and later in the calculation of Gravitational fields in General Relativity in the early 20th century.

**In QED
Infinities must
be cancelled**

**In Tetryonics
Infinities do not
exist**



The mass of a charged particle should include the mass-energy in its electrostatic field (Electromagnetic mass) which in turn would approach infinity as the electron radius decreases.

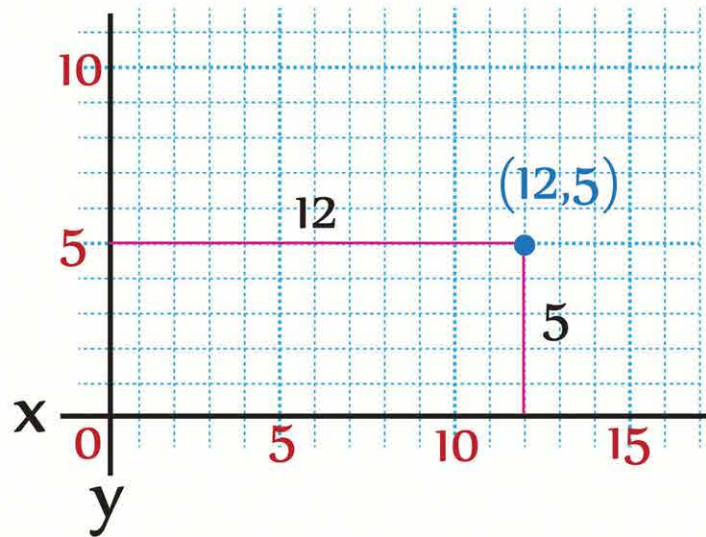
Tetryonics solves the problem by clearly differentiating between EM mass and Matter and using finite equilateral geometries for all Matter in motion

Initially viewed as a suspicious provisional procedure by some of its originators, renormalization was eventually embraced as an important and self-consistent tool in several fields of physics and mathematics.

2D space [c^2]

The adjective Cartesian refers to the French mathematician and philosopher René Descartes who developed the coordinate system in 1637

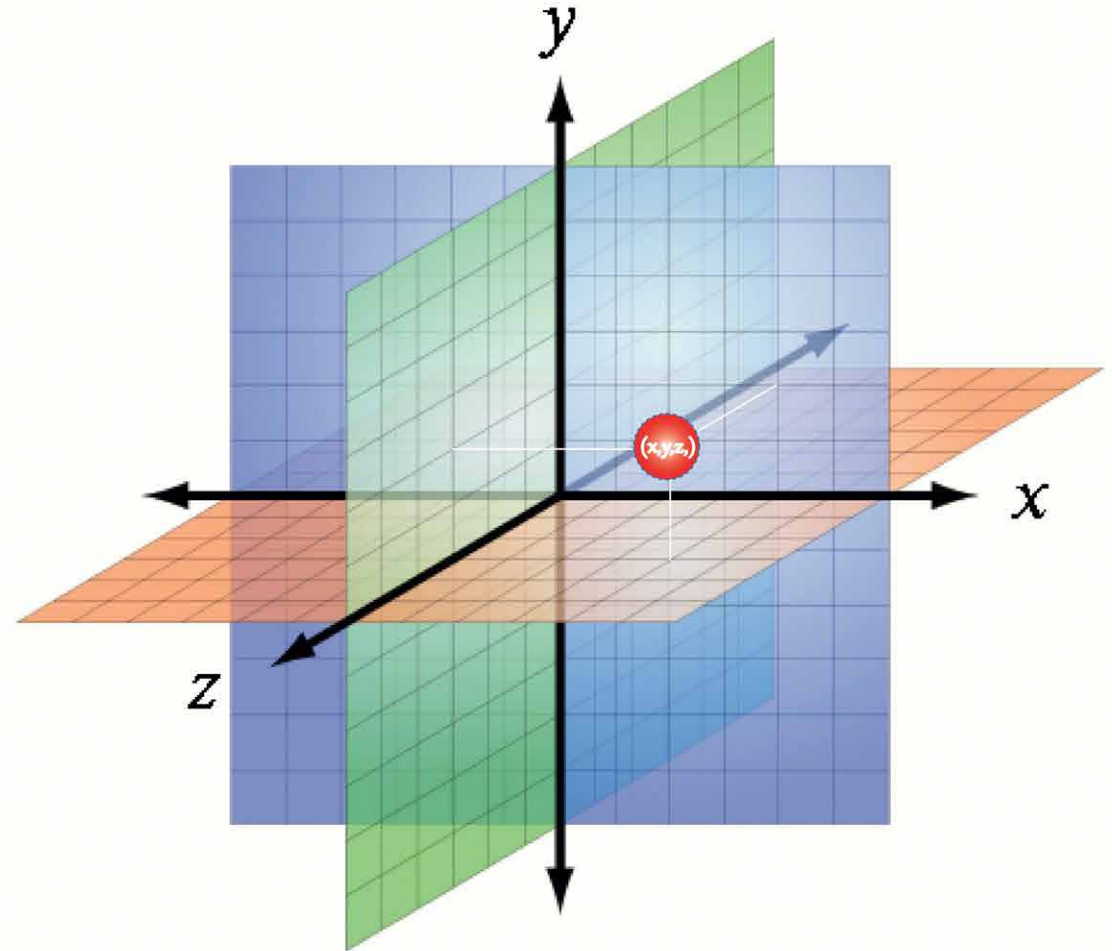
Since then many other coordinate systems have been developed such as the polar coordinates for the plane, and the spherical and cylindrical coordinates for three-dimensional space.



Cartesian coordinates are the foundation of analytic geometry, and provide enlightening geometric interpretations for many other branches of mathematics, such as linear algebra, complex analysis, differential geometry, multivariate calculus, group theory, and more

Mapping 3D spaces using Recti-linear co-ordinates

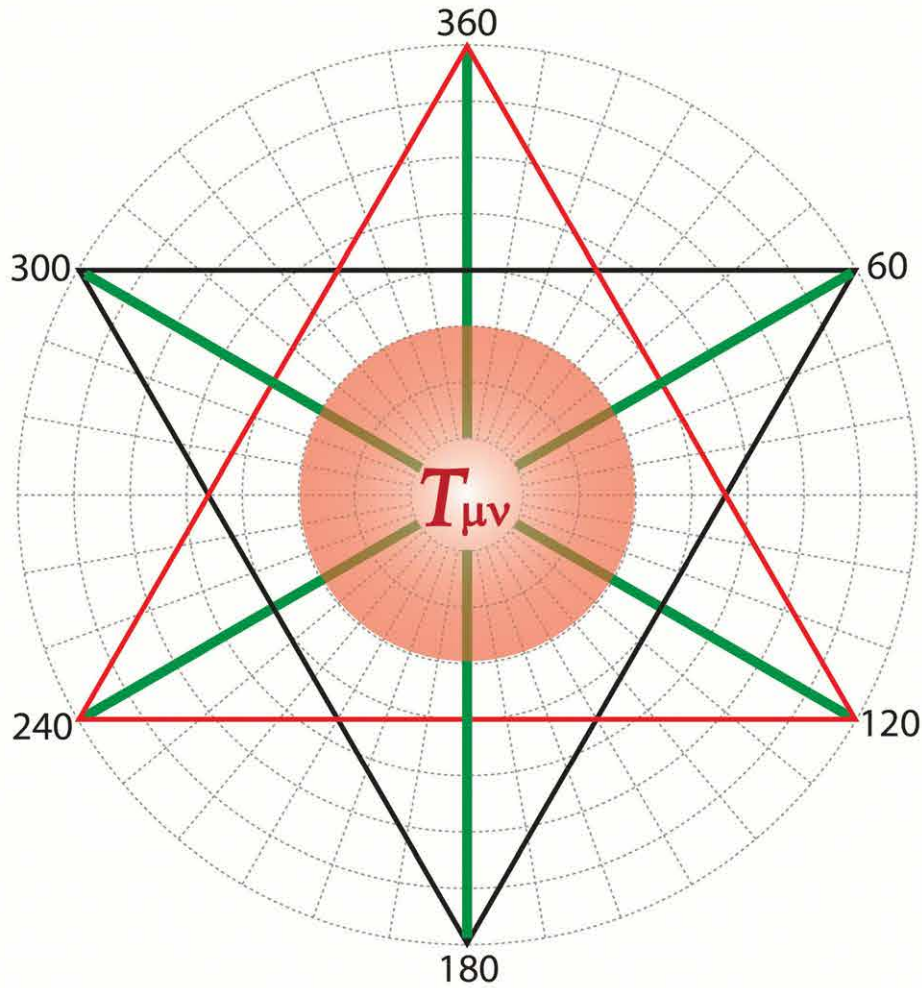
Cartesian coordinates can be defined as the positions of the perpendicular projections of a point onto the two or more axes, expressed as signed distances from the origin.



3D Cartesian co-ordinate [c^3] systems are distinct from spherical co-ordinate [c^4] systems

Polar co-ordinates

In mathematics, the polar coordinate system is a two-dimensional co-ordinate system in which each point on a plane is determined by a distance from a fixed point and an angle from a fixed direction.

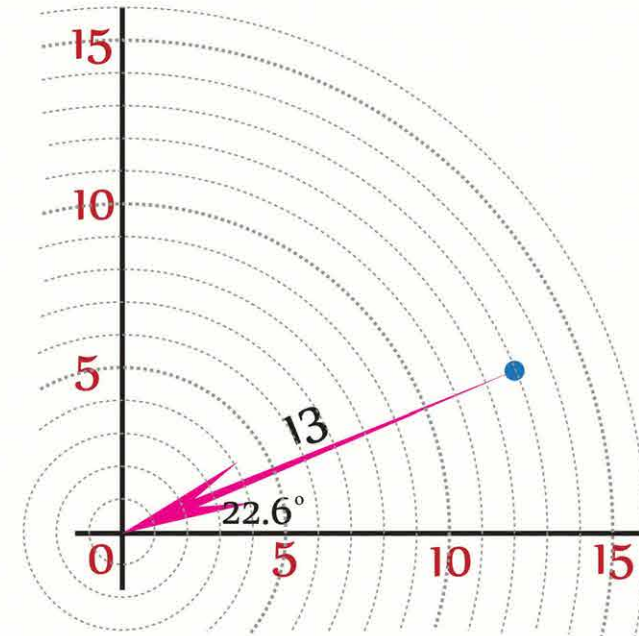


In geometry, curvilinear coordinates are a coordinate system for Euclidean space in which the co-ordinate lines may be curved.

Action Dynamics

Curvilinear co-ordinates may be derived from a set of rectilinear Cartesian coordinates by using a locally invertible transformation that maps one point to another in both systems

Metric Tensors



Gravitational acceleration

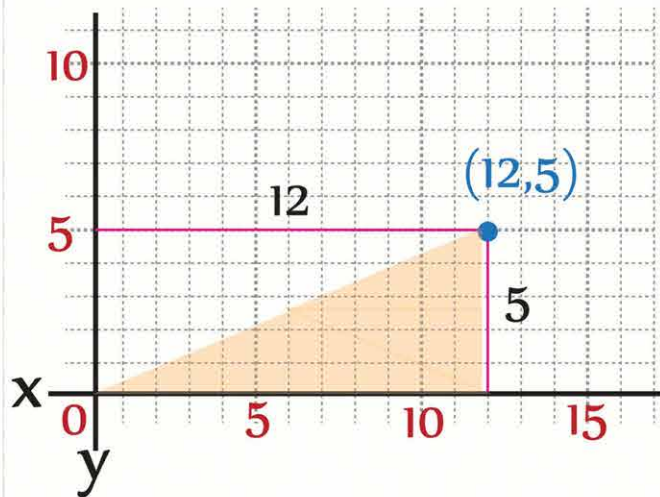
Polar or curvilinear co-ordinate systems are used extensively by Einstein in his theory of General Relativity

Reimannian curved space-time

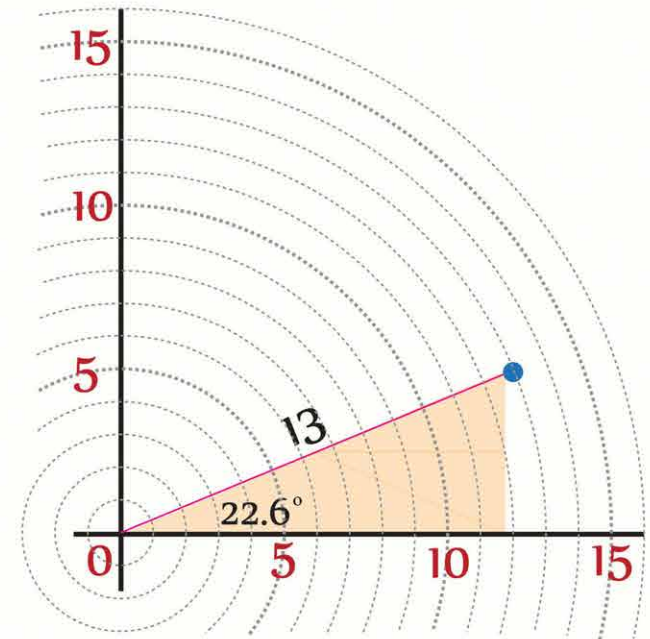
Co-ordinate transformations

There are many different possible coordinate systems for describing geometrical figures and they can all be related to one another.

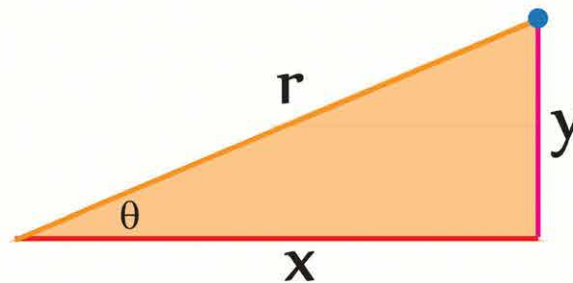
Such relations are described by coordinate transformations which give formulas for the coordinates in one system in terms of the coordinates in another system



Converting between
Polar and Cartesian
coordinates



$$\begin{aligned}\tan \theta &= \frac{\text{opposite}}{\text{adjacent}} \\ &= \tan^{-1}(5/12) \\ &= 22.619\end{aligned}$$



$$\begin{aligned}r^2 &= 12^2 + 5^2 \\ &= \sqrt{169} \\ &= 13\end{aligned}$$

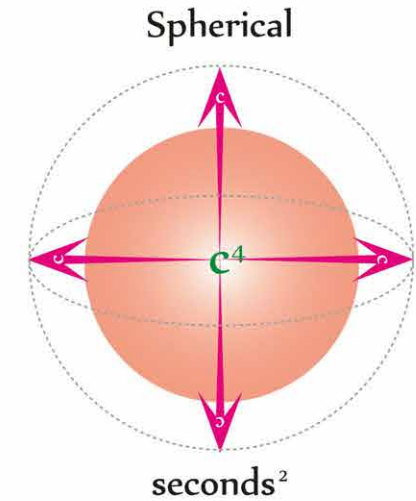
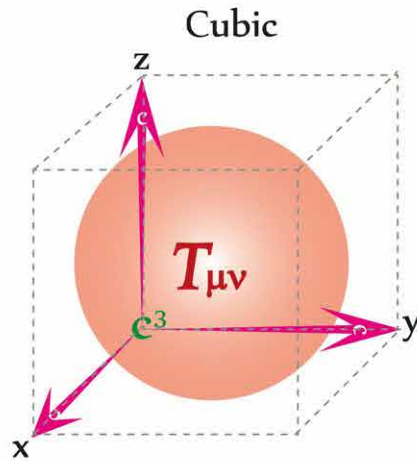
solving for the triangle
using trigometric functions

Spatial co-ordinate systems

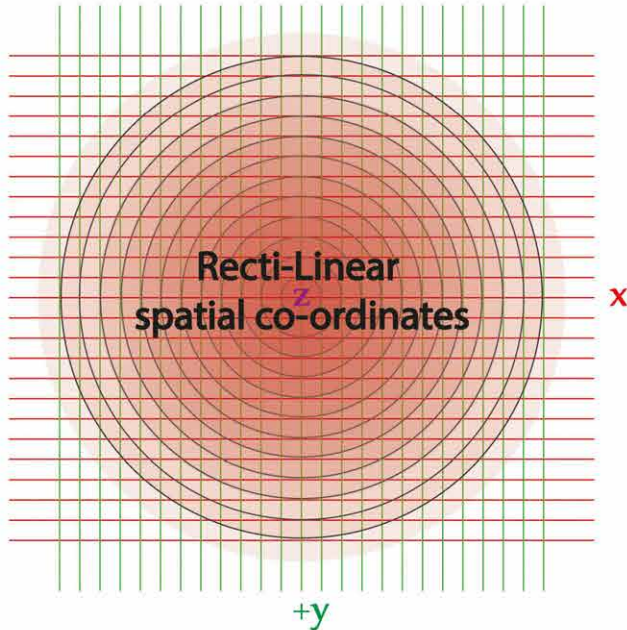
Spacetime is any mathematical co-ordinate system or model that combines space and time into a single continuum.

Spacetime is usually interpreted with space as being three-dimensional with time playing the role of a fourth dimension that is different from the spatial dimensions.

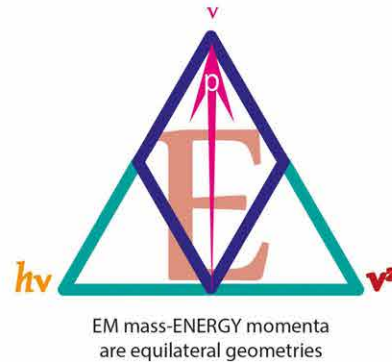
From a Euclidean space perspective, the universe has three spatial dimensions and one dimension of time [reflected by quantised angular momentum].



Cartesian Space-Time

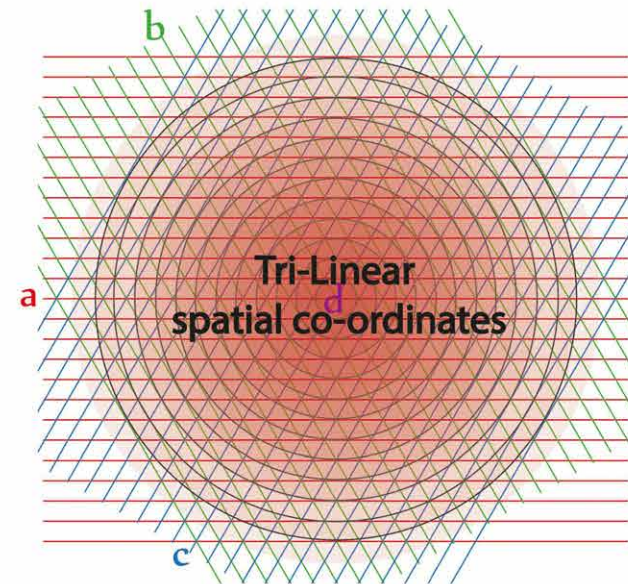


Tetryonics maps spatial co-ordinates through the momenta vectors of equilateral Energy



Mapping equilateral Energy geometries onto recti or curvi-linear spatial co-ordinate systems introduces mathematical complexity to a otherwise simplistic geometry for all EM mass-Energy-Matter interactions

Tetryonic Space-Time



In physics spatial co-ordinates to date have been based on Cartesian co-ordinates when in fact Energy momenta follow a Tri-Linear co-ordinate geometry

vectors



1 Dimensional
velocity

Euclidean



2 Dimensions
velocity squared

$$m = \frac{E}{c^2}$$

mass-energy equivalence

mass-Matter

$$\frac{m}{c^2} = M$$

equivalence

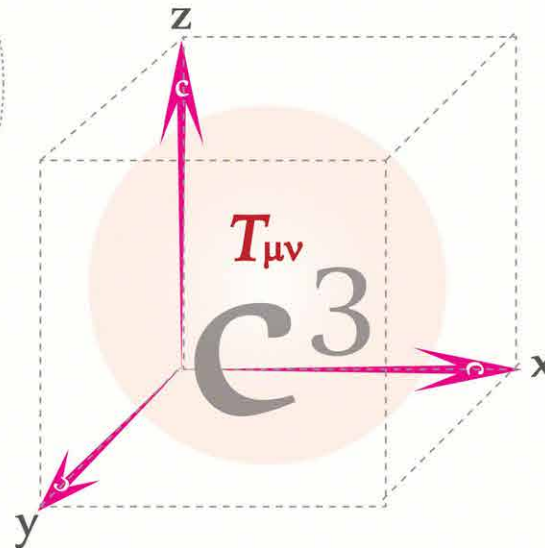
$T_{\mu\nu}$

energy-Matter equivalence

$$M = \frac{E}{c^4}$$

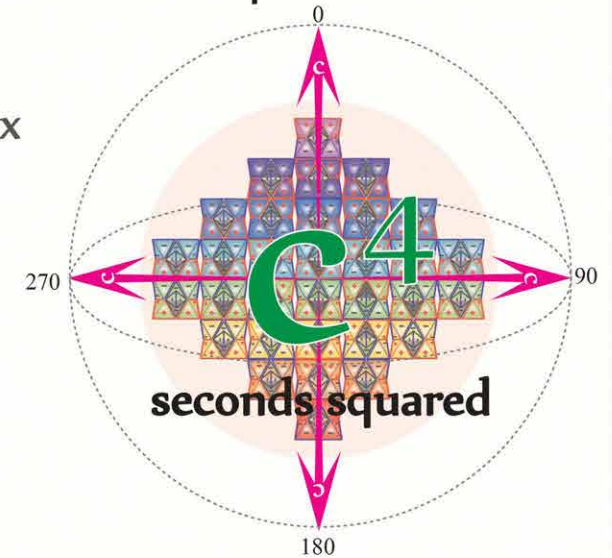
*GR fails differentiate between
EM mass-ENERGY-Matter
unlike Tetryonic theory*

Cartesian co-ordinates



3 Dimensions
velocity cubed

Spherical



3 Dimensions
quadrature velocity

Space-time co-ordinates

*The propagation of Energy momenta forms
distinct spatial co-ordinate systems*

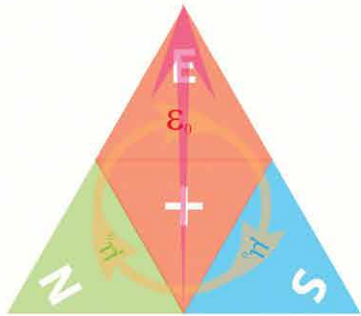
Where angles are typically measured in degrees (°)
or radians (rad), where $360^\circ = 2\pi \text{ rad} = \tau \text{ radians}$.

Energy per second

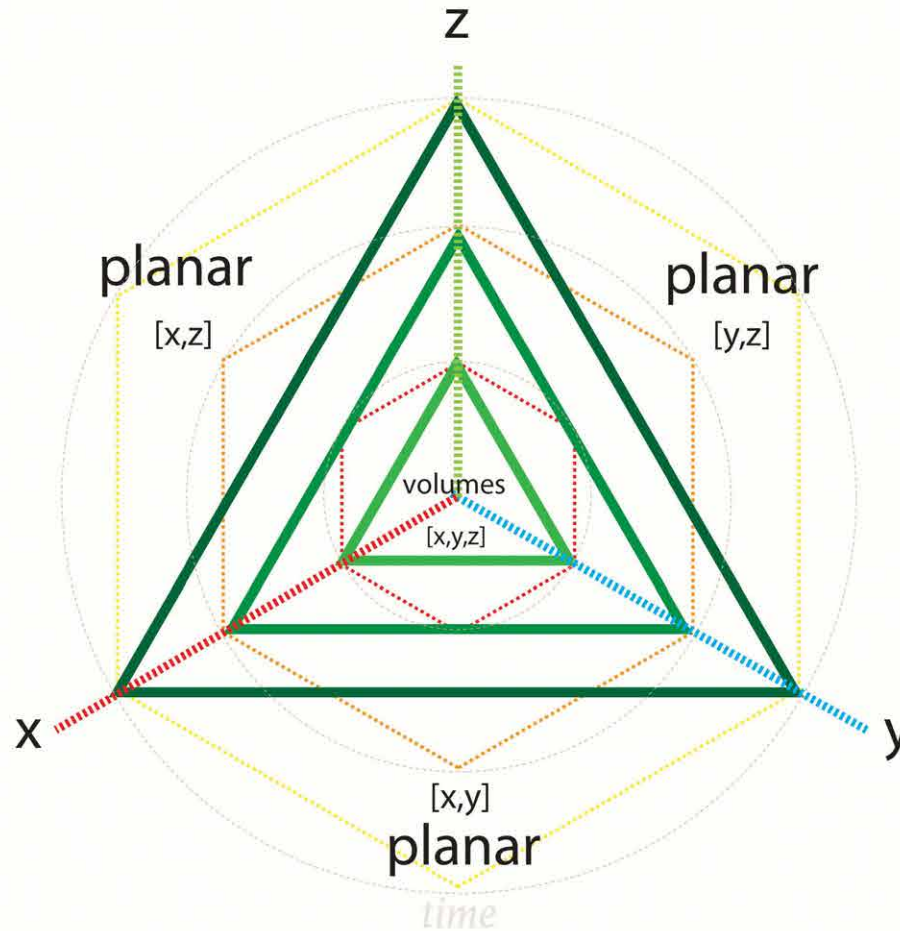
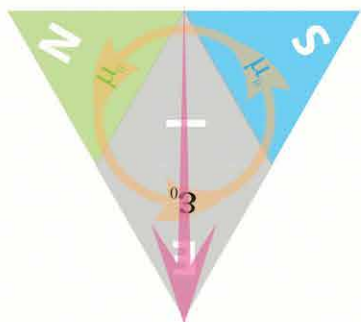
Tetryonic co-ordinate systems

Energy per second squared

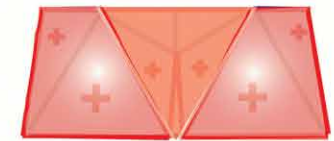
m



2D mass-energy geometries



M



Proton

3D Matter topologies

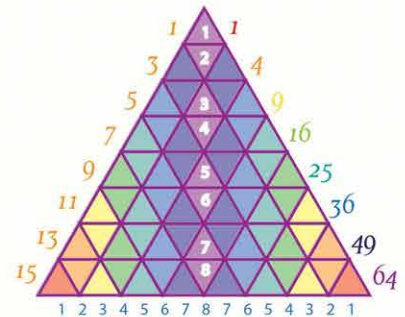
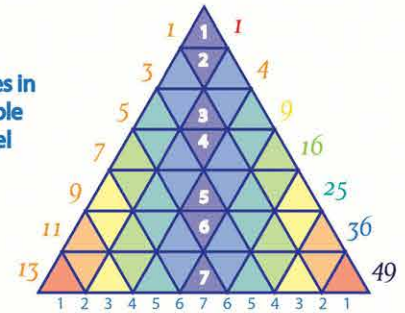
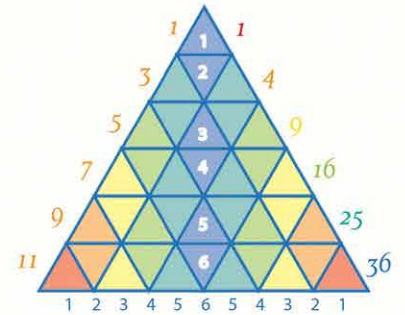
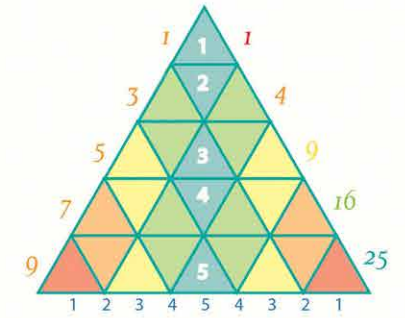
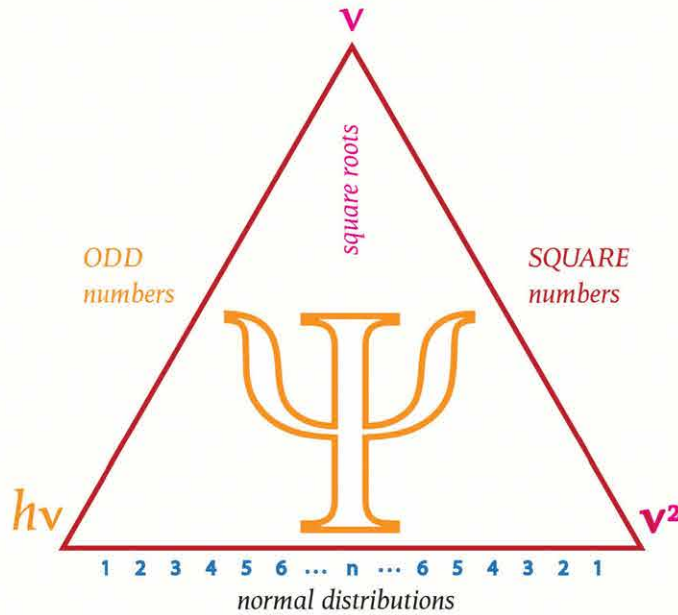
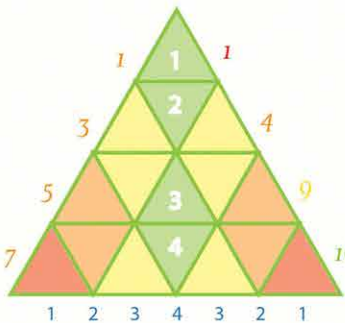
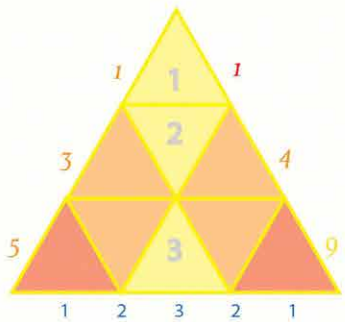
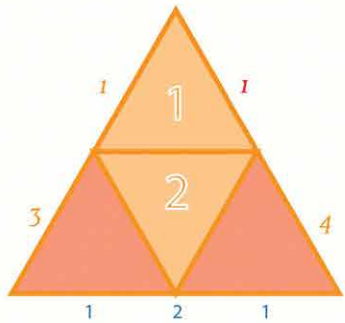
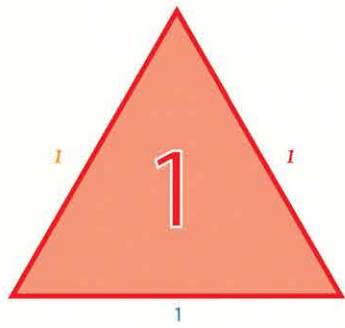
Neutron



Planar mass-energy geometries have no z-components

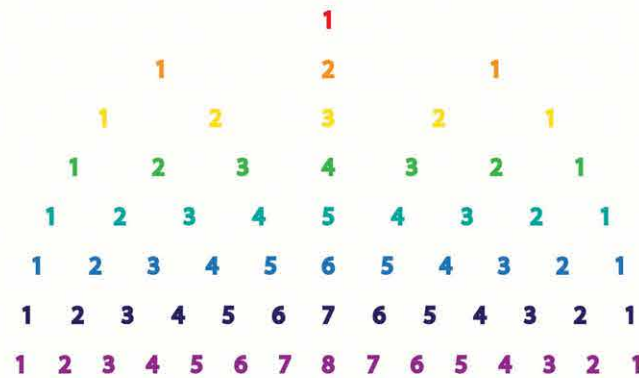
Differentiation between 2D mass-energy & 3D Matter is key to extending our understanding of physics

Matter topologies have z-components



Quantum probability distributions

The equilateral geometry and distribution of quantised Energy momenta provides the basis for all statistical probabilities in Quantum mechanics, thermodynamic & information entropy - including a solution to Heisenberg's Uncertainty Principle thus paving the way forward for a new understanding, and manipulation of physical phenomena at the quantum level



Normal distributions are extremely important in statistics, and are often used in the natural and social sciences for real-valued random variables whose distributions are not known

Quantum Probability Distributions

The normal distribution is a probability distribution.
It is also called Gaussian distribution because it was discovered by Carl Friedrich Gauss.

$$x/n^2$$

Probabilities are the square of the Amplitude

$$n$$

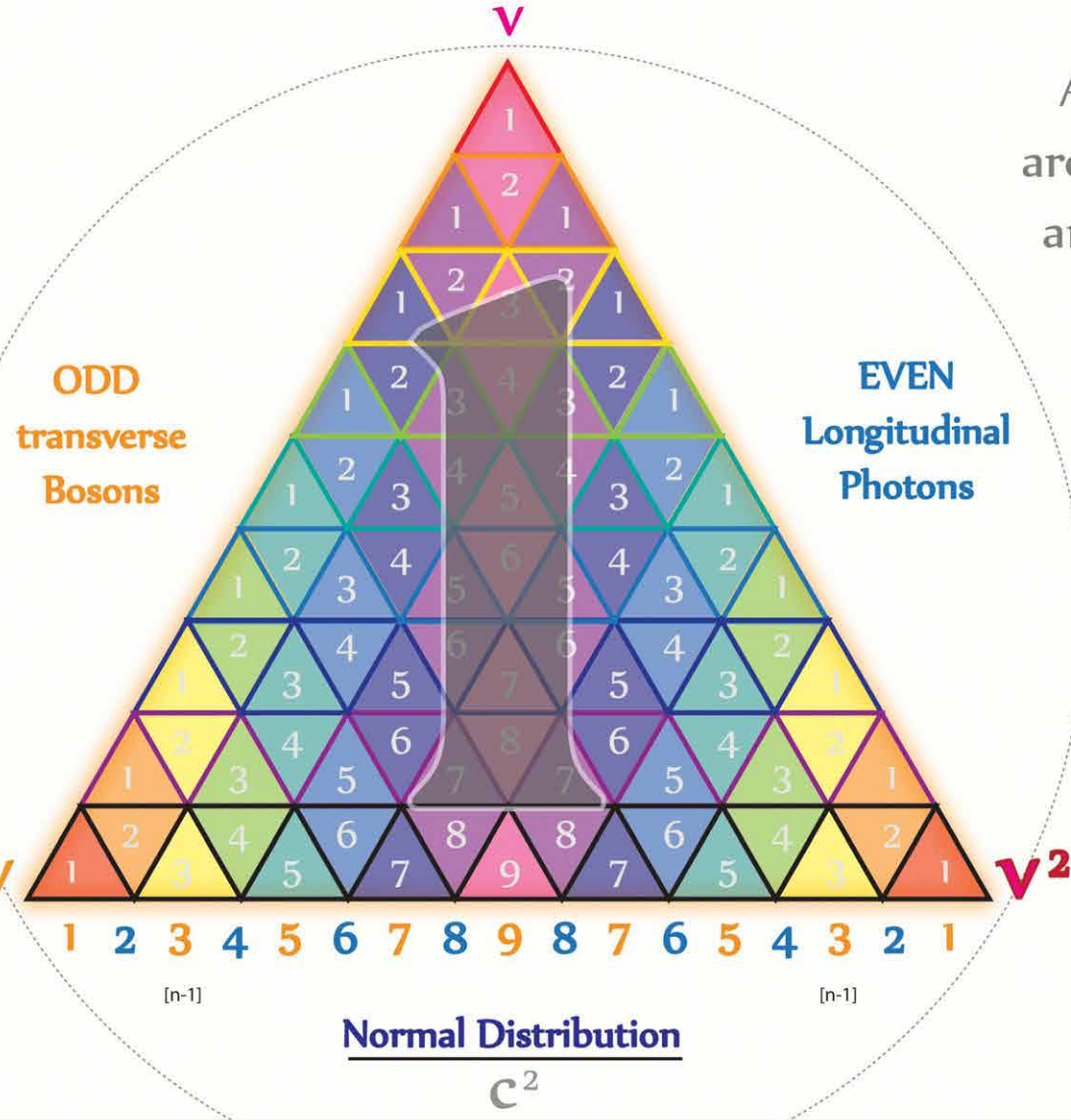
square root momenta

$$v$$

$$\sum x/n^2$$

All probabilities are re-normalisable and sum to Unity

$$1$$



Planck quanta

$$hv$$

$$v^2$$

Square energies

Normal Distribution

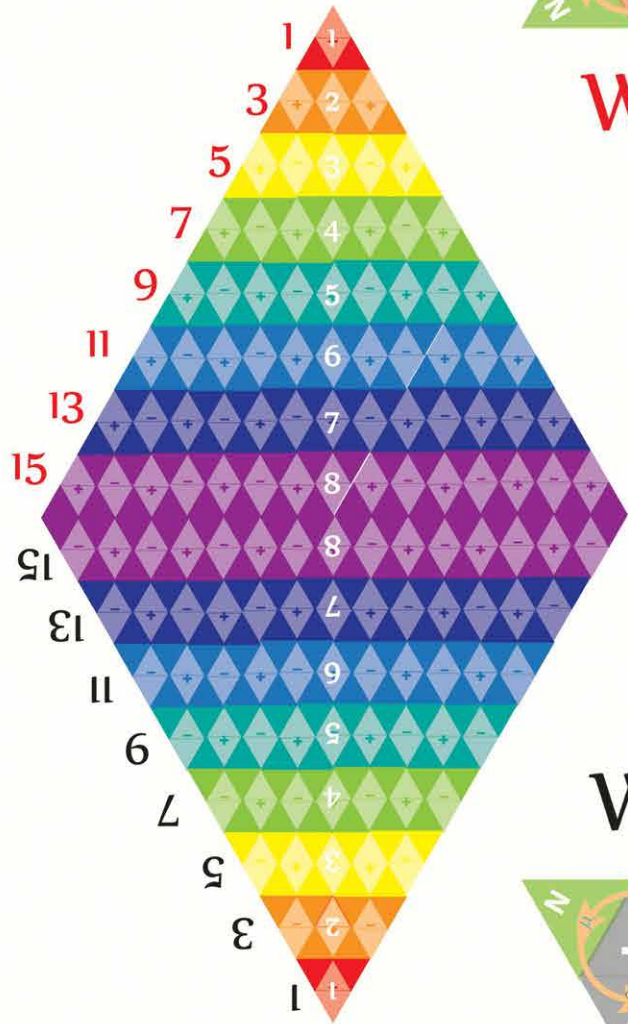
$$c^2$$

Quanta Distributions

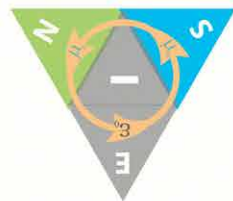
$$2h\nu = E = hf$$

Quantum Levels

transverse bosons



W+

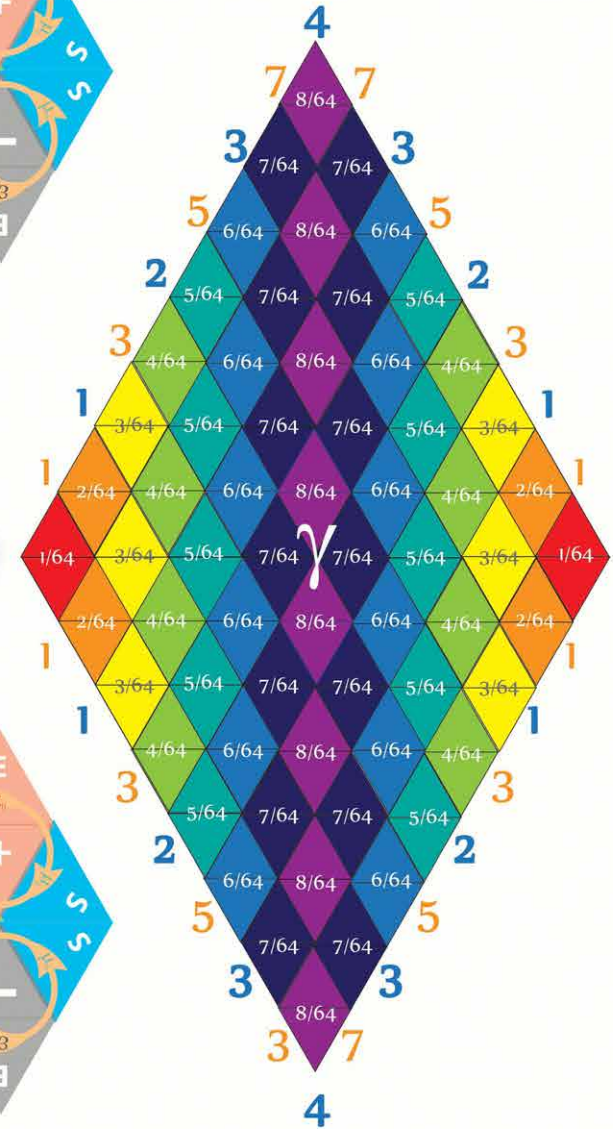


W-

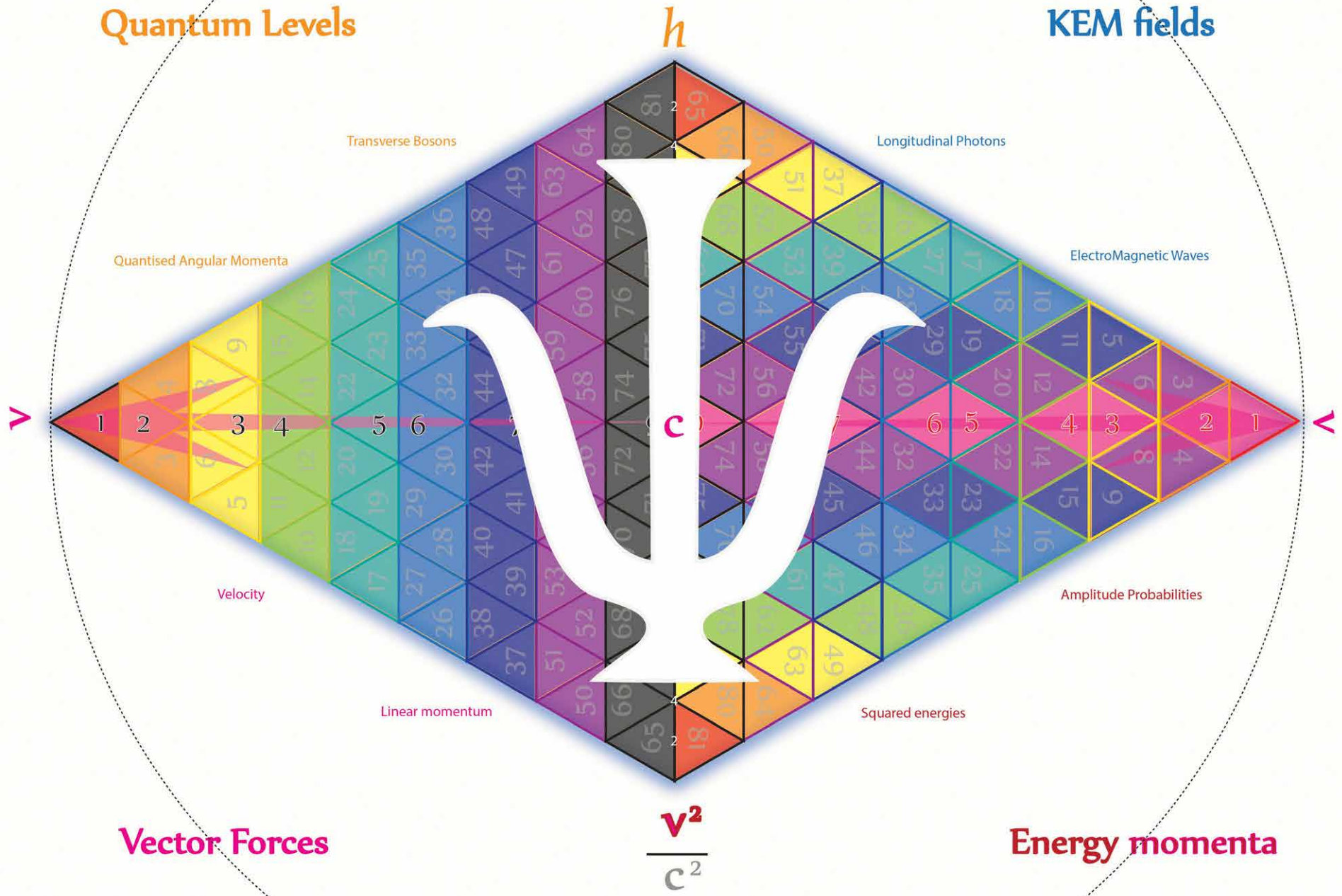


Quantum Probabilities

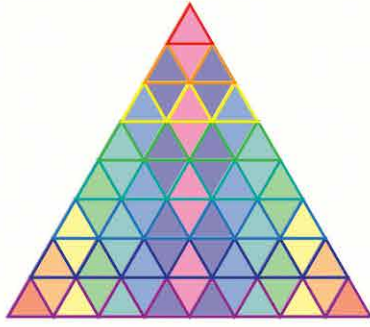
longitudinal photons



Wavefunctions



EM waveforms



All EM waveforms can be measured by either their Transverse EM masses [Bosons] or their Longitudinal EM masses [Photons]

BOSONS

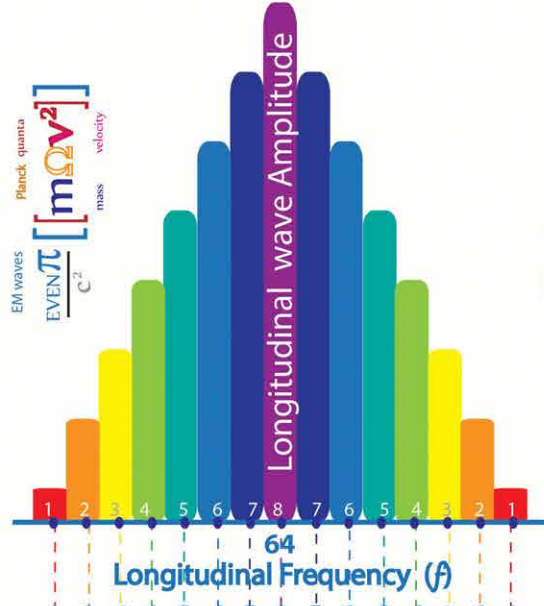
$$\frac{\text{Bosons}}{c^2} \left[\frac{\text{Planck quanta}}{m \Omega v^2} \right]$$

mass velocity



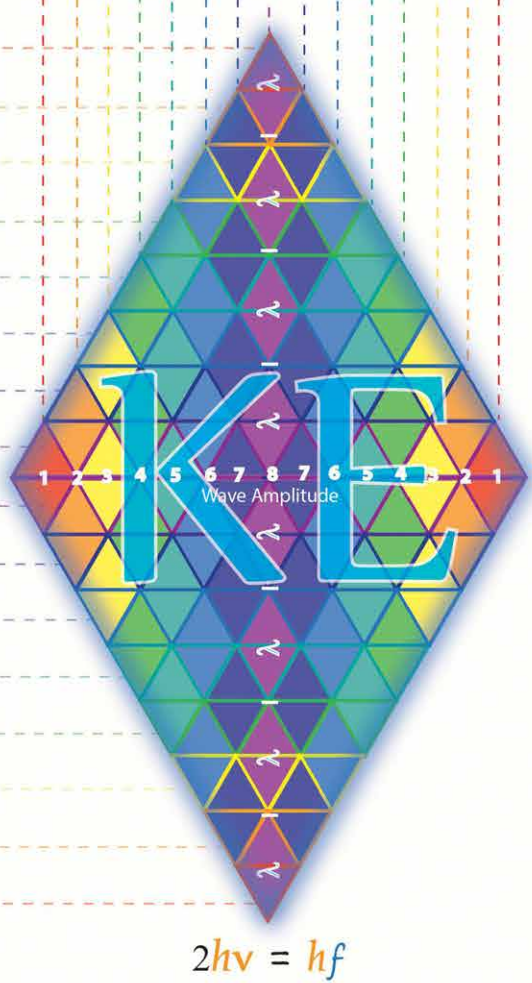
Bosons are transverse quanta

PHOTONS



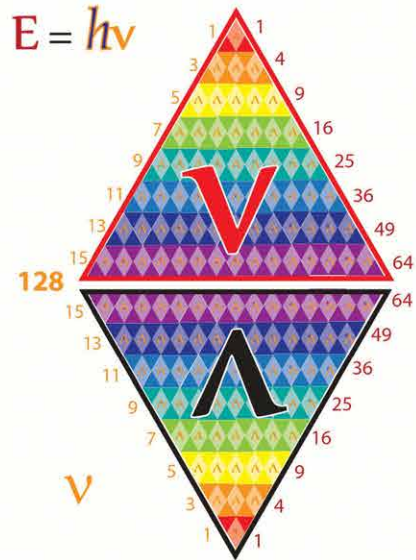
Photons are longitudinal quanta

VS.

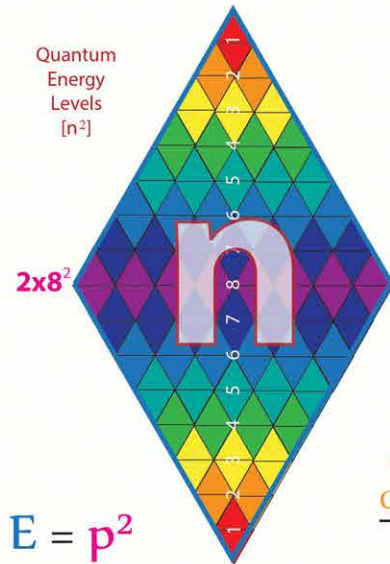


$$2hv = hf$$

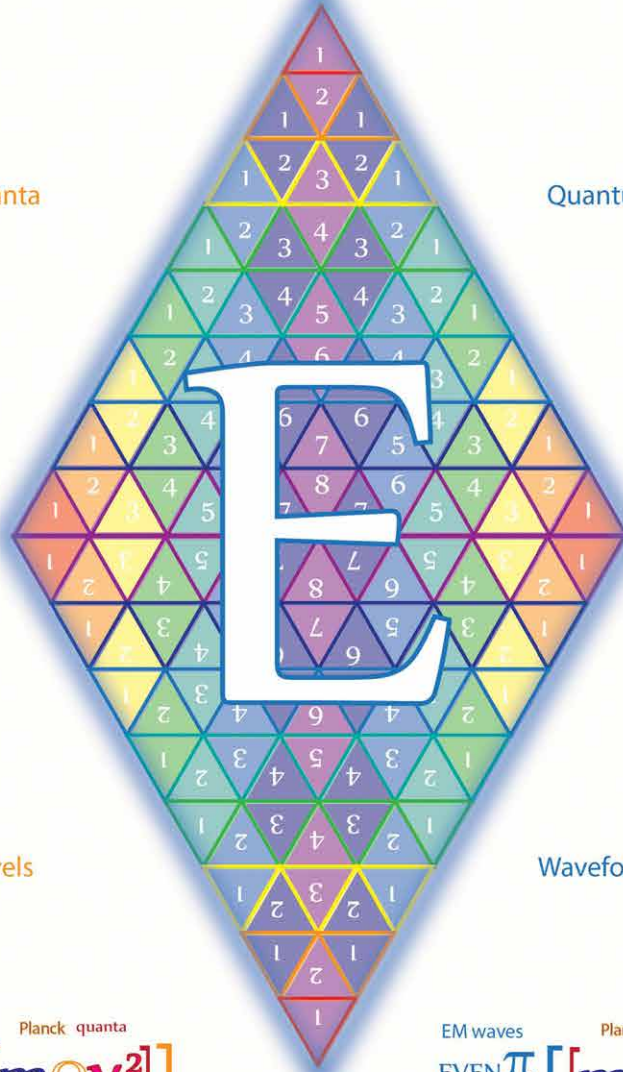
Quantum Energy distributions



Transverse Boson quanta



Quanta



Quantum

Levels

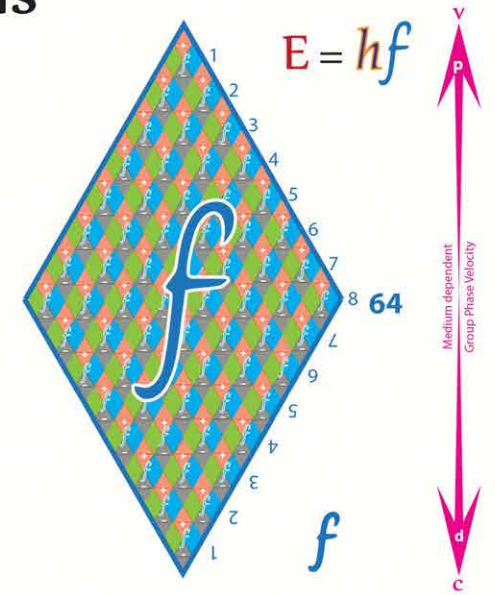
Waveforms

Bosons Planck quanta

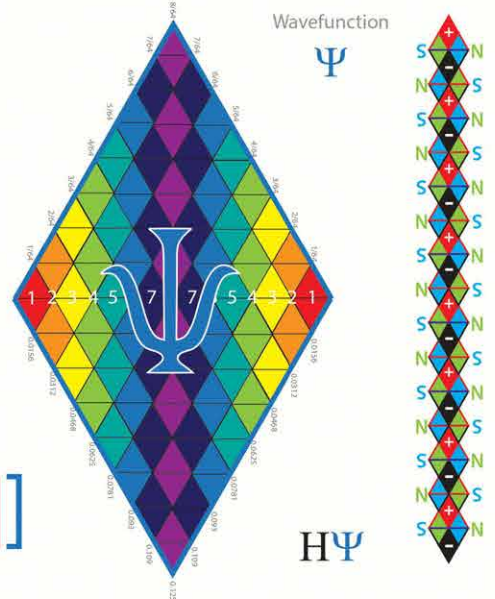
$$\frac{ODD\pi}{c^2} \left[\left[\frac{m\Omega v^2}{\text{mass velocity}} \right] \right]$$

EM waves Planck quanta

$$\frac{EVEN\pi}{c^2} \left[\left[\frac{m\Omega v^2}{\text{mass velocity}} \right] \right]$$



Longitudinal Photon Frequency



Normal Distributions

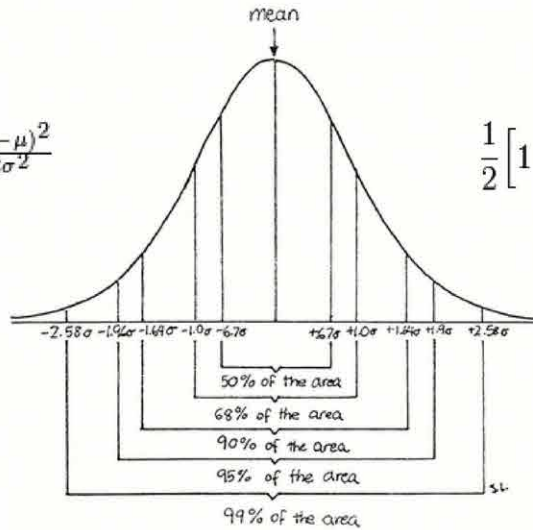
The Gaussian distribution sometimes informally called the bell curve.



Pierre de Fermat

Pierre de Fermat is given credit for early developments that led to infinitesimal calculus.

$$\frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$



$$\frac{1}{2} \left[1 + \operatorname{erf} \left(\frac{x - \mu}{\sqrt{2\sigma^2}} \right) \right]$$



Leonhard Euler

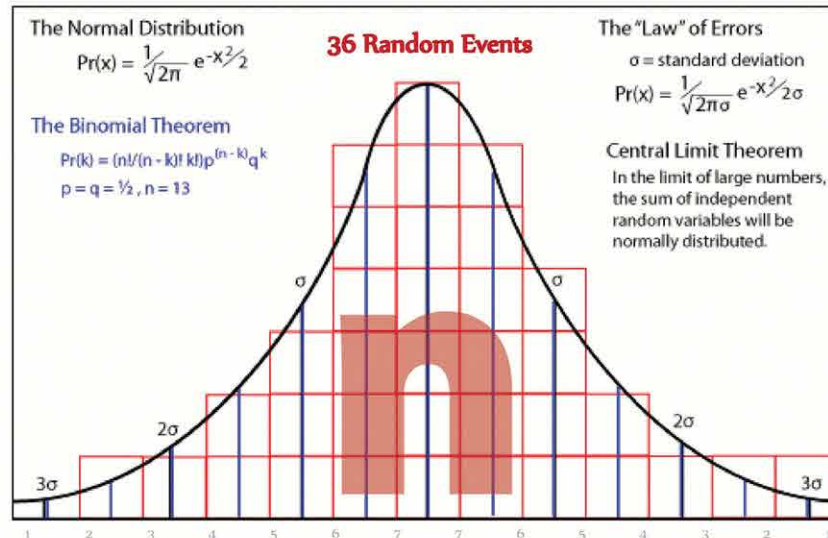
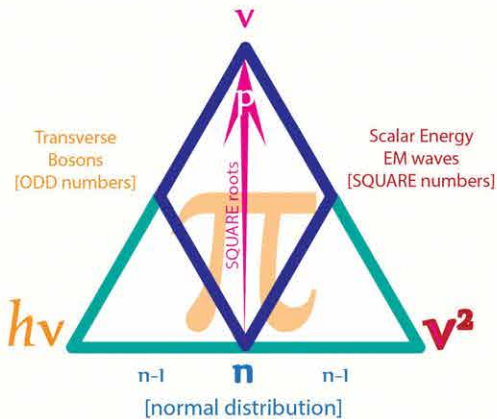
Leonhard Euler developed a formula which links complex exponentiation with trigonometric functions

A bell shaped curve defines the standard normal distribution, in which the probability of observing a point is greatest near the average, and declines rapidly as one moves away from the mean.

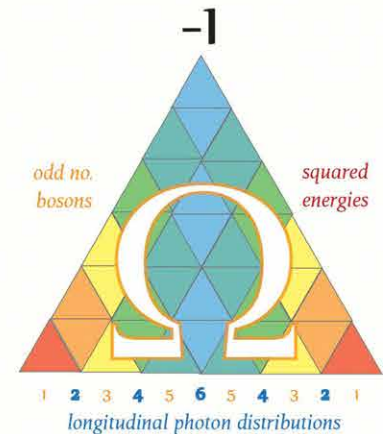
all ODD numbers are

$$a^2 - b^2 = [a-b].[a+b]$$

the difference of two squares



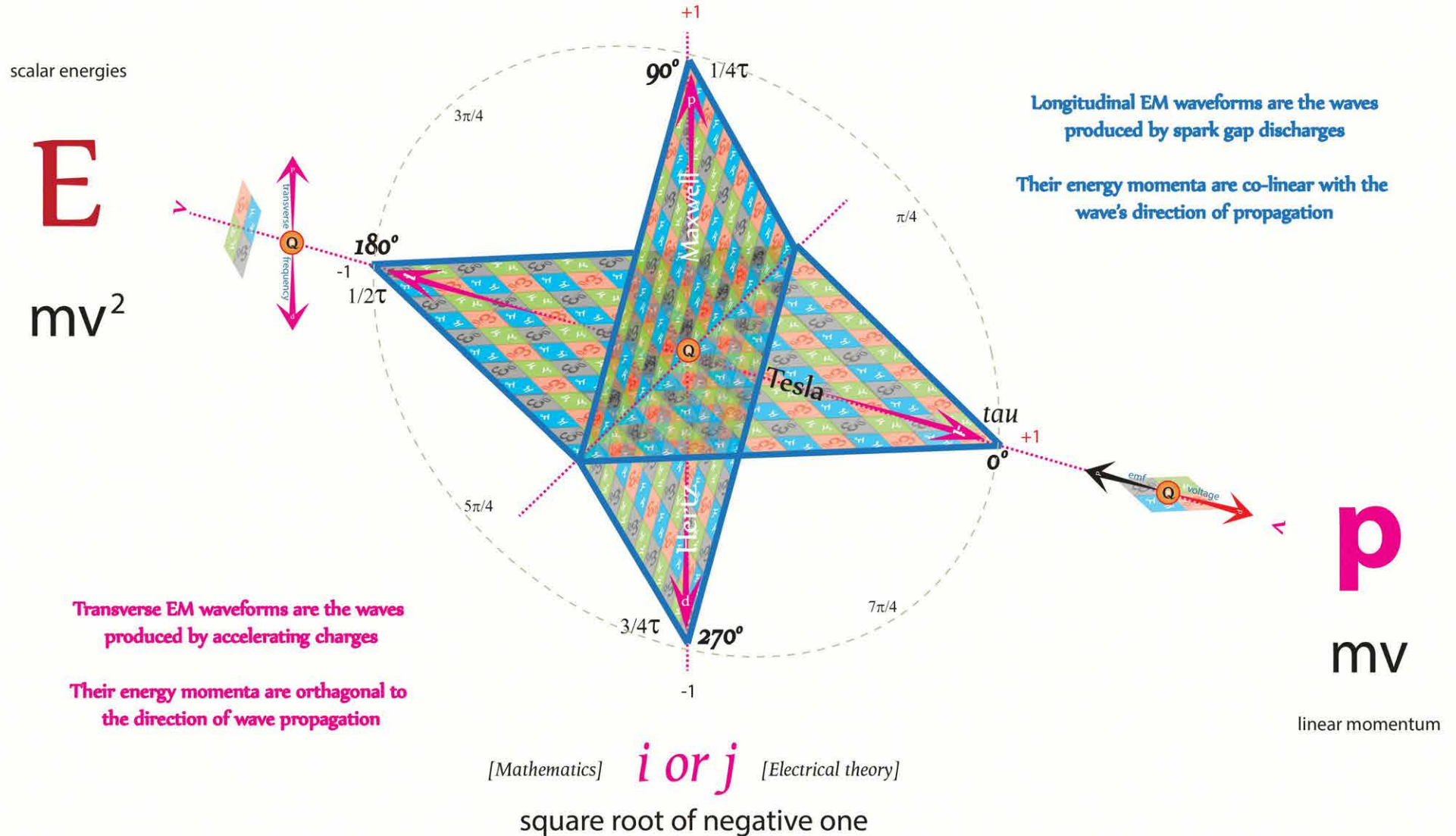
$$e^{i\pi} = -1$$



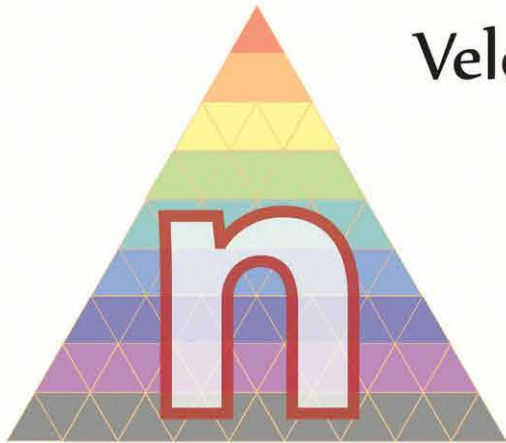
In probability theory, the normal (or Gaussian) distribution is a continuous probability distribution that has a bell-shaped probability density function, known as the Gaussian function

Fundamental theorem of Energy momenta

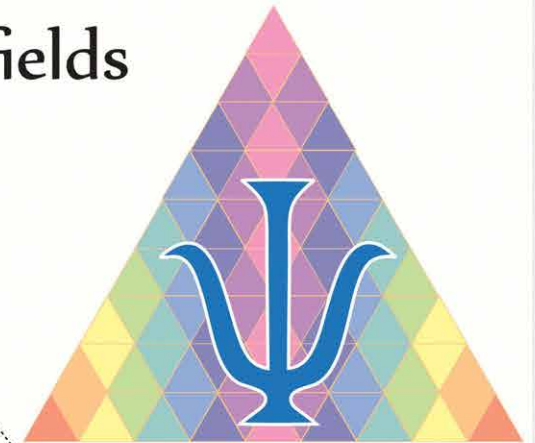
A nth level scalar energy momenta waveform has exactly n linear momentum in unit circle co-ordinate systems
(with Longitudinal and Transverse equilateral Planck waveforms being orthogonal to each other)



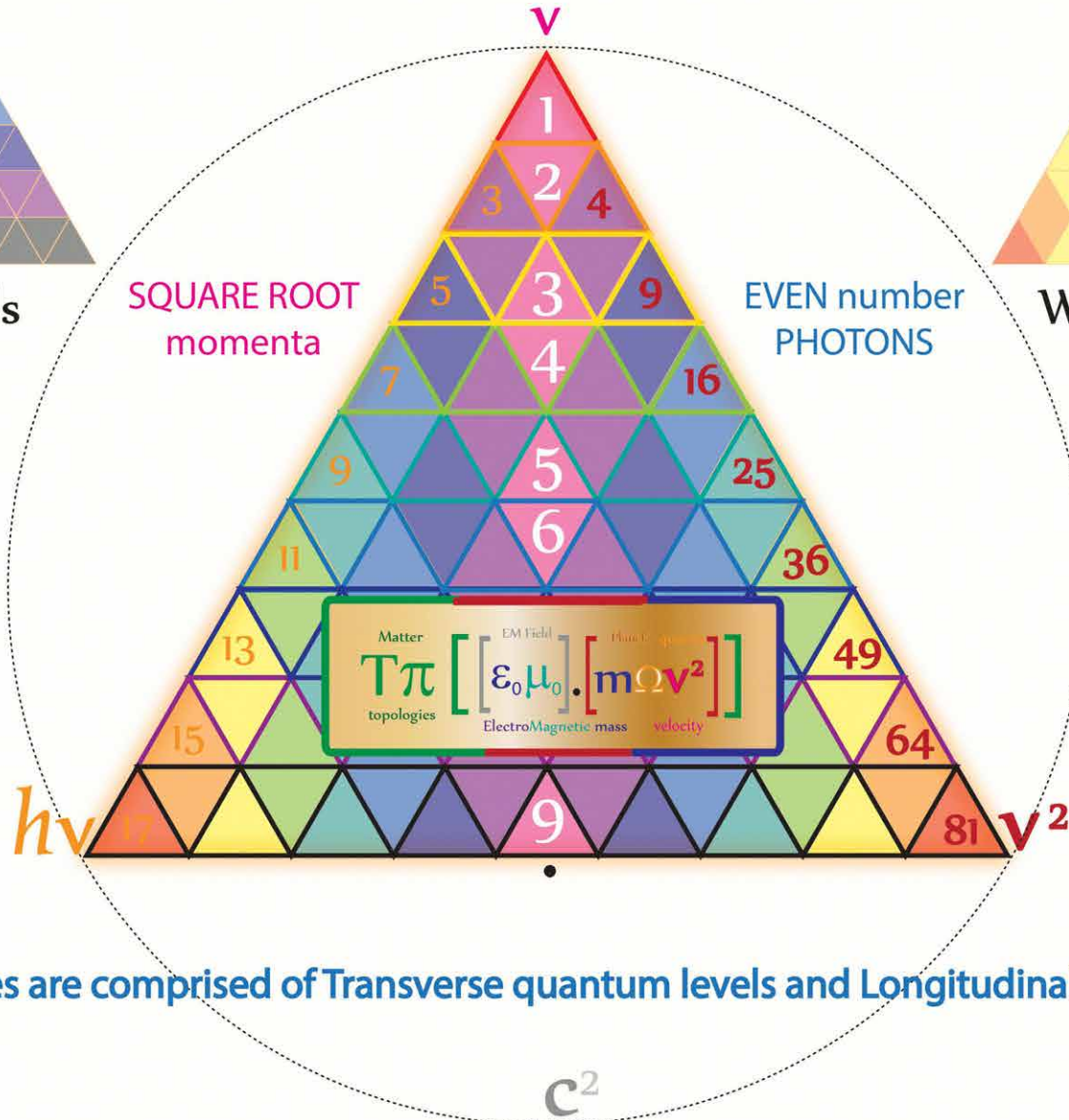
Velocity and Time dependent EM fields



Quantum levels



Wave probabilities



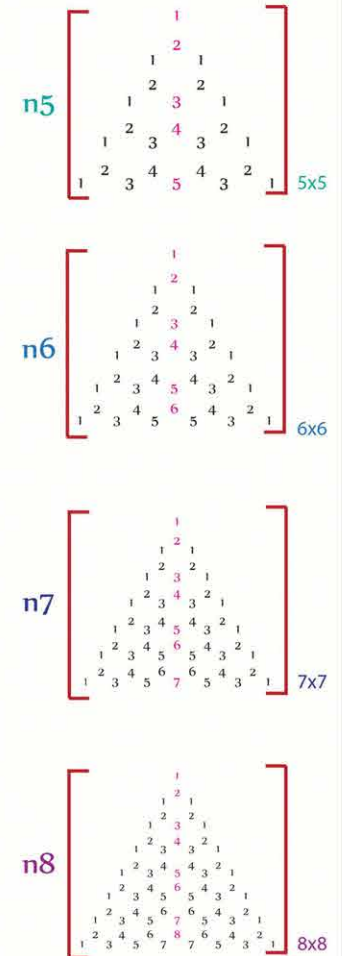
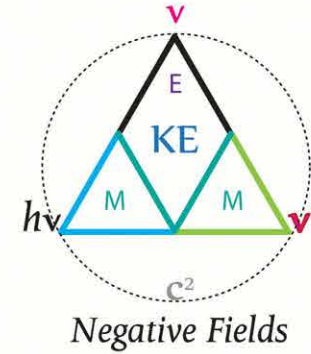
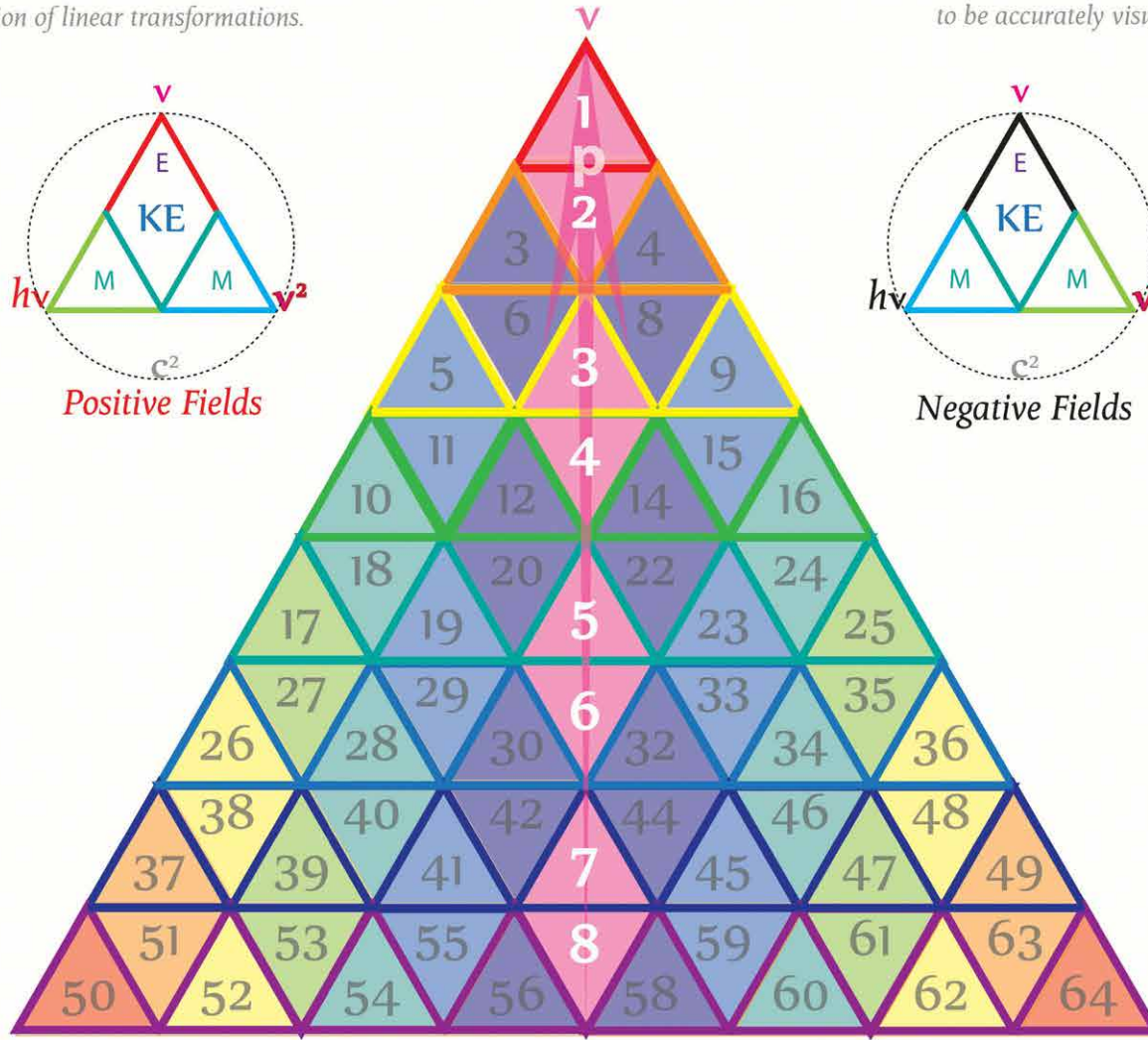
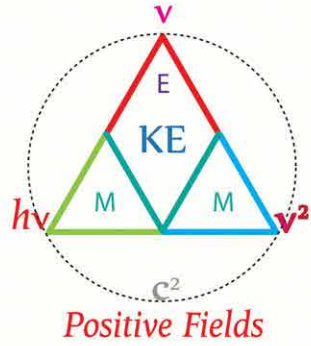
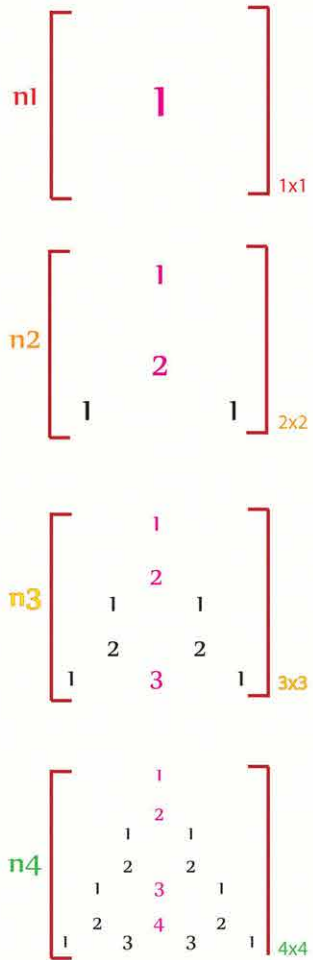
All EM geometries are comprised of Transverse quantum levels and Longitudinal wave probabilities

Matrices are a key tool in linear algebra.

One use of matrices is to represent linear transformations, which are higher-dimensional analogs of linear functions of the form $f(x) = cx$, where c is a constant; matrix multiplication corresponds to composition of linear transformations.

Matrices

Further developing equilateral Matrices and tensor mathematics to reflect the 2D geometry of EM, KEM and GEM quantum fields, along with the geometric quantisation of mass-energy momenta and their energy distributions allows for field interactions to be accurately visualised and modelled

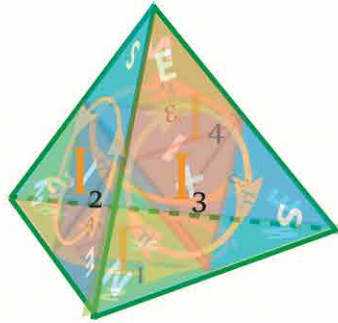


Tensors are geometric entities introduced into mathematics and physics to extend the notion of scalars, geometric vectors, and matrices to increasingly higher orders.

Modifying Square matrices to reflect the equilateral geometries of Tetronic fields allows for the accurate geometric modelling of all Scalar & Vector fields along with their varied intrinsic quantum energies and physical properties

Energy momenta Tensors

momenta
(a property of Energy)
is conservative



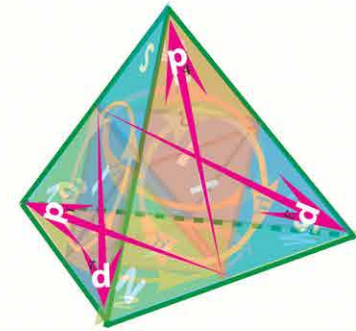
$$\mathbf{p}_M \rightarrow (\mathbf{E}, p_1, p_2, p_3, p_4).$$

All standing-wave Matter topologies can be modelled using its Tetryonic charge energy momenta Tensors

with an additional Kinetic EM energy-momenta tensor required for Matter in motion

$$\mathbf{p}_{KEM} \rightarrow (\mathbf{E}, p_5).$$

Matter
(a geometric property)
is NOT conservative

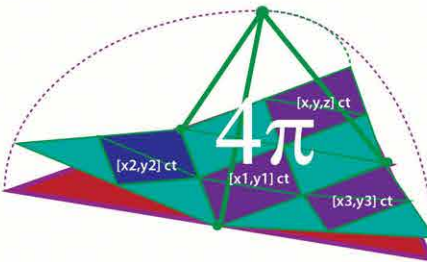


2D+1 [SR] mass-energy momenta can be folded into 3D+1 [GR] Matter that can be modelled using 4 Energy-momenta tensors



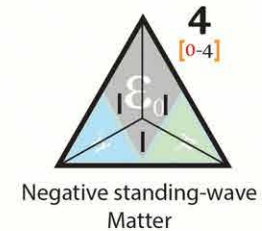
$$E = \sum_{\text{all fascia}} E$$

Energy of a massive particle is the total of all Planck quanta (compton frequency) in a 3D geometry



$$\vec{p} = \sum_{\text{all fascia}} \vec{p}$$

Total Momentum is the total of all quanta linear Momenta in a 3D particle



Relativistic Matter in motion

$$I = \sum_{\text{all fascia}} I$$

Inertial mass is the total of all inertia in a 3D particle



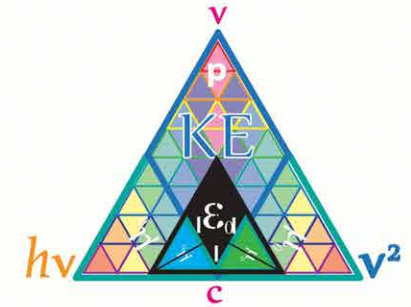
Photons have null energy-momentum tensors

Note that both 2D mass-energies [Special Relativity] and 3D Matter [General Relativity] have distinct Energy momenta

It is the 3D Tetrahedral topologies that provides a definitive basis for Matter



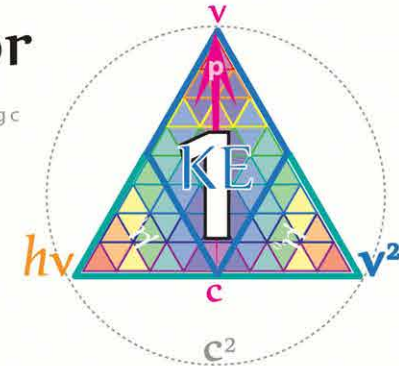
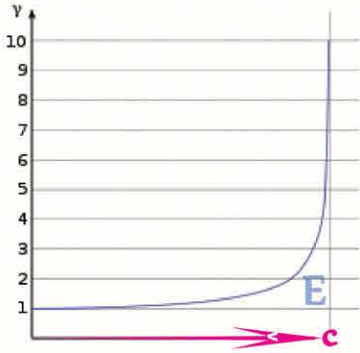
Tetryonic Energy momenta tensors should not be confused with Four vector tensors which map energy-momenta vectors in 3D spatial[cartesian] co-ordinate systems



Relativistic Lorentz correction factor

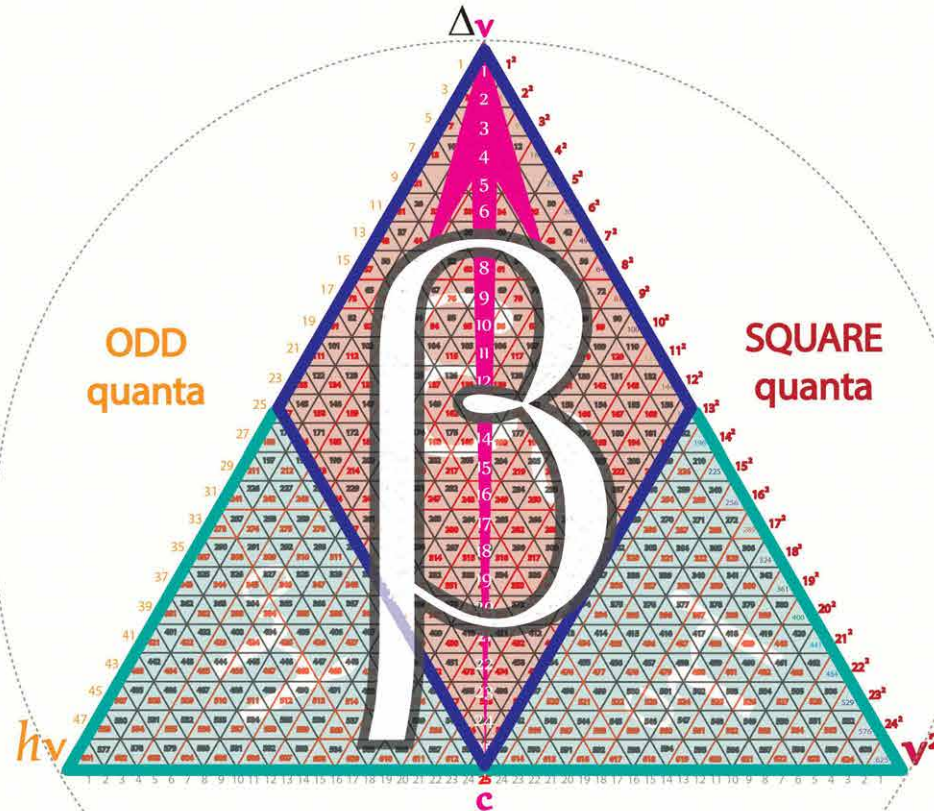
The Lorentz factor or Lorentz term is an expression which appears in several equations in special relativity. It is often incorrectly graphed [as pictured to the right] as an increasing function of velocity approaching but never reaching c .

**'c' is the maximum velocity achievable through the electrical acceleration of particles
is NOT the maximum velocity possible for Matter in motion**



Linear correction factor

$$\beta = \left[\frac{v}{c} \right]$$



Scalar correction factor

$$\beta^2 = \left[\frac{v^2}{c^2} \right]$$

$$\frac{\Delta \gamma}{c^2} \quad \text{Wavelength contraction}$$

$$\frac{\Delta mv}{c^2} \quad \text{Relativistic momentum}$$

$$\frac{\Gamma}{c^2} \quad \text{Lorentz corrections}$$

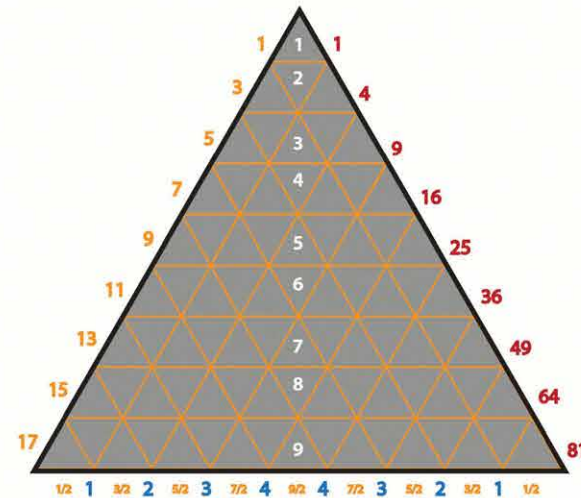
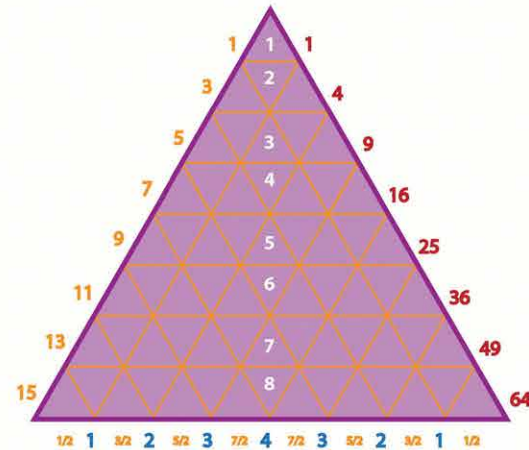
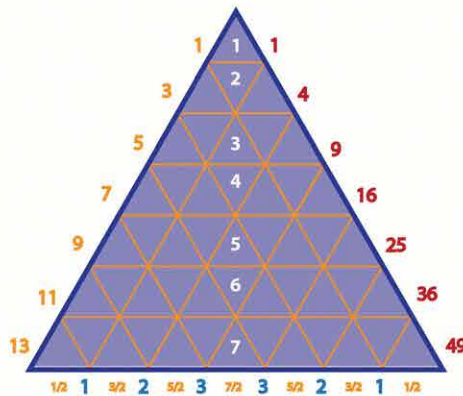
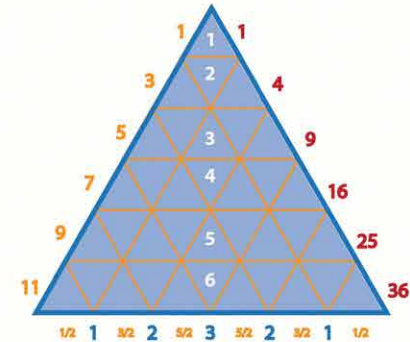
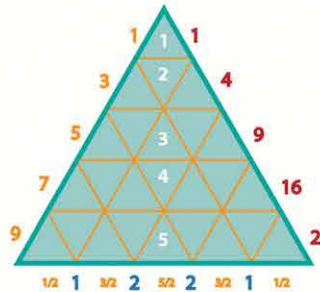
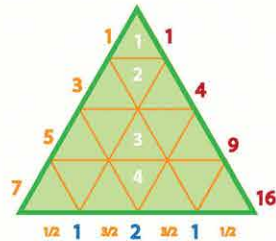
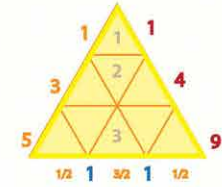
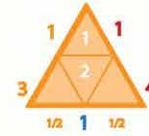
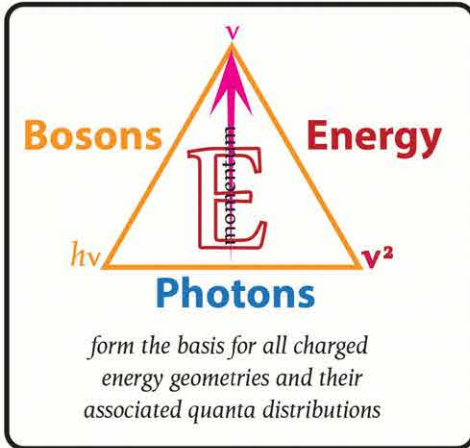
$$\frac{\Delta \Omega}{c^2} \quad \text{Time Dilation}$$

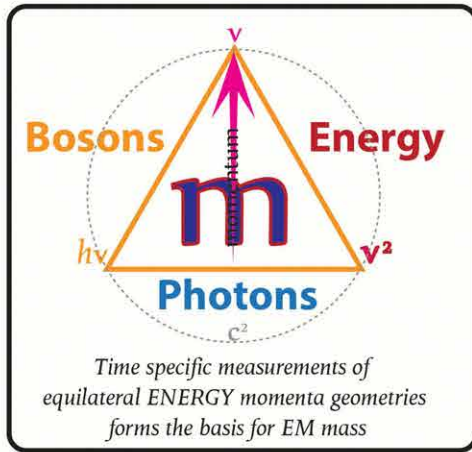
$$\frac{\Delta hv}{c^2} \quad \text{Relativistic mass-energy}$$

Lorentz factors are LINEAR and SCALAR velocity related corrections to the relativistic mass-energy momenta content of any physical system accelerated by EM Forces

Equilateral energies

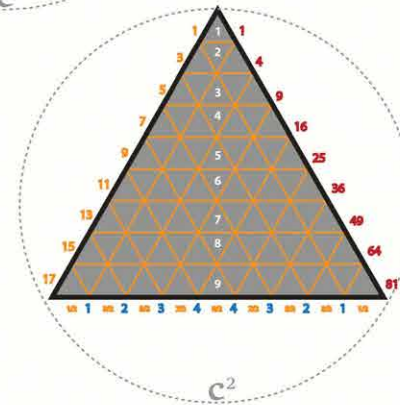
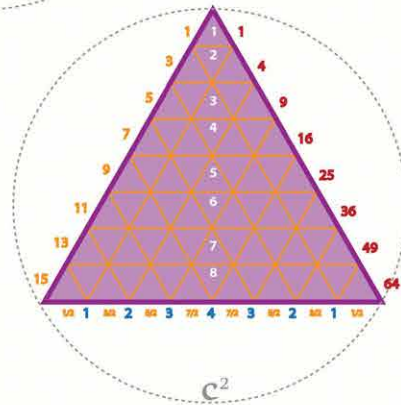
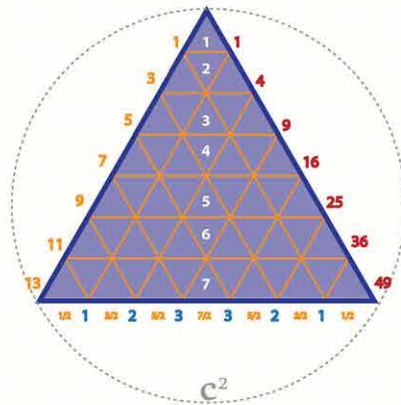
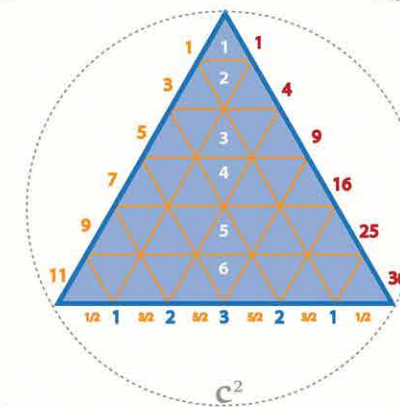
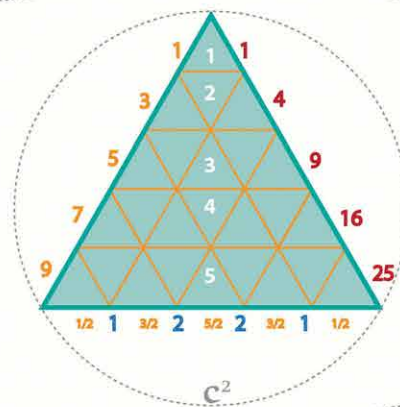
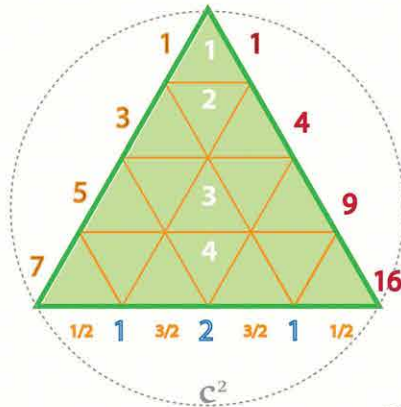
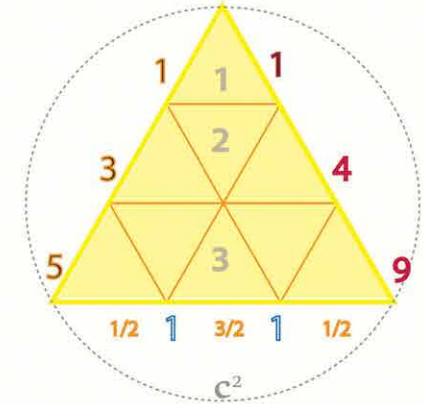
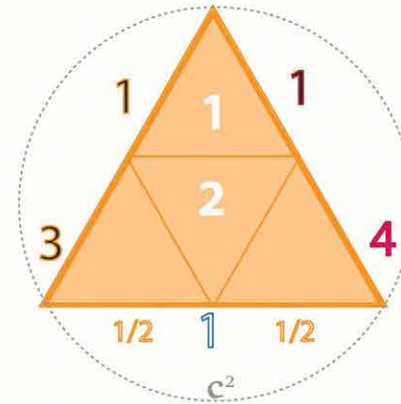
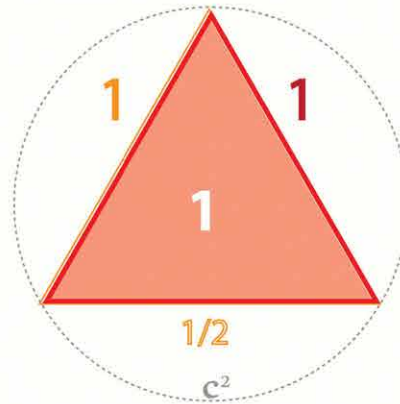
Any measurements of mass without a Space-Time co-ordinate system are measurements of Energy





Electromagnetic mass

2D mass-energy is the surface integral of 3D Matter



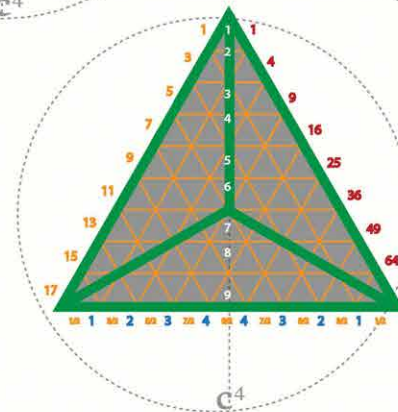
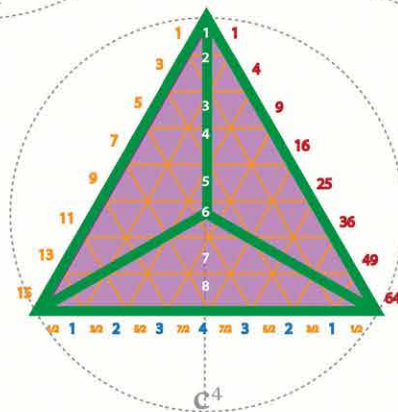
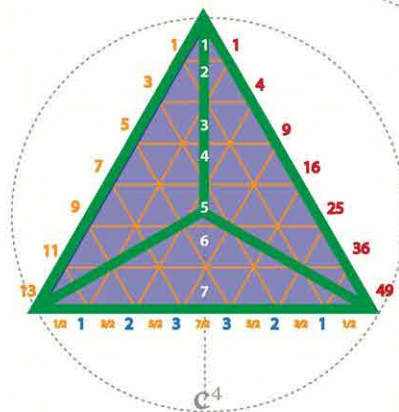
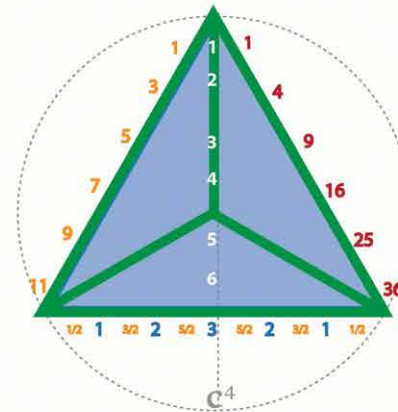
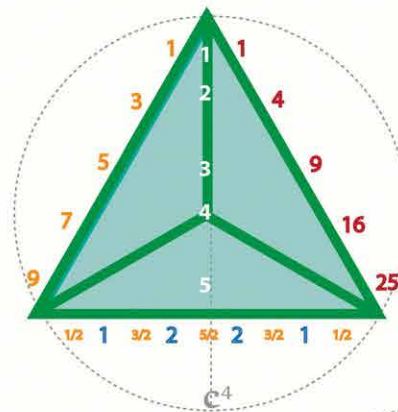
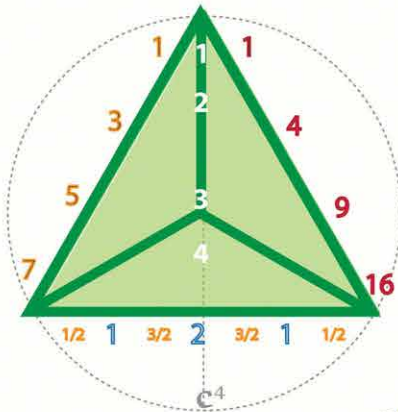
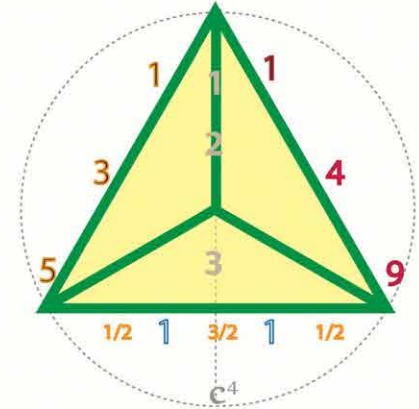
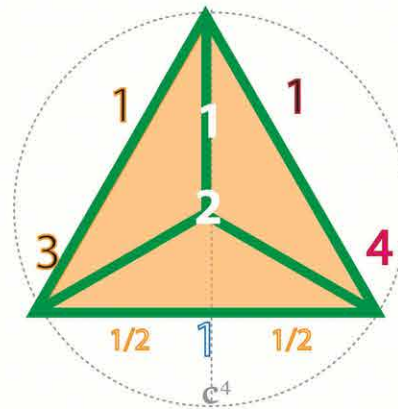
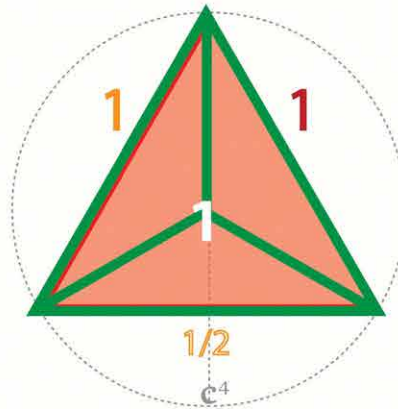
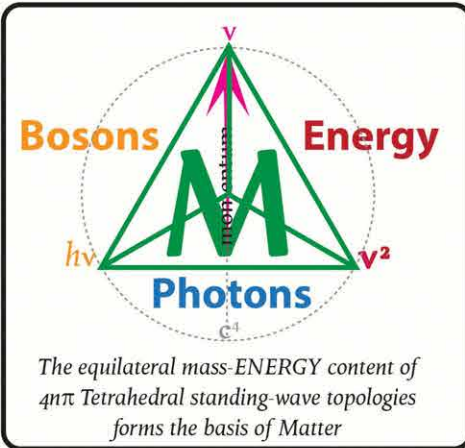
mass-less particles is a physical misnomer

All measurements of energy in spatial co-ordinate systems are measurements of mass

Matter-less is the appropriate terminology

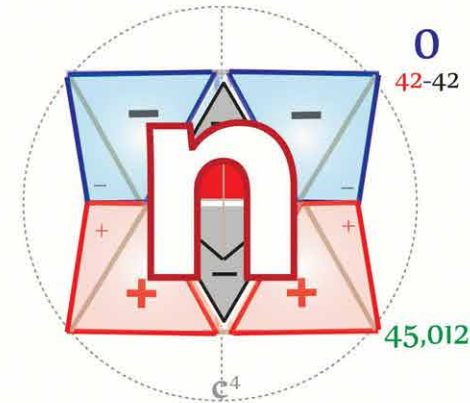
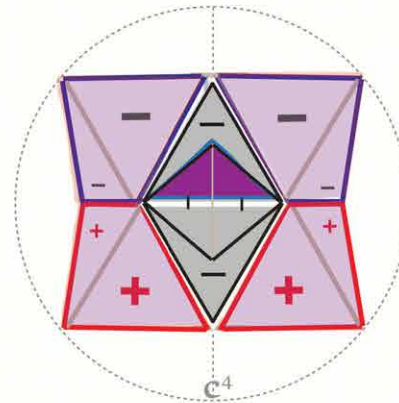
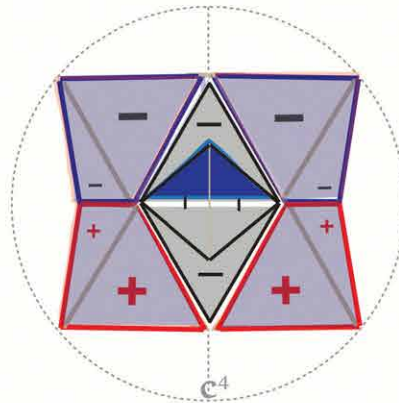
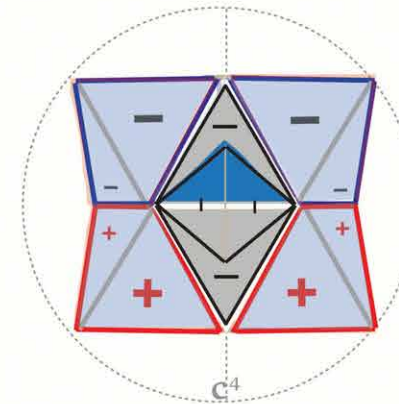
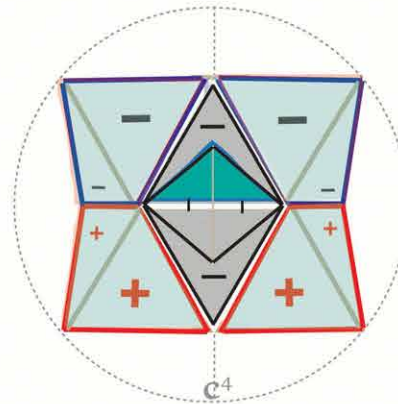
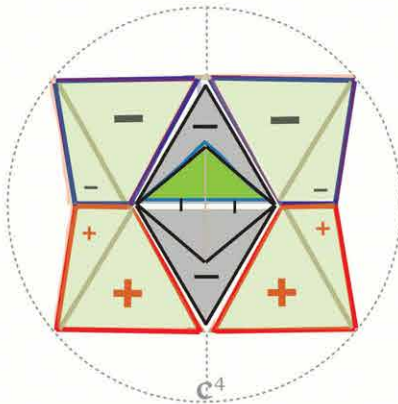
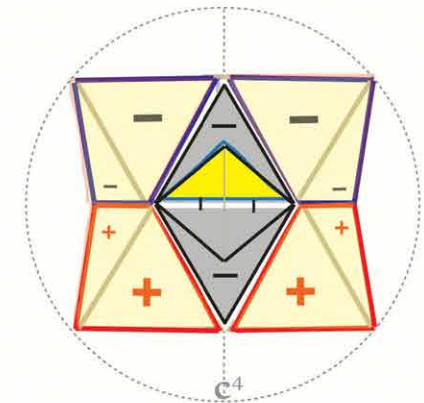
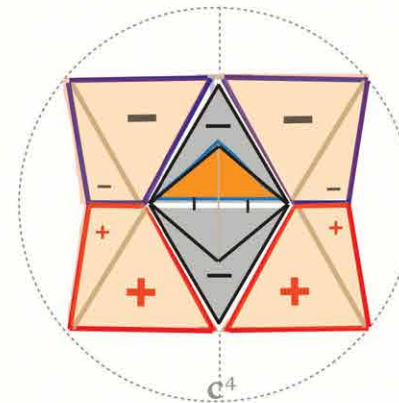
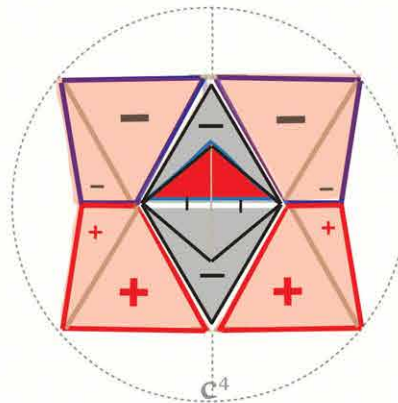
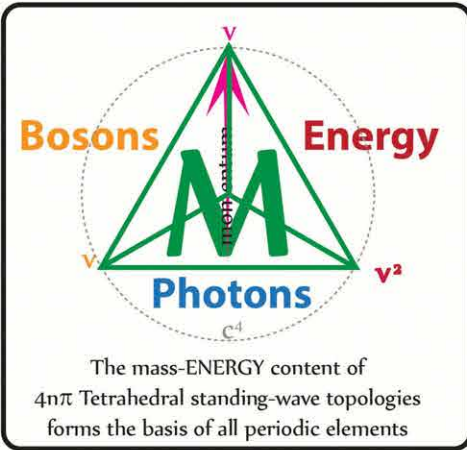
Standing-wave Matter

Matter is a higher order 3D topology created by standing wave mass-energies

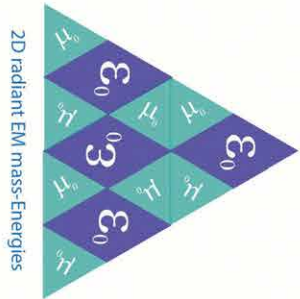
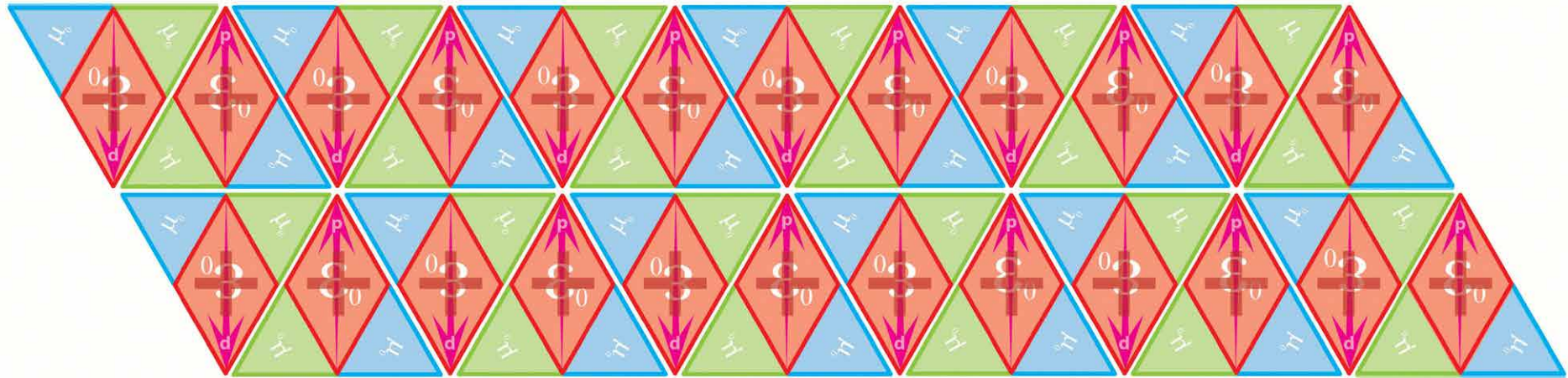


Only mass-ENERGIES contained in the tetryonic fascia of standing-wave topologies contribute to weight

Periodic element nuclei

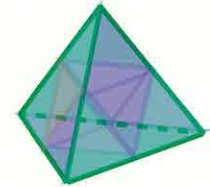


ALL
periodic elements are
comprised of
 n level deuterium
nuclei

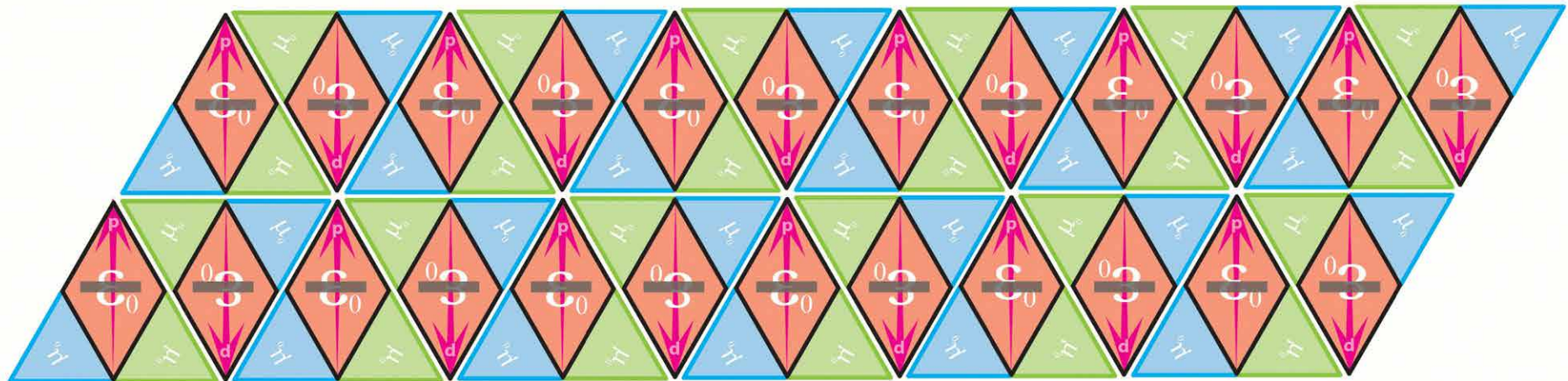


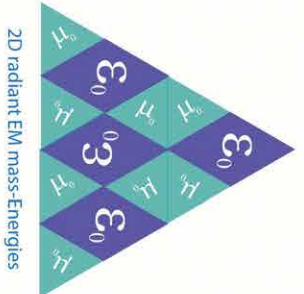
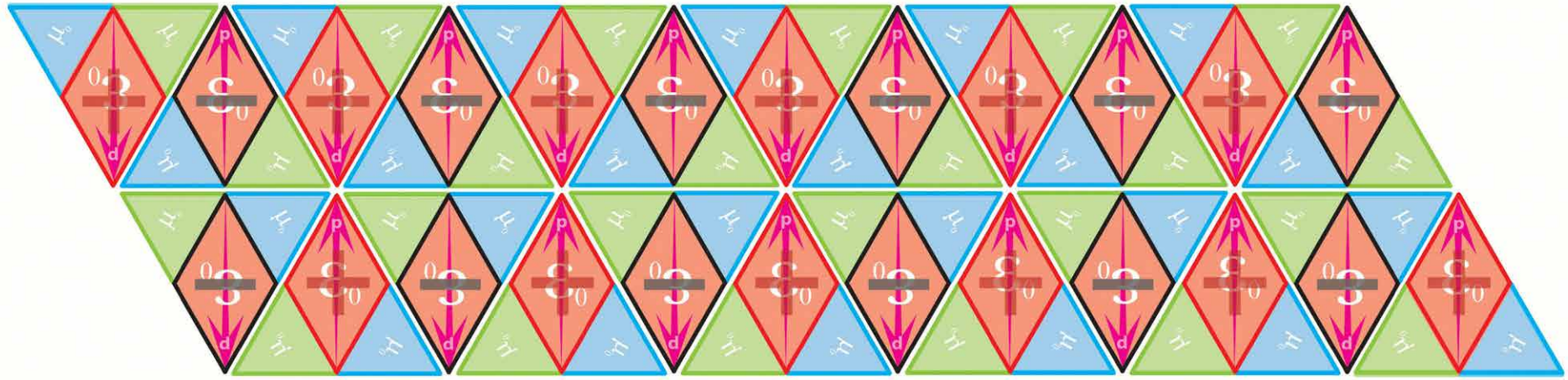
2D radiant EM mass-Energies

n1 - Charged Tetryon Templates



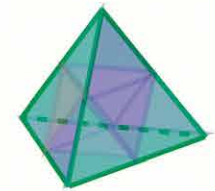
3D standing-wave Matter



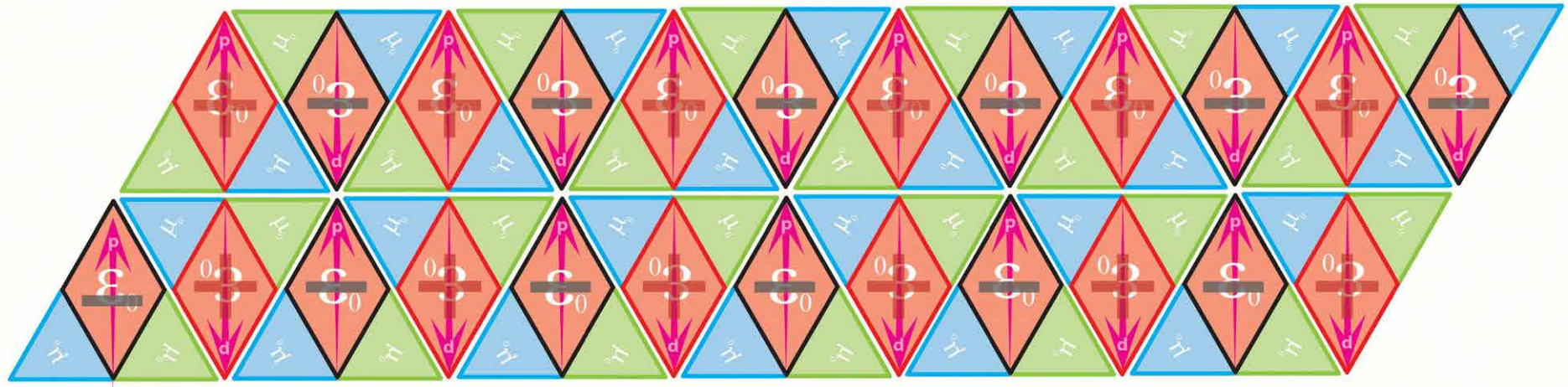


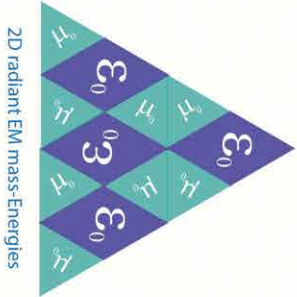
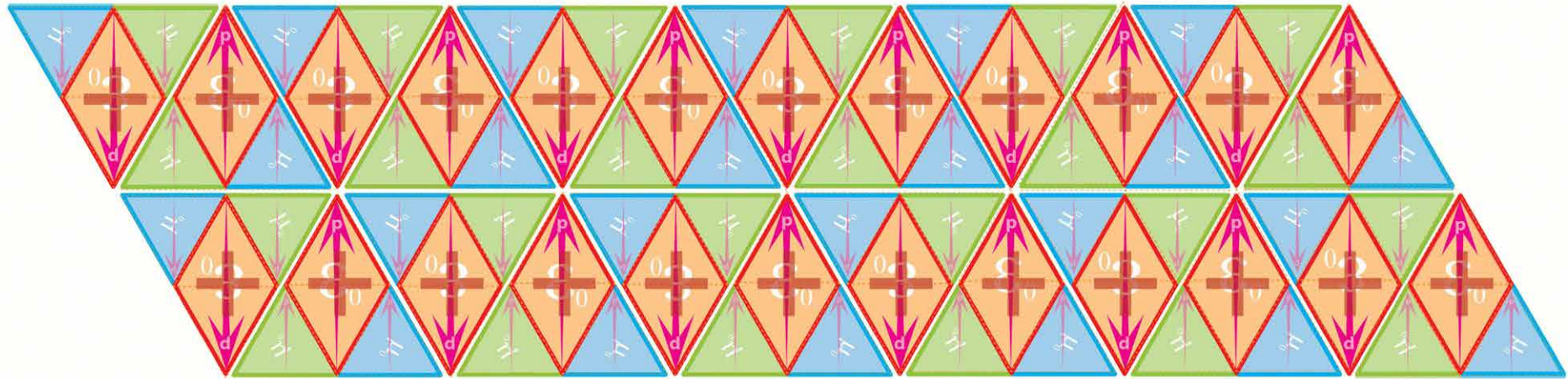
2D radiant EM mass-Energies

n1 - Neutral Tetryon Templates



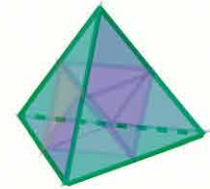
3D standing-wave Matter



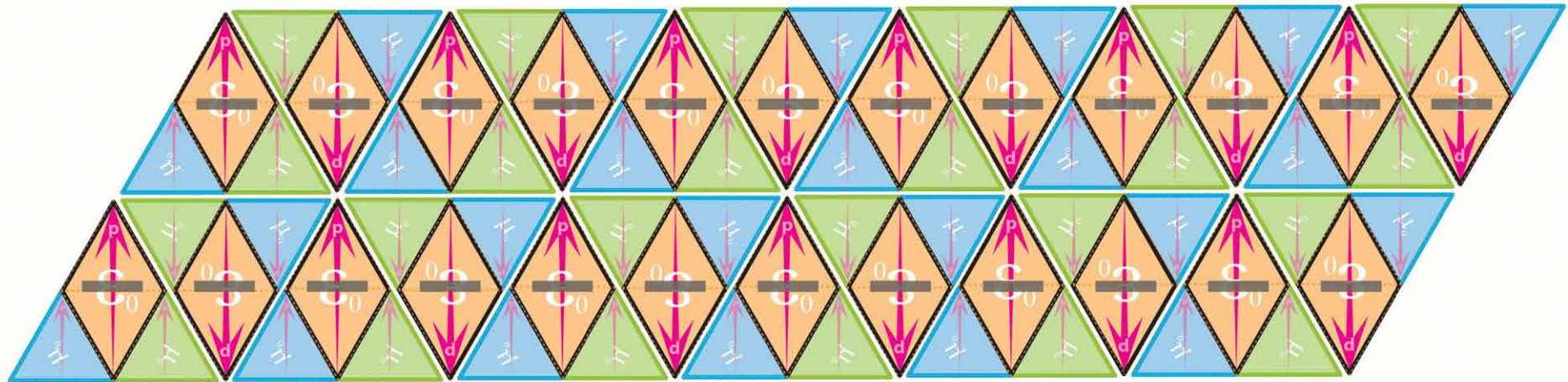


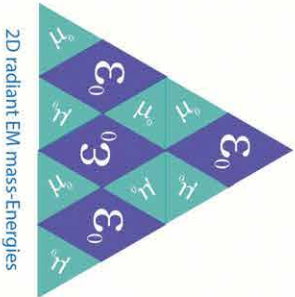
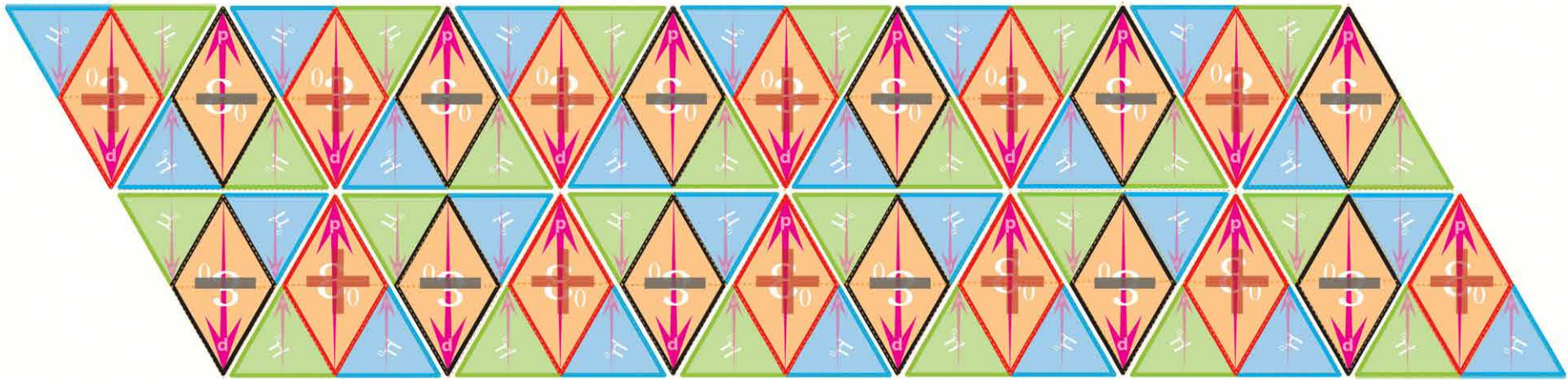
2D radiant EM mass-Energies

n2 - Charged Tetryon Templates



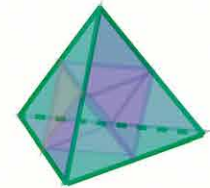
3D standing-wave Matter



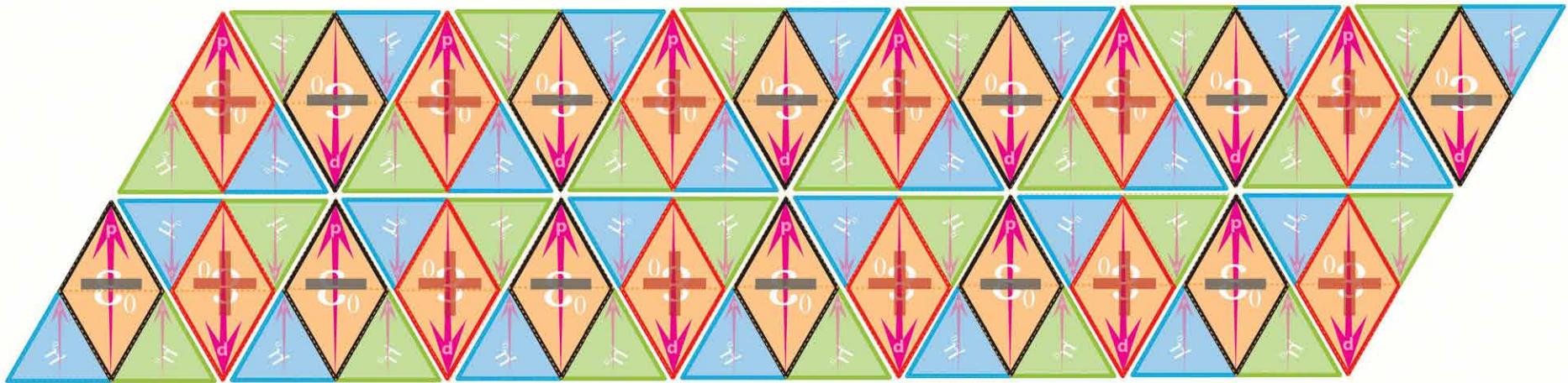


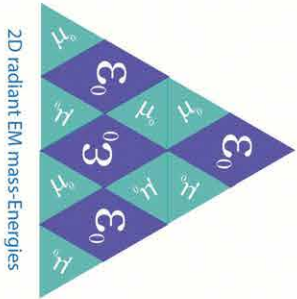
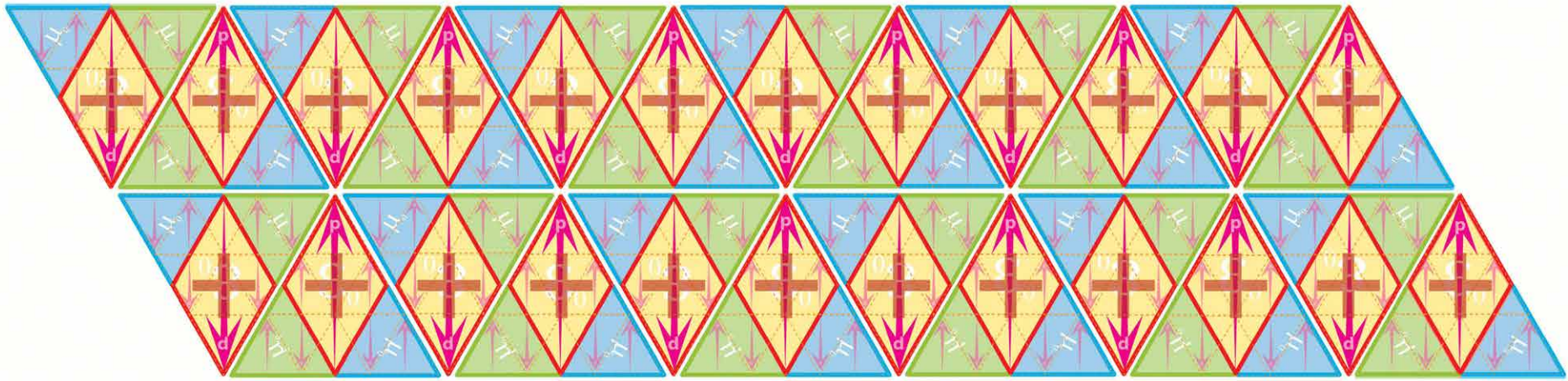
2D radiant EM mass-Energies

n2 - Neutral Tetryon Templates

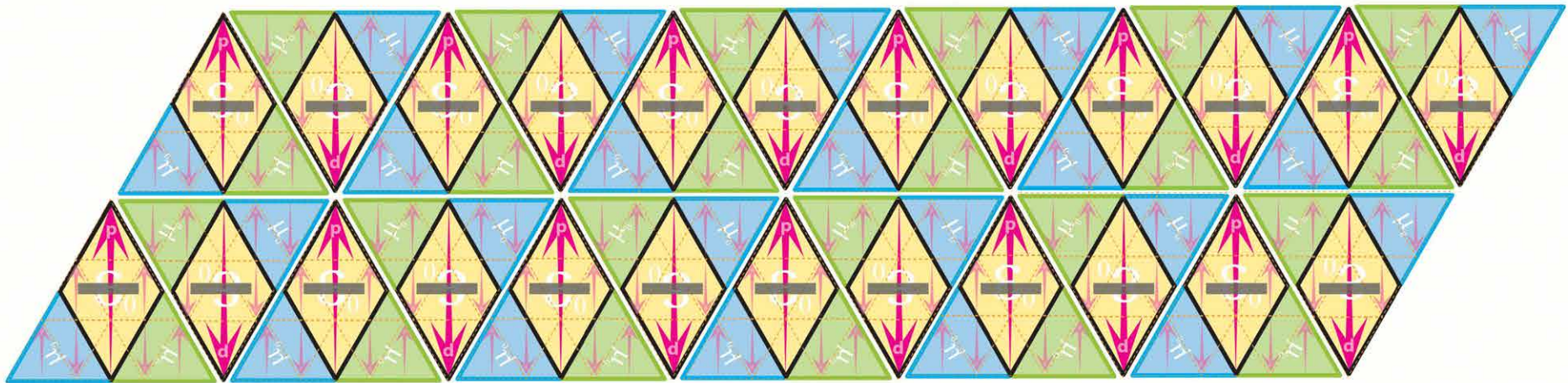
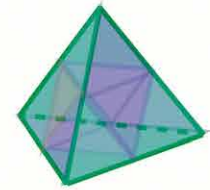


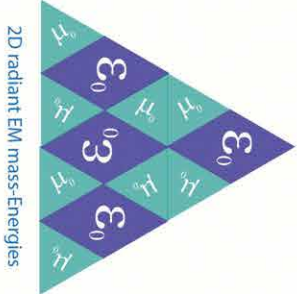
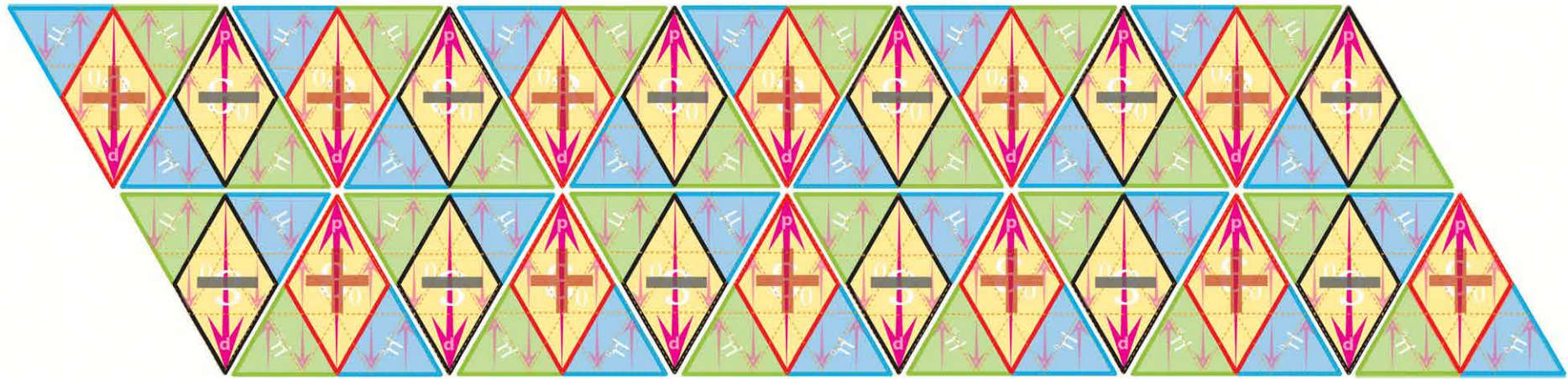
3D standing-wave Matter



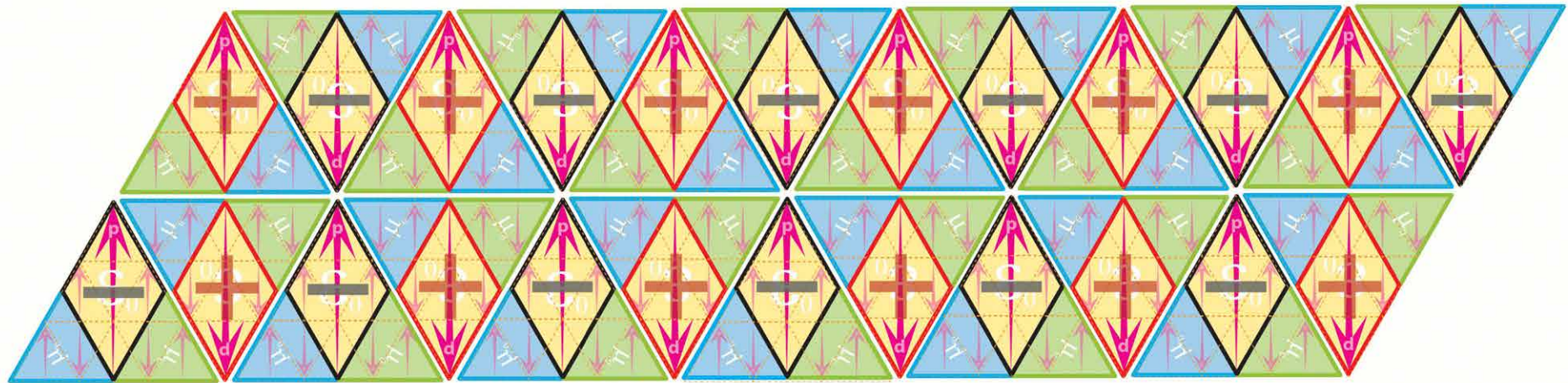
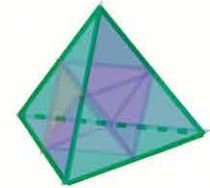


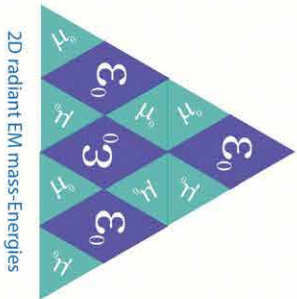
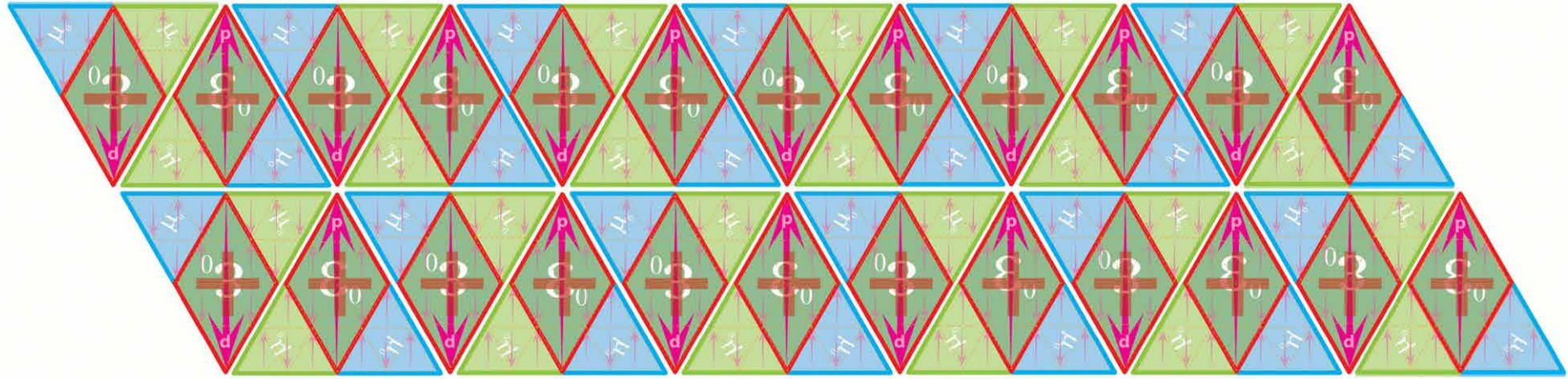
n3 - Charged Tetryon Templates



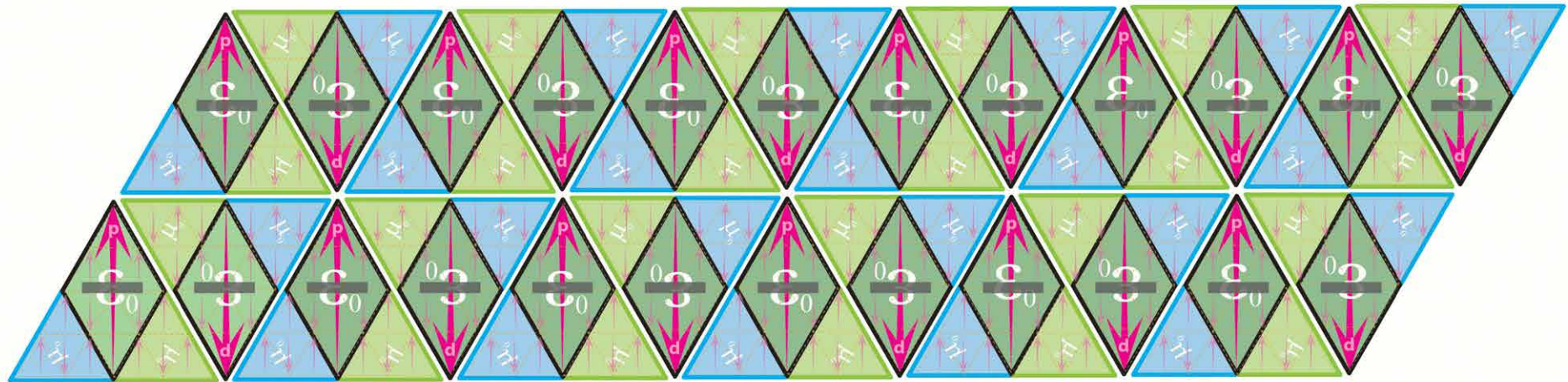
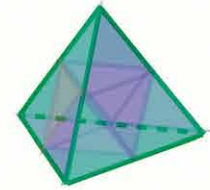


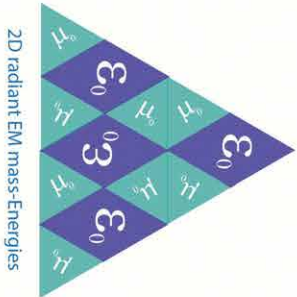
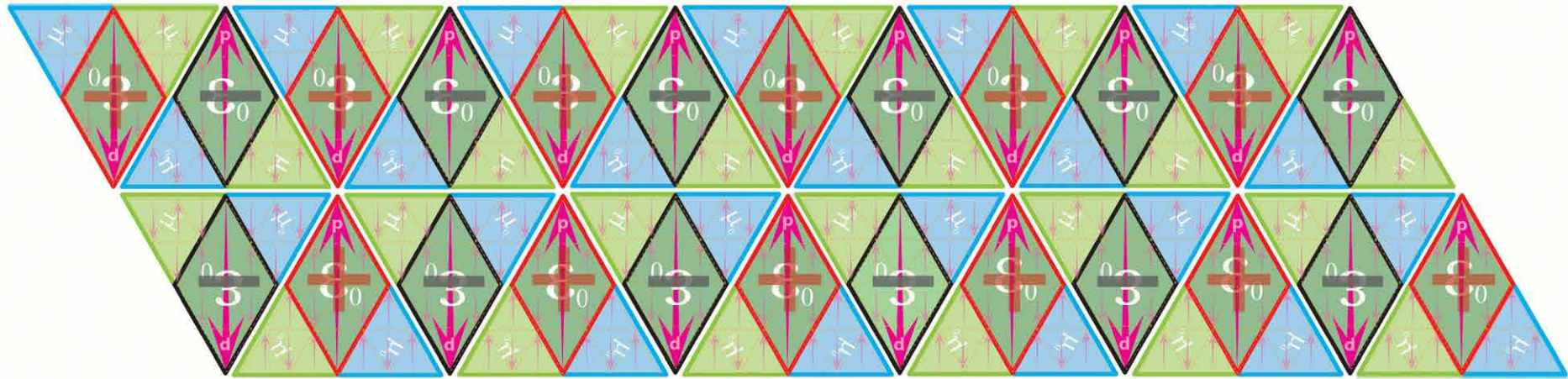
n3 - Neutral Tetryon Templates



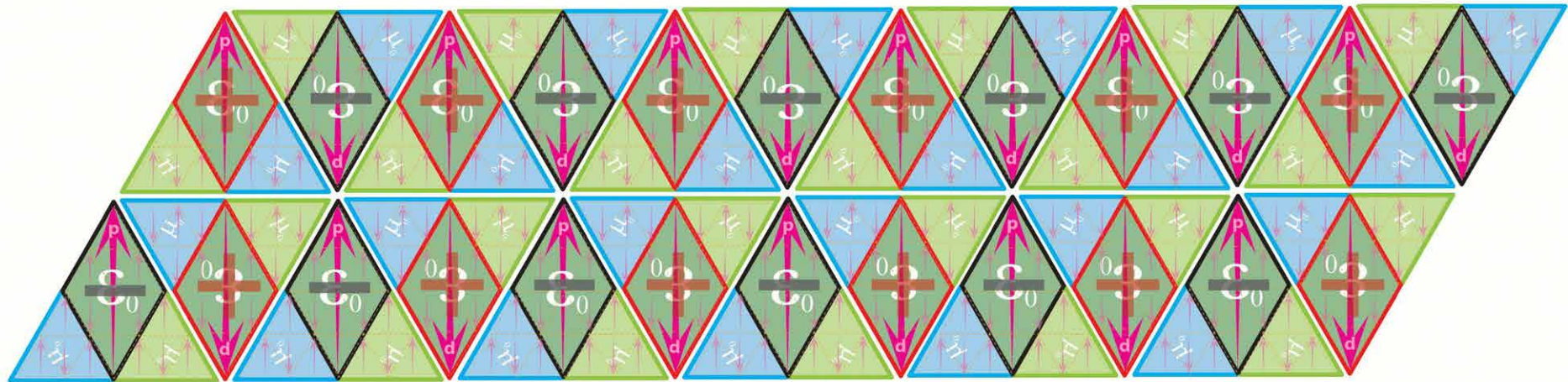
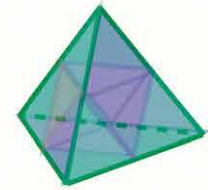


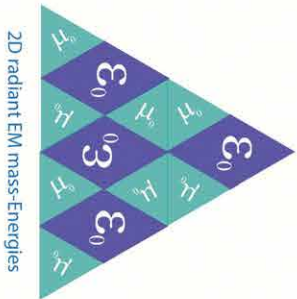
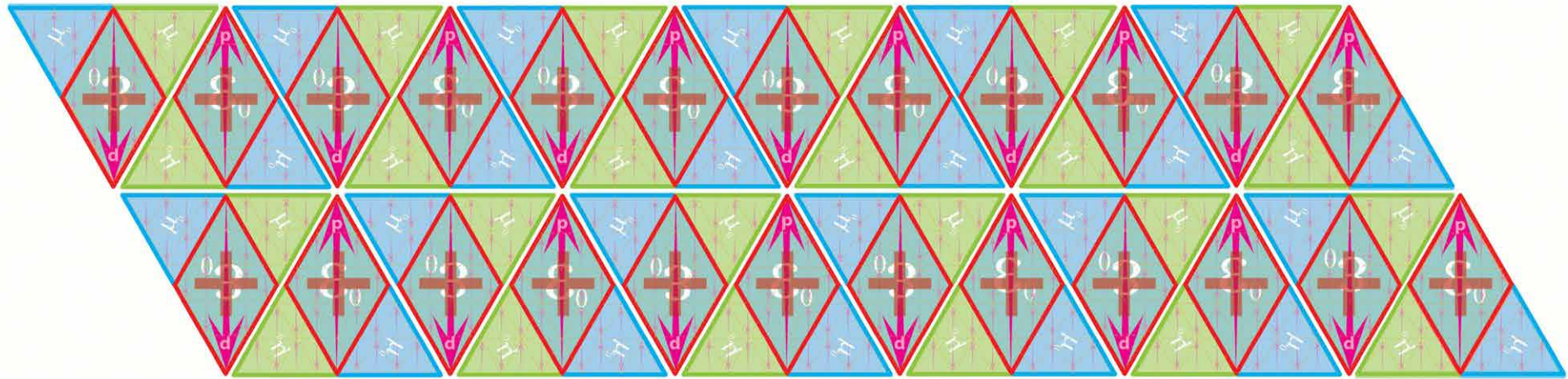
n4 - Charged Tetryon Templates



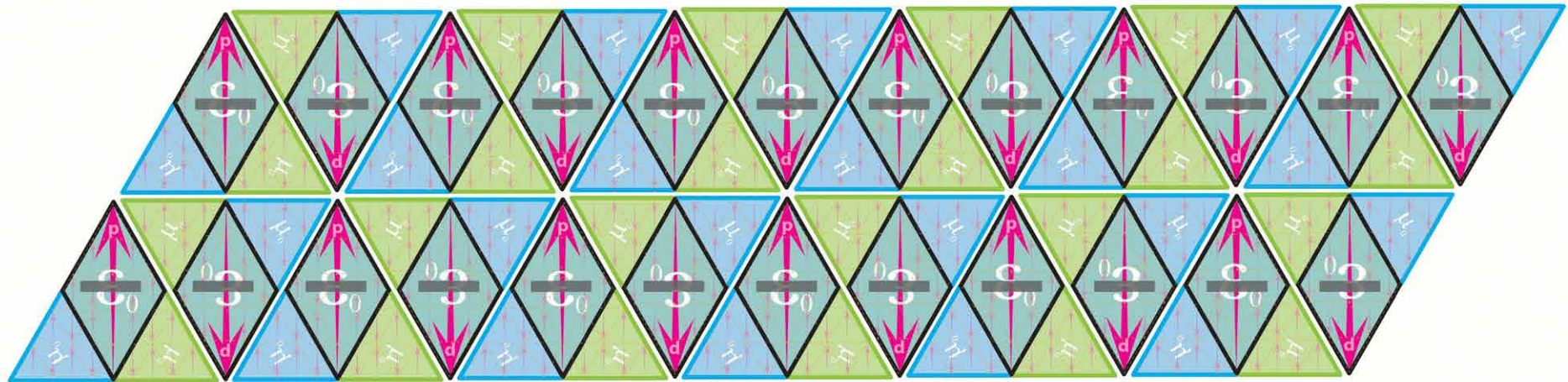
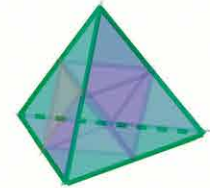


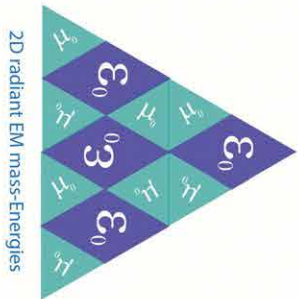
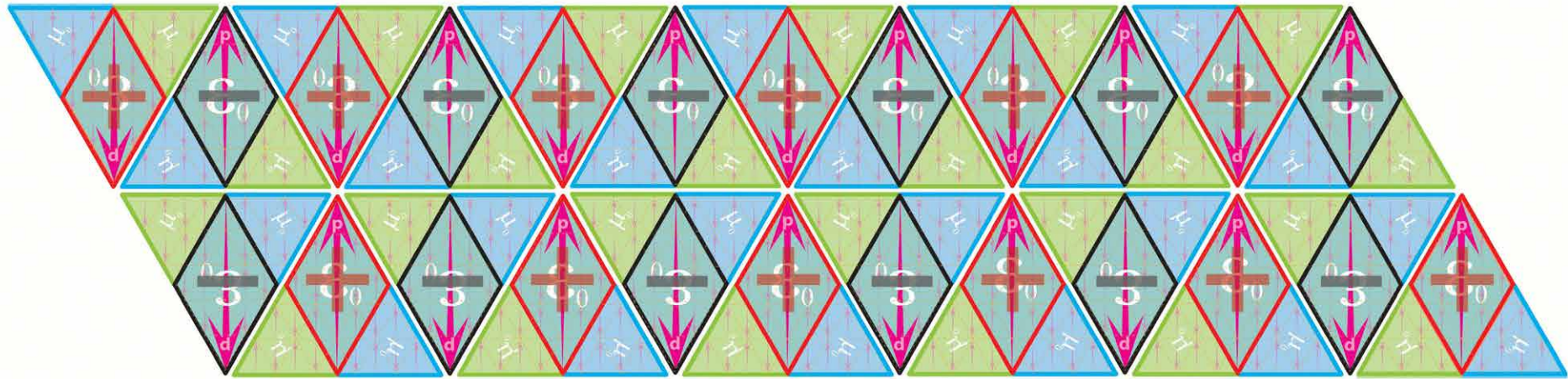
n4 - Neutral Tetryon Templates





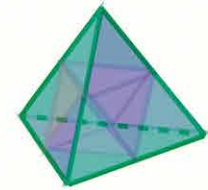
n5 - Charged Tetryon Templates



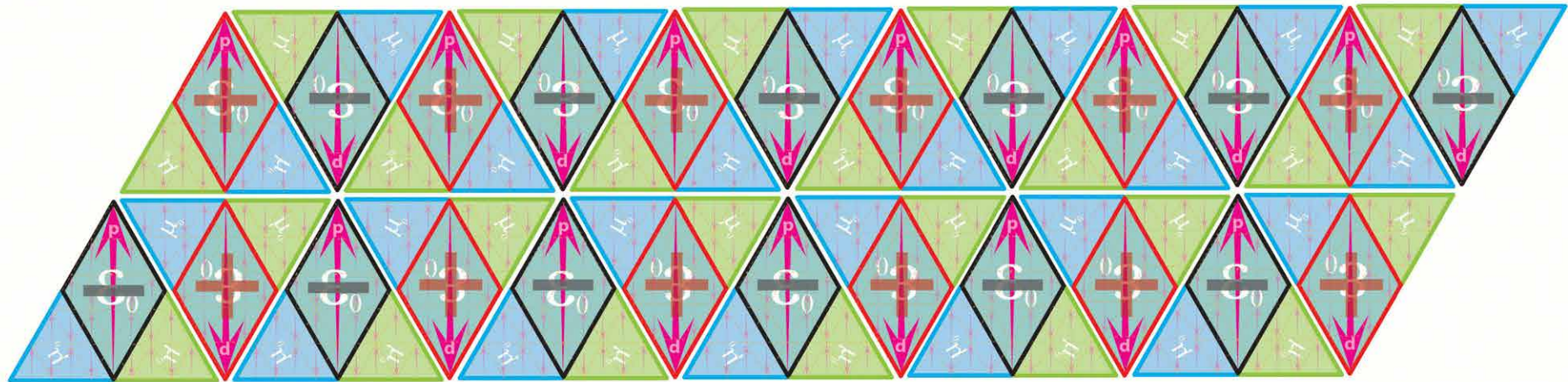


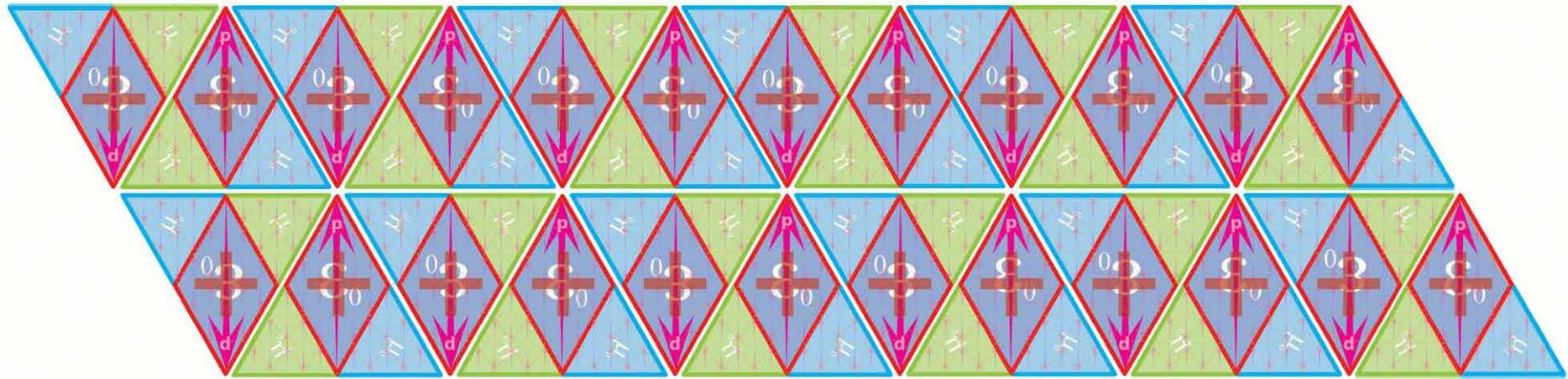
2D radiant EM mass-Energies

n5 - Neutral Tetryon Templates



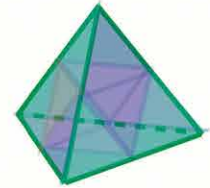
3D standing-wave Matter



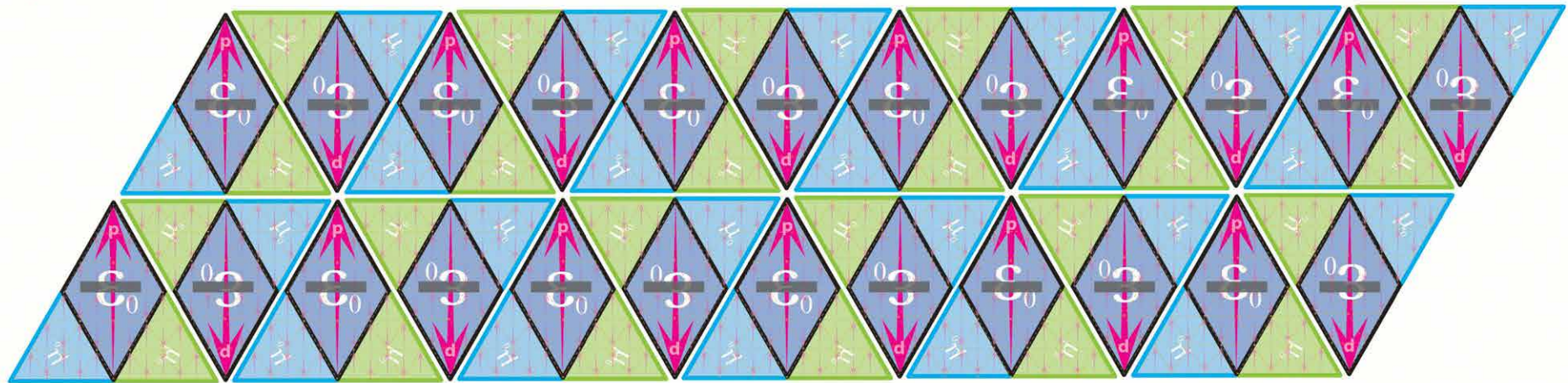


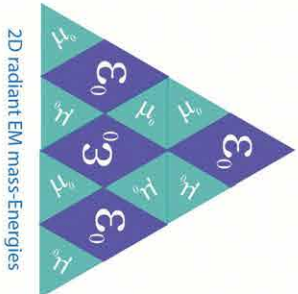
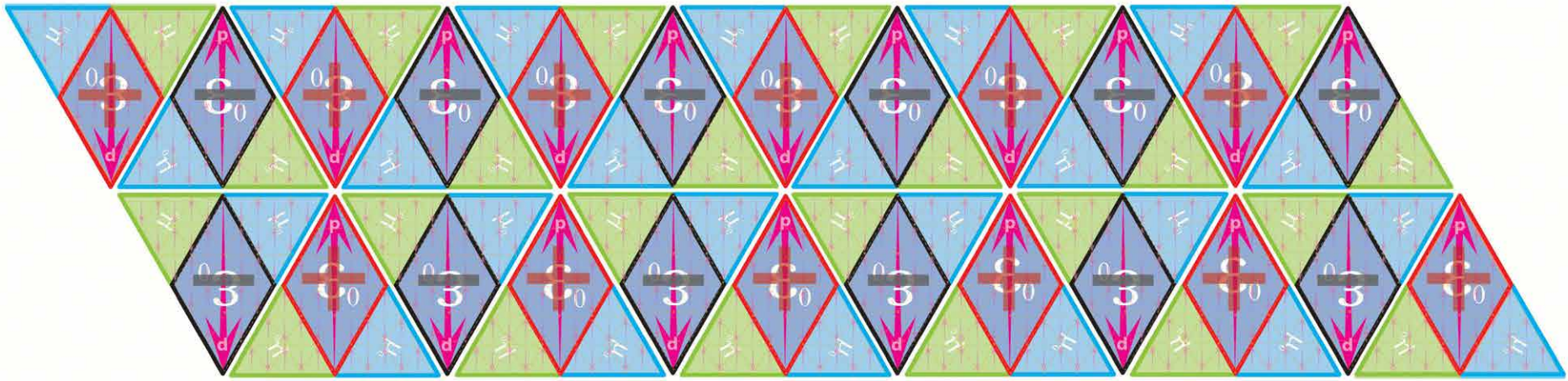
2D radiant EM mass-Energies

n6 - Charged Tetryon Templates



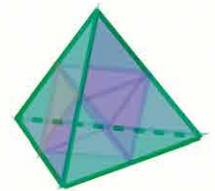
3D standing-wave Matter



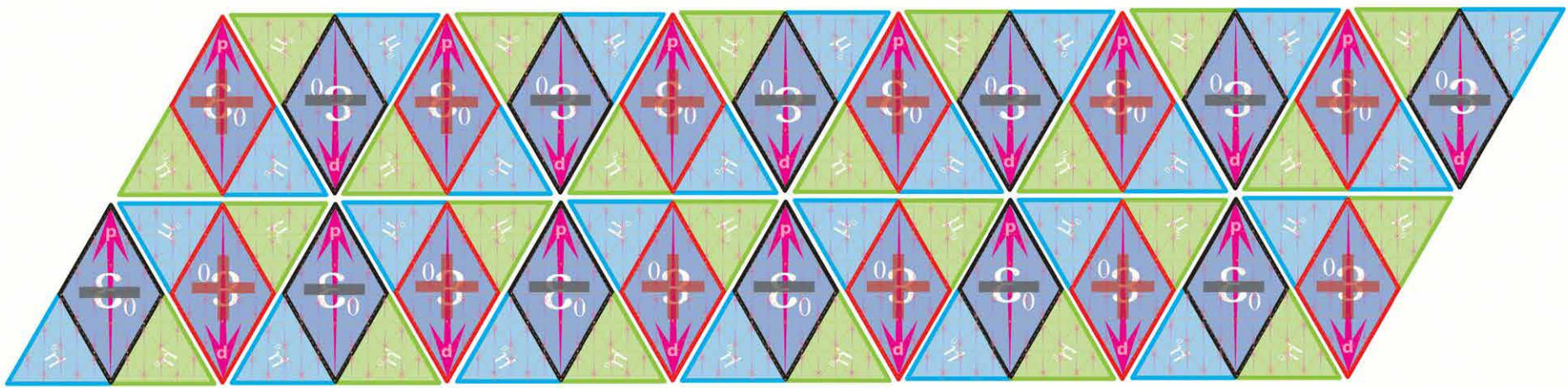


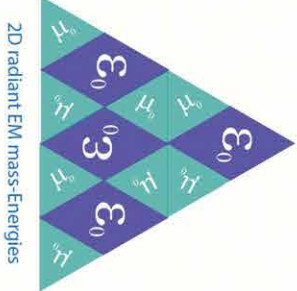
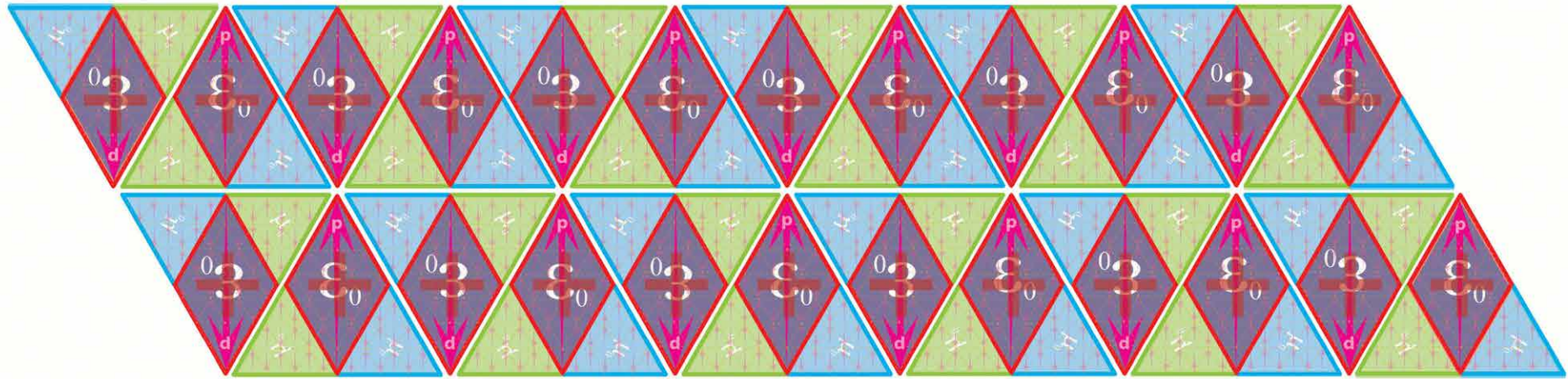
2D radiant EM mass-Energies

n6 - Neutral Tetryon Templates

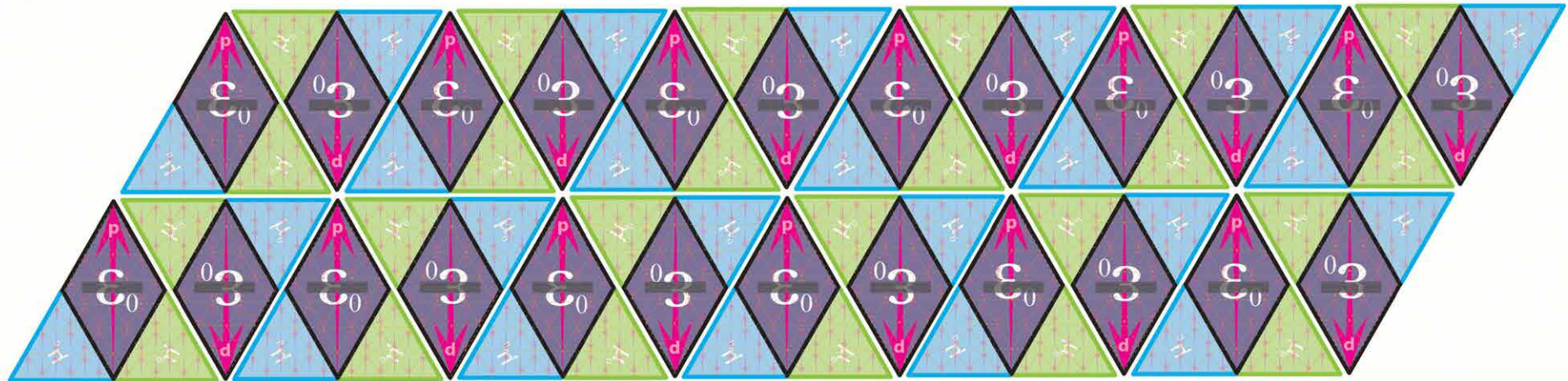
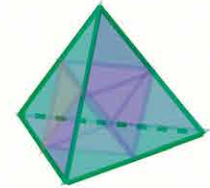


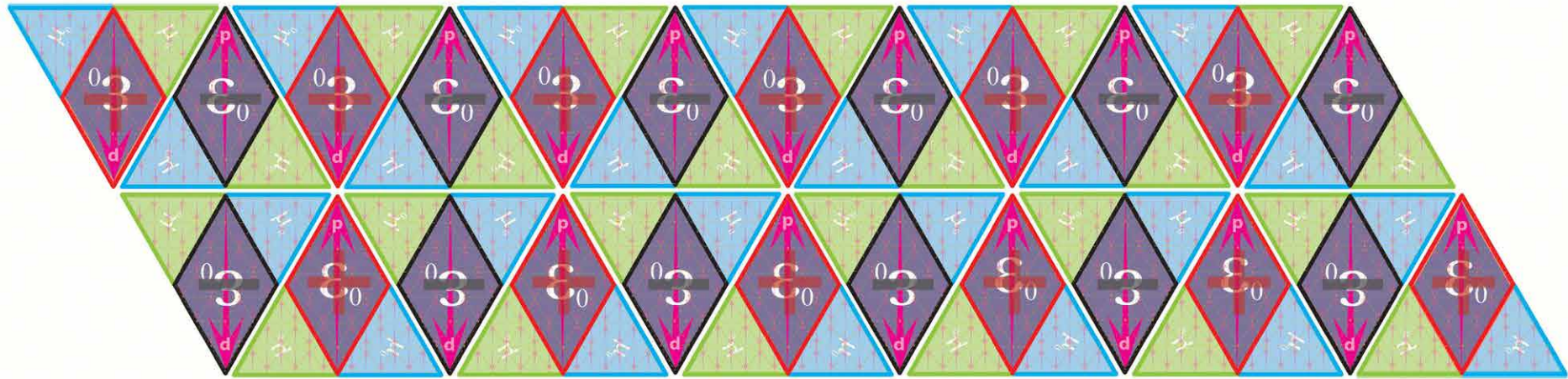
3D standing-wave Matter





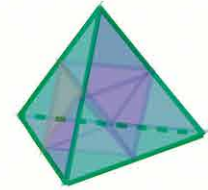
n7 - Charged Tetryon Templates



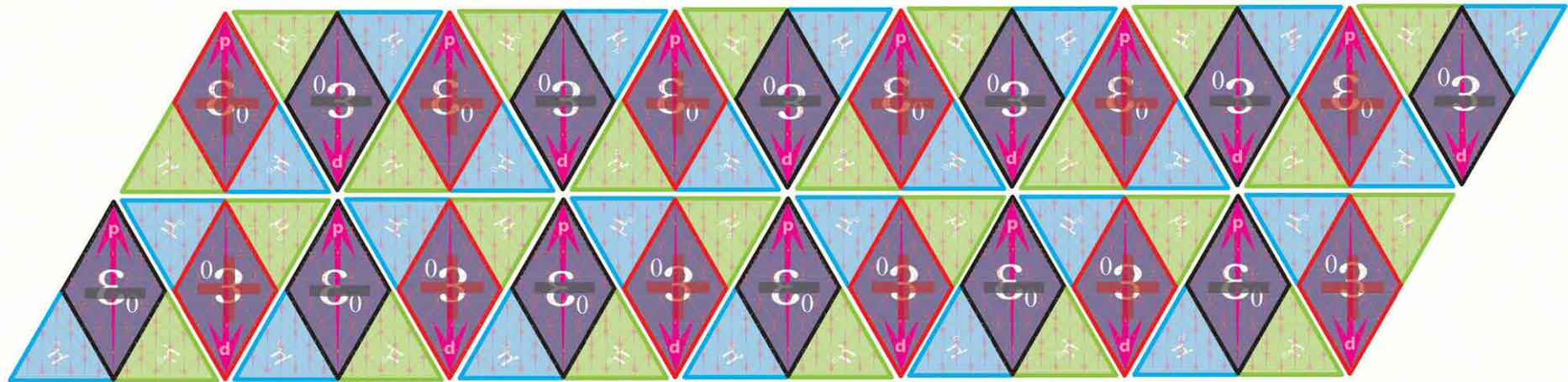


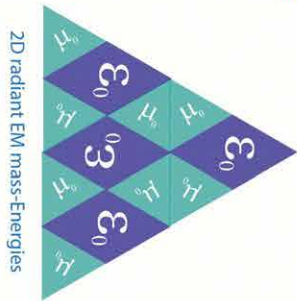
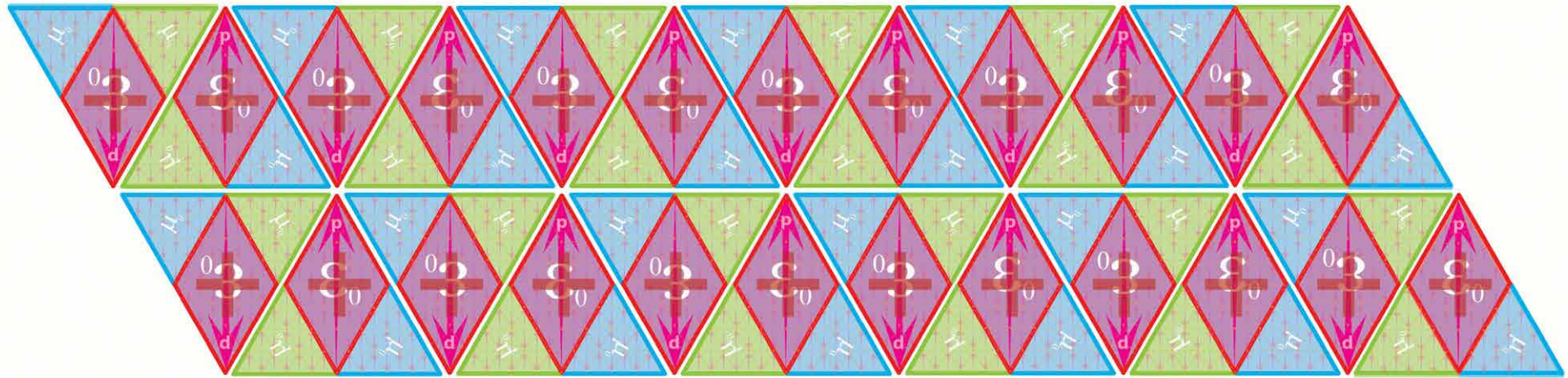
2D radiant EM mass-Energies

n7 - Neutral Tetryon Templates



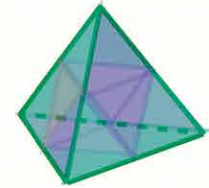
3D standing-wave Matter



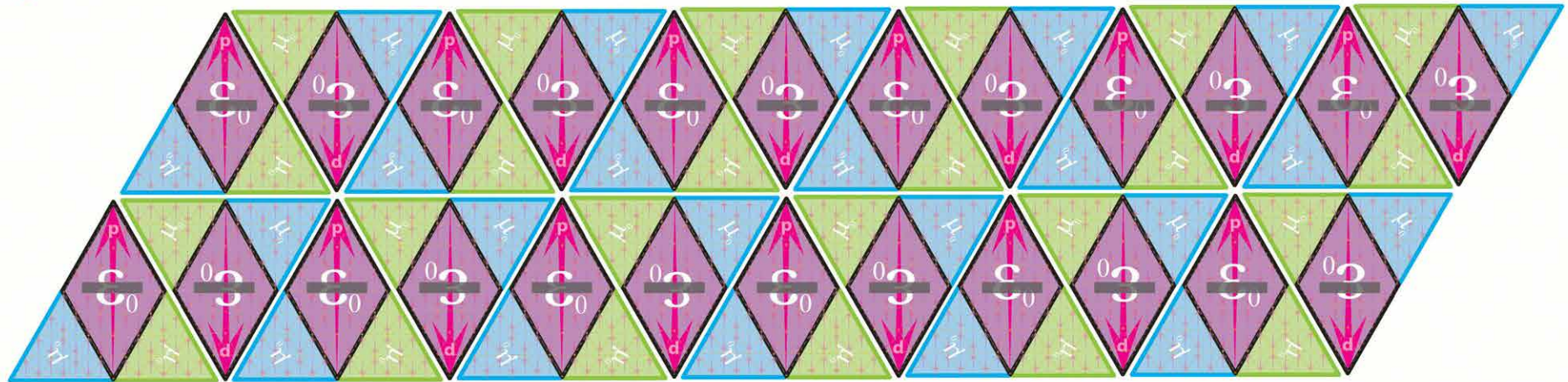


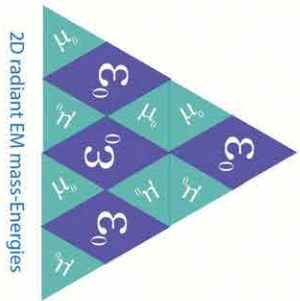
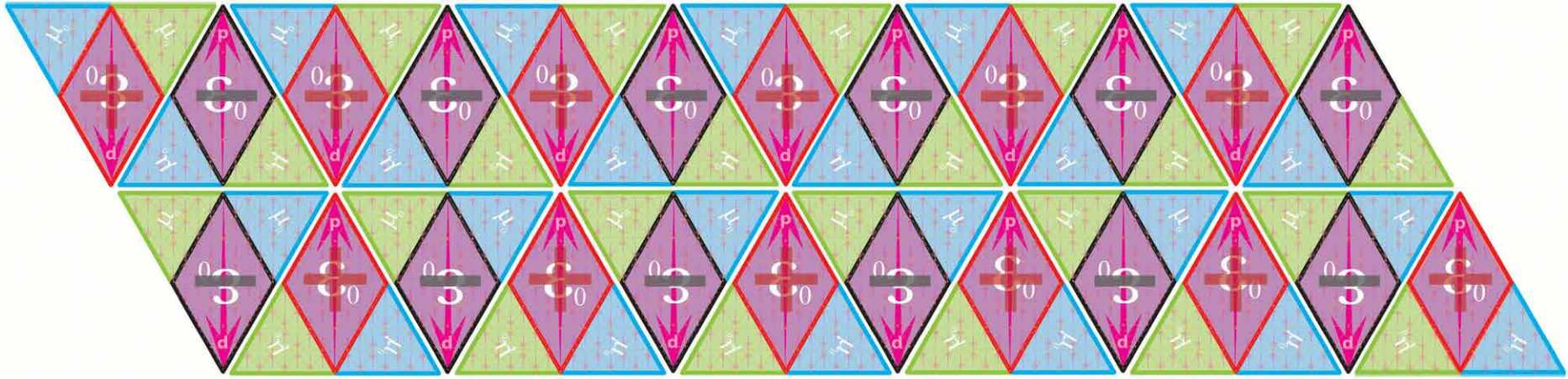
2D radiant EM mass-Energies

n8 - Charged Tetryon Templates

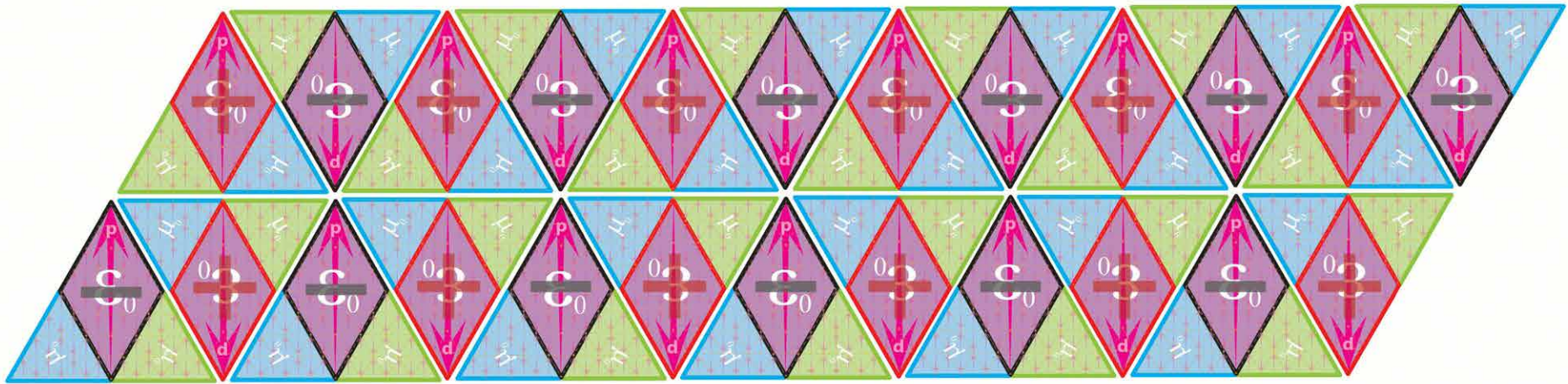
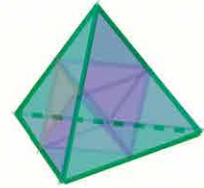


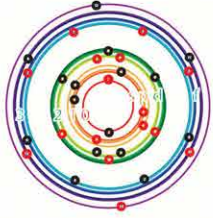
3D standing-wave Matter





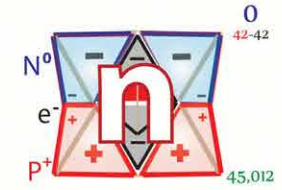
n8 - Neutral Tetryon Templates





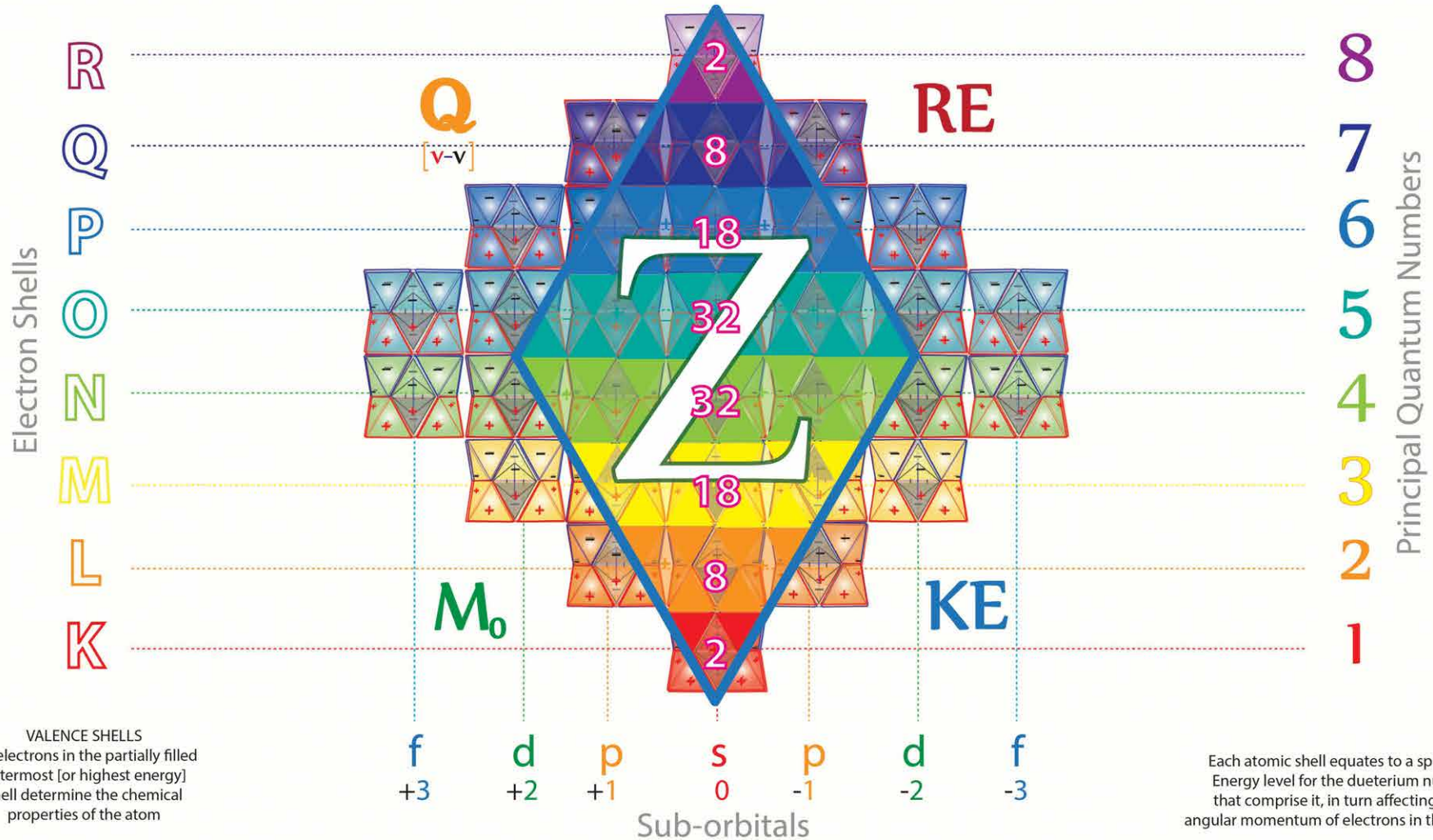
Periodic element geometries

An electron shell may be thought of as an orbit followed by electrons around an atom's nucleus. The closest shell to the nucleus is called the "1 shell" (also called "K shell"), followed by the "2 shell" (or "L shell"), then the "3 shell" (or "M shell"), and so on further and further from the nucleus. The shell letters K, L, M, ... are alphabetical



Each shell can contain only an integer number of whole deuterium nuclei [Proton, Neutron & electron]

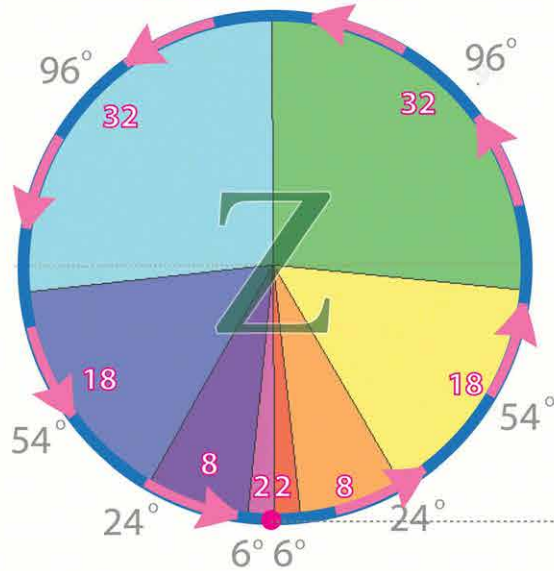
Each shell consists of one or more subshells, and each subshell consists of one or more atomic orbitals.



Periodic Harmonic motions

$$x = A \cos(\omega t + \varphi)$$

Circular motion



circular harmonic motion

Circular motions describe the motion of a body with a changing velocity vector [the result of an acceleration force].

Much of the math in of modern physics is predicated on the assumption that π [where it appears] is related to the properties of a circle

$$P \sum 2(n^2)$$

Simple harmonic motion can be visualized as the projection of uniform circular motion onto one axis

Principal Quantum Numbers

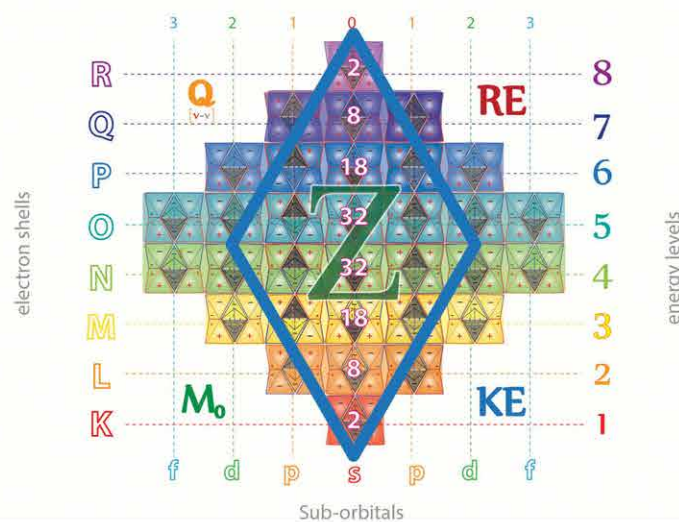
$$F = -kx$$

Linear motion



simple harmonic motion

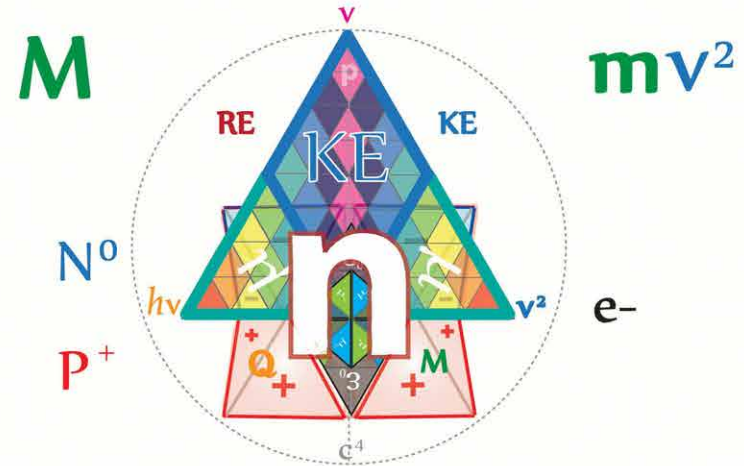
Nuclei per shell in elements follows a 'periodic summation rule' that is reflective of photonic energies





Atomic nuclei mass-energies

Each element's weight [mass-Matter in a gravitational field] is the result of the total quanta comprising that element



The nuclei forming each atomic shell have specific mass-energy quanta

$$\begin{matrix} 8 \\ n \\ 1 \end{matrix} \left[\begin{matrix} \text{Baryon rest masses} & \text{lepton rest mass} & \text{KEM} \\ [72(n)^2] & + [12e19] & + [m_e v^2] \end{matrix} \right]$$

Deuterium mass-energy per shell

Despite having differing mass-energies each Deuterium nuclei has the same velocity invariant Matter geometry [84π]

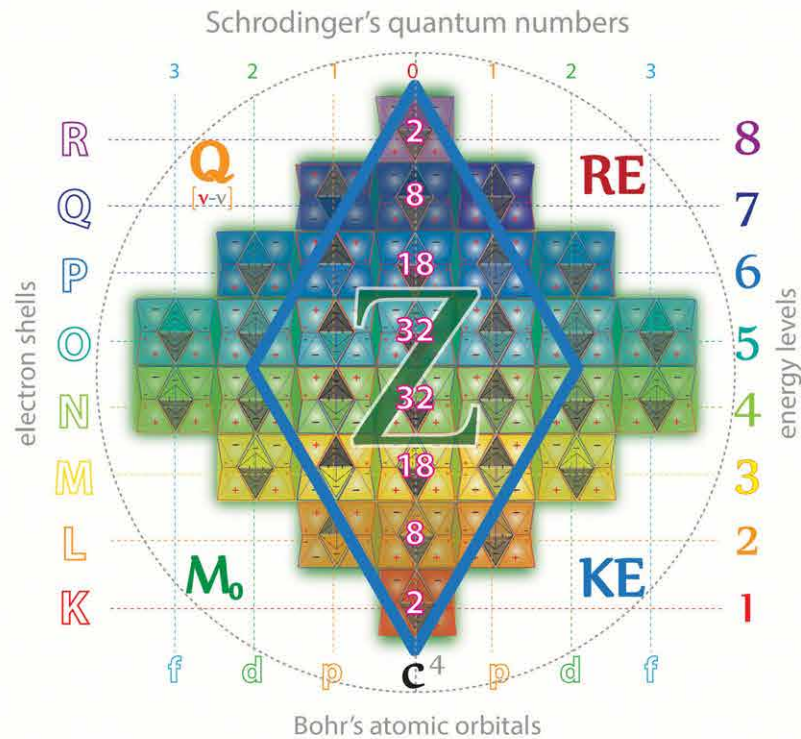
spin orbital coupling in synchronous quantum convertors

Electrons act as quantum scale rotating armatures in atomic nuclei and can only have specific energies reflective of the electron orbital energy level of the Baryons in which they are found

They acheive these energy levels by absorbing or emitting photons to acheive the specific angular momentum required

$$\text{Baryons } 930.947 \text{ MeV} + \text{KEM fields } 13.525 \text{ ev} + \text{electrons } 496.519 \text{ keV}$$

Mapping Planck mass-energy contributions to elementary Matter and isotopes



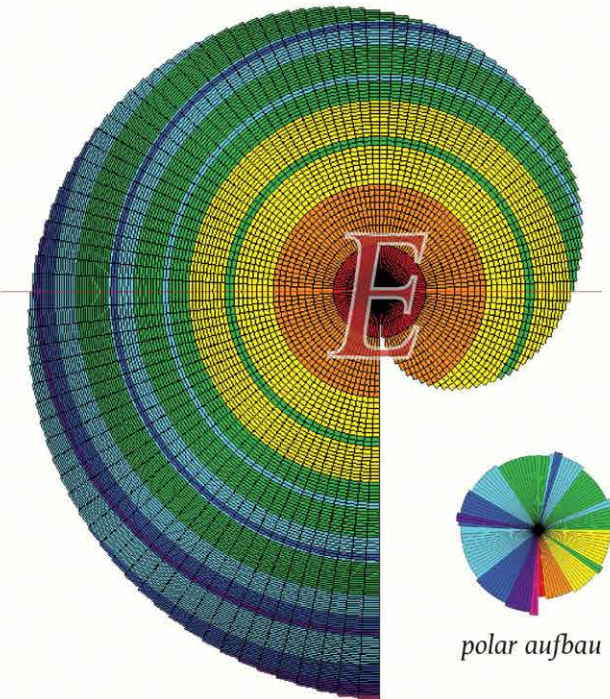
$$E = hv^2$$

$$n^2 + v^2 + e = Z$$

general form quadratic equation

$$ax^2 + bx + c = Z$$

$$E = nhv$$



polar energy spirals courtesy of Rene Cormier

Identifying electron rest Matter topologies as velocity invariant we can re-arrange the component Planck mass-energy geometry formulation of periodic elements to

$$h [72 [v^2]_{\text{Deuteron rest mass}} + v_{\text{Spectral lines}} + 1.20 \text{ e}20 v_{\text{electron rest mass}}]$$

reveal a quadratic formulation for all Z numbers



STEP ONE

Periodic summation follows the atomic shell electron config

$$\begin{matrix}
 1 & R \\
 2 & \\
 3 & \\
 4 & \\
 4 & \\
 3 & \\
 2 & \\
 1 & K
 \end{matrix}
 \Sigma 2(x^2) =$$

Each atomic shell can hold only a fixed number of deuterium nuclei

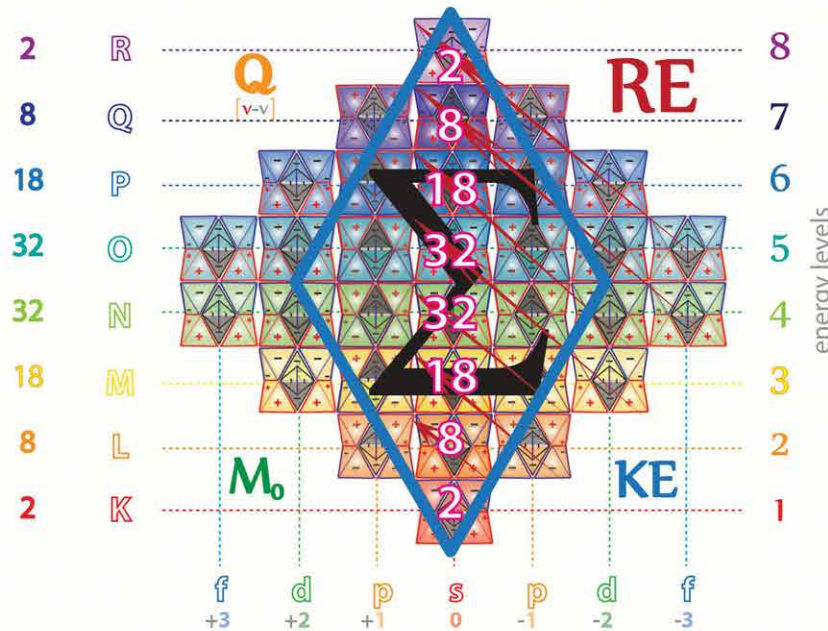
Periodic Summation

Periodic summation is a notation developed for Tetryonic theory to model the geometric series addition of $Z[n^2]$ energy level Deuterium nuclei that form the periodic elements

$$\Sigma Z \begin{matrix} 120 \\ \text{element number} \\ 1 \end{matrix}$$

STEP TWO

Periodic elements build up following the aufbau sequence



$\Sigma R = 2$	2 nuclei [74,496 ea]	120	Unbinilium
$\Sigma Q = 8$	+ 8 nuclei [69,780 ea]	118	Ununoctium
$\Sigma P = 18$	+ 18 nuclei [65,232 ea]	110	Darmstadtium
$\Sigma O = 32$	+ 32 nuclei [60,852 ea]	92	Uranium
$\Sigma N = 32$	+ 32 nuclei [56,640 ea]	60	Neodymium
$\Sigma M = 18$	+ 18 nuclei [52,596 ea]	28	Argon
$\Sigma L = 8$	+ 8 nuclei [48,720 ea]	10	Neon
$\Sigma K = 2$	+ 2 nuclei [45,012 ea]	2	Helium
		0	Hydrogen

The LHS of the notation determine the number of nuclei in each atomic shell, from the periodic mass-energy levels for atoms, and the RHS follows the aufbau building principle to determine the rest mass-Matter of any specific element

Aufbau

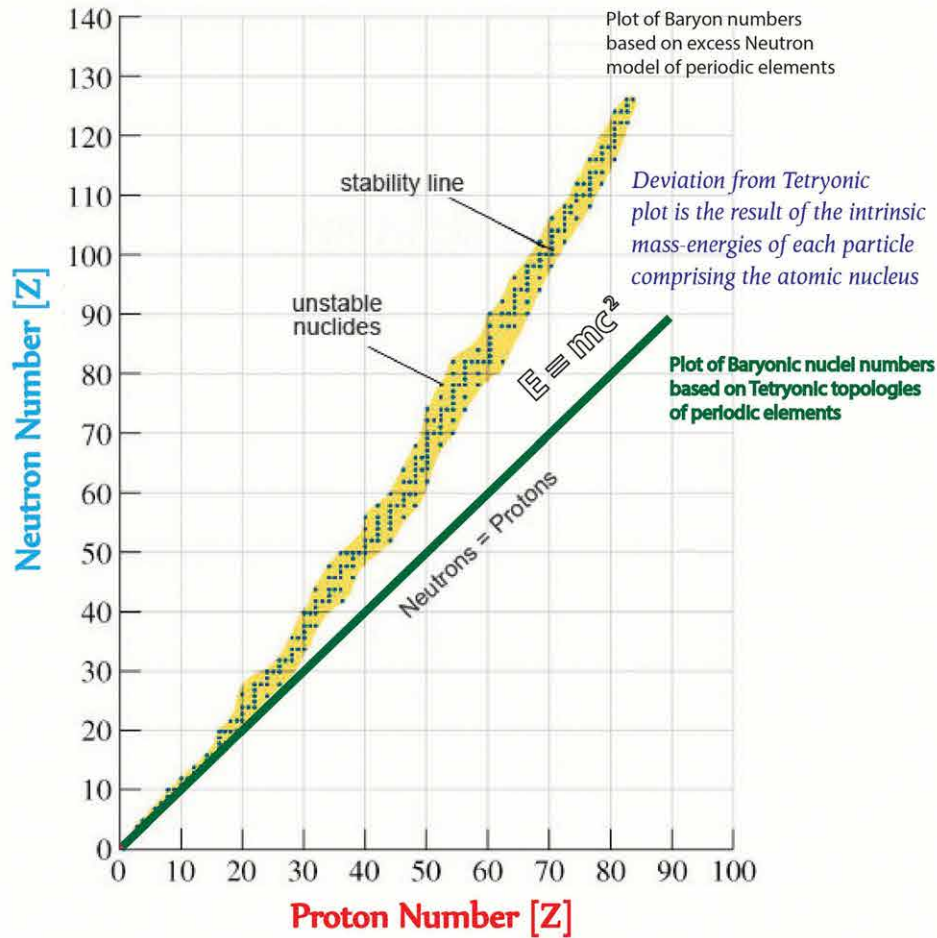
Each periodic element is made of $Z [n^2 \text{ energy}]$ deuterium nuclei

$$Z\# \left[\begin{matrix} z \text{ Protons} & [24-12] \\ z \text{ Neutrons} & [18-18] \\ z \text{ electrons} & [0-12] \end{matrix} \right] n1-8$$

Planck mass-energies form the surface integral of rest Matter topologies for each periodic element

Proton - Neutron Curve

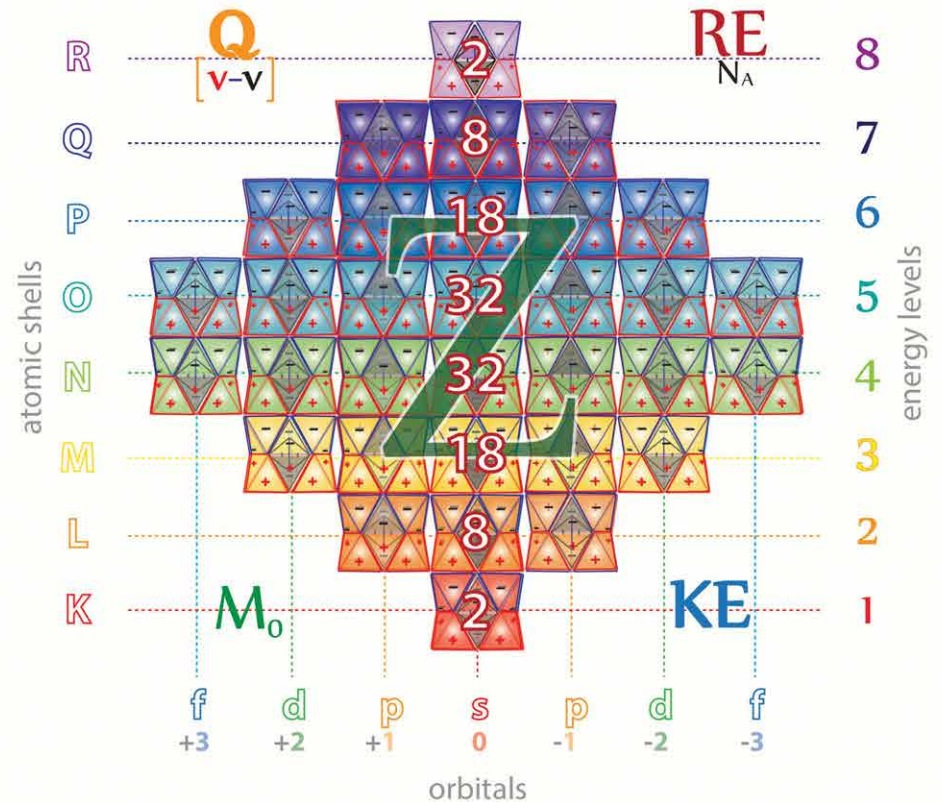
The graph below is a plot of neutron number against proton number. It is used as rule to determine which nuclei are stable or unstable.



Historically, Proton-electron numbers are viewed as being equivalent in neutral elementary matter with the excess molar mass measured being the result of 'excess or extra' Neutrons in the atom

Atomic Nuclei Numbers

All periodic elements have an EQUAL number of Protons, Neutrons & Electrons with their molar mass-Matter being determined by their quantum level mass-energies



Tetryonic modelling of the charged mass-ENERGY-Matter topologies of elementary atoms and the nuclei that comprise them, reveals a DIRECT LINEAR relationship for the number of Protons-electrons-Neutrons in all periodic elements and nuclear isotopes

All elements are comprised of n level Dueterium nuclei

The atomic shell energy levels of Deuterium nuclei in elements



Determines the spectral line [KEM field energies] of electrons bound to them

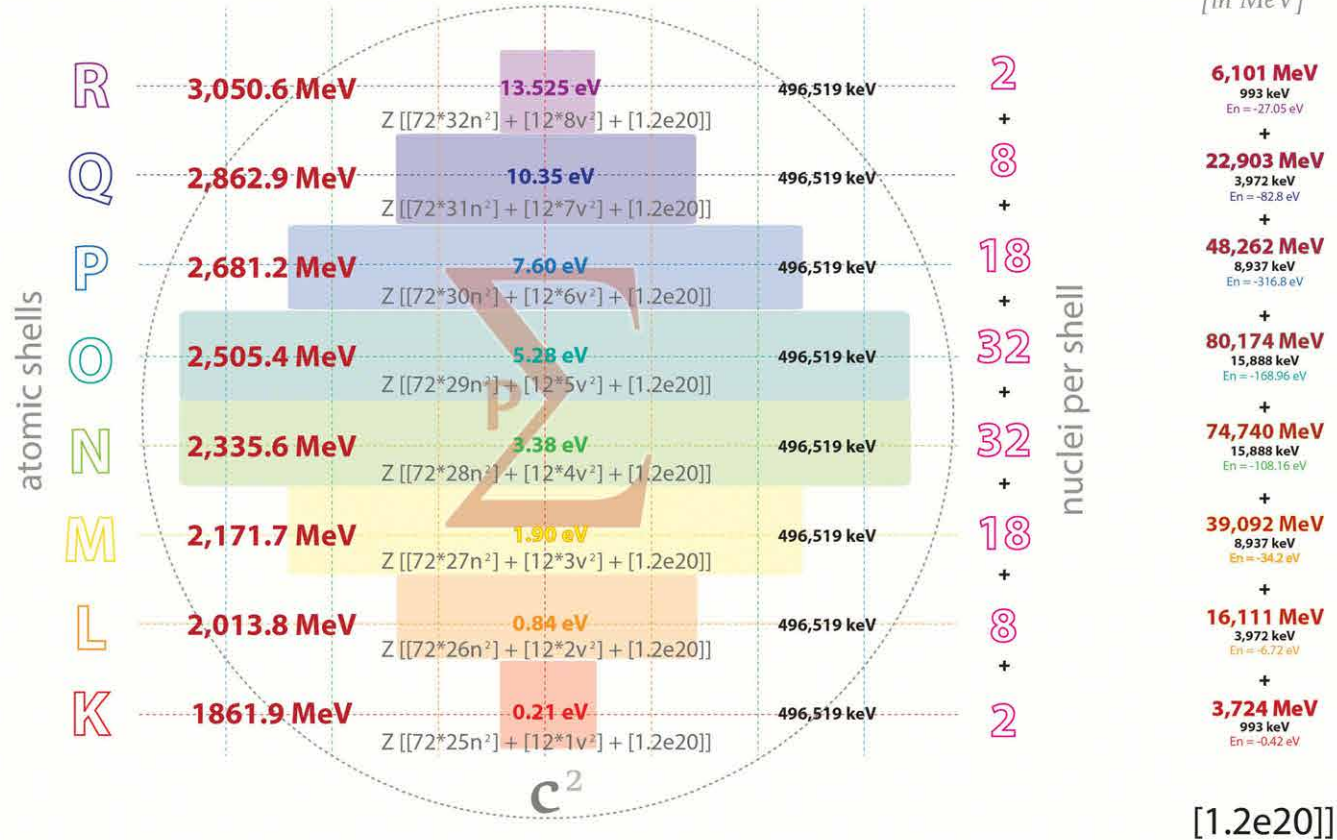
$$Z \text{ [} [72n^2] + [12v^2] + [1.2e20] \text{]}$$

Baryons **KEM fields** **electrons**
 1,861,949 MeV 13.525 eV 496,519 keV

$$2H^+ \quad Z \quad \gamma$$

[72n²] [MeV²]

Elemental mass-Matter [in MeV]

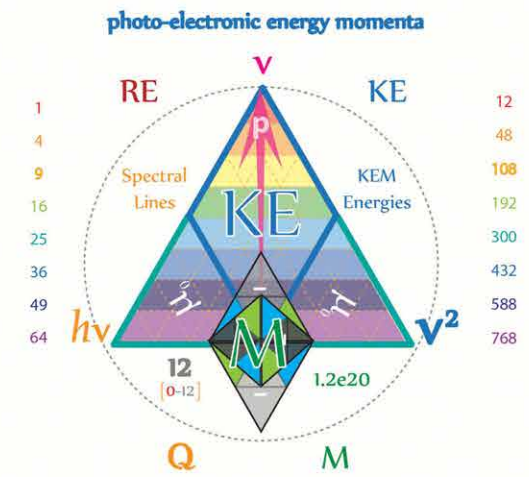
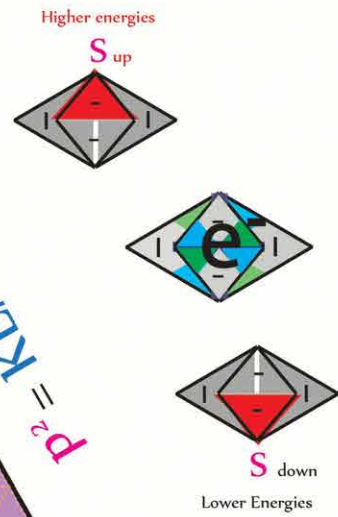
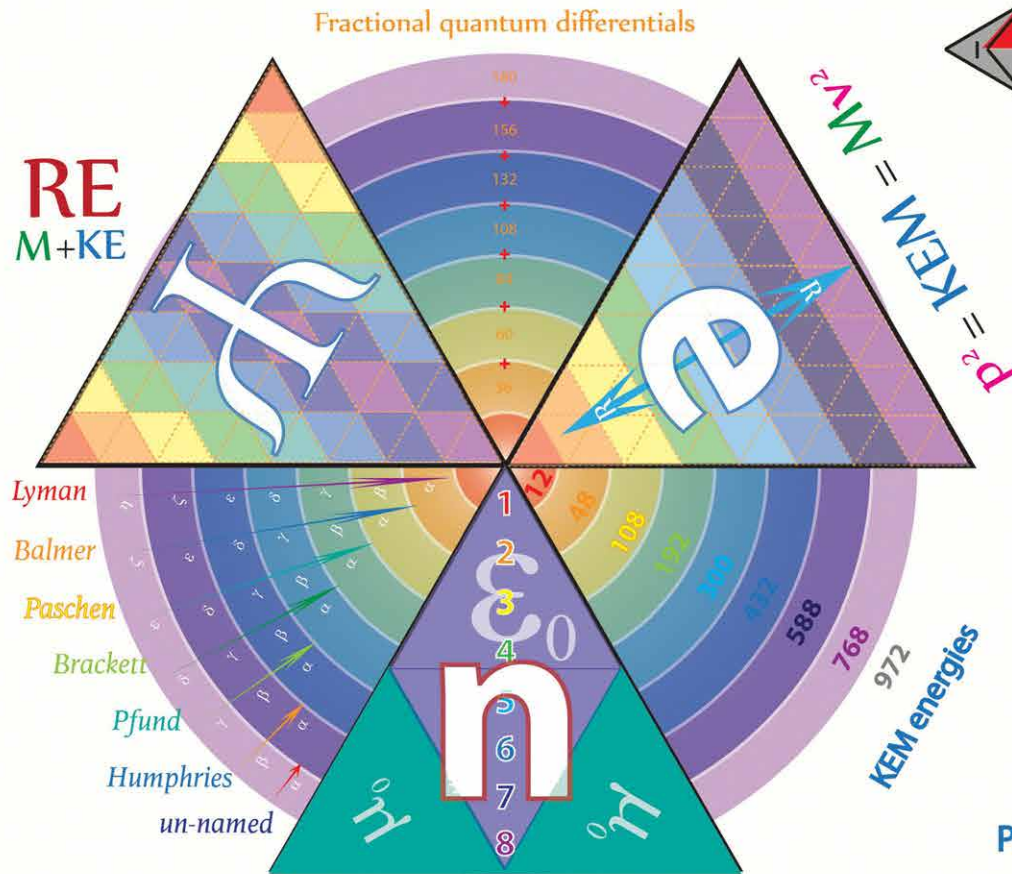


The relativistic rest mass-energy-Matter of all periodic elements

is the sum of the mass-energies of all atomic nuclei and spectral lines that comprise its mass-Matter topology as measured in any spatial co-ordinate system per unit of time

e
the rest mass-Matter of bound photo-electrons is velocity invariant

Ionisation energies



Mapping photo-electron transition energies to Tetryonic energy momenta geometries reveals many key facts about the ionisation energies of nuclei

$$E = -\frac{Z^2 k e^2}{n^2 2a_0} = -\frac{13.6Z^2}{n^2} eV$$

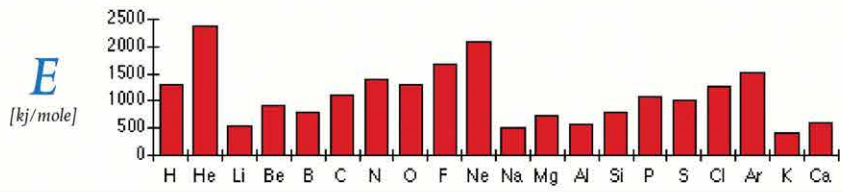
The differing fractional KEM field energy momenta of electrons that results from their transitions to specific energy nuclei in elements results in differing QAM quanta and produces spectral lines and fine line splitting

Photo-electrons absorb/emit spectral energies

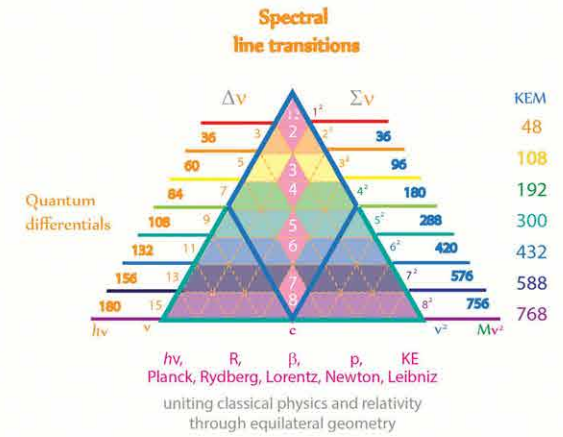
$$hf = \Delta Mv = \Delta p$$

spectral lines are produced by accelerating electrons

Note: this is an Illustrative schema for modelling KEM field energies
All KEM fields possess the same physical spatial geometry in radial-time defined spatial co-ordinate systems



$$E = eV = \frac{1}{4\pi\epsilon_0} \frac{ne^2}{a}$$



Element numbers

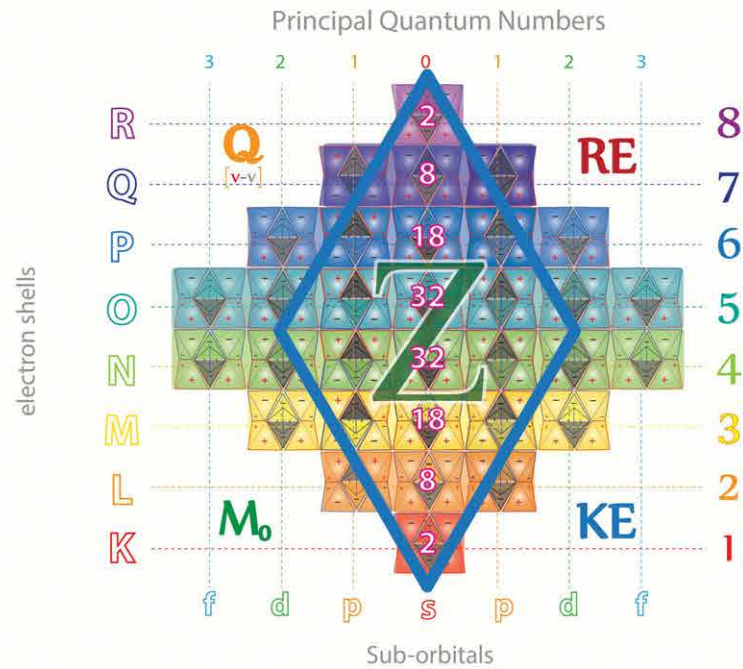
Nuclei per shell in elements follow a 'periodic summation rule' that is reflective of photonic energies

$$\sum_{K=1}^R P 2(x^2) = 2 + 8 + 18 + 32 + 32 + 18 + 8 + 2$$

Z

- 120 Unbinilium
- 119 Ununennium
- 118 Ununoctium
- 87 Francium
- 112 Copernicium
- 55 Caesium
- 102 Nobelium
- 37 Rubidium
- 70 Ytterbium
- 19 Potassium
- 30 Zinc
- 11 Sodium
- 10 Neon
- 3 Lithium
- 2 Helium
- 1 Deuterium

Hydrogen 0



Periodic mass-ENERGY-Matter

Following periodic summation rules for shell filling n[1-8] quantum energy deuterium nuclei combine to form elementary Matter

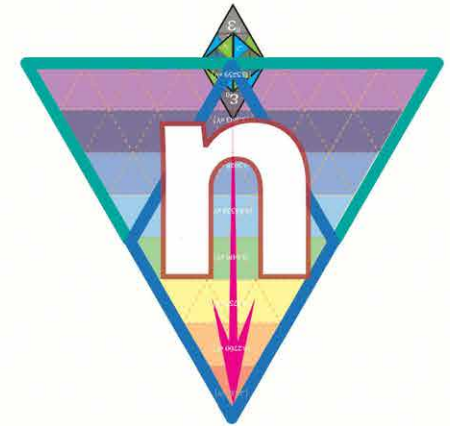
$$\sum_{K=1}^R P \sum_{25}^{32} \left[\begin{matrix} \text{Baryon rest masses} & \text{lepton rest mass} & \text{KEM} \\ [72(n)^2] & + [12e19] & + [m_e v^2] \end{matrix} \right]_1^8$$

Deuterium mass-energy per shell

The measured weight of Matter in gravitational fields is the result of planar mass-energies in tetryonic standing-wave geometries

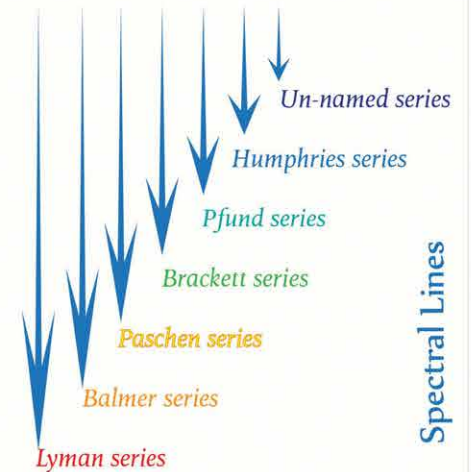
The periodicity of all the elements, along with their exact molar rest mass-energies and quantum wavefunctions can be described with Tetryonic geometries

Ionisation energies



energy levels

γ



Spectral Lines

$$Mv^2 = KEM = hcR_H$$

Photon emission/absorption

Spectral line differentials

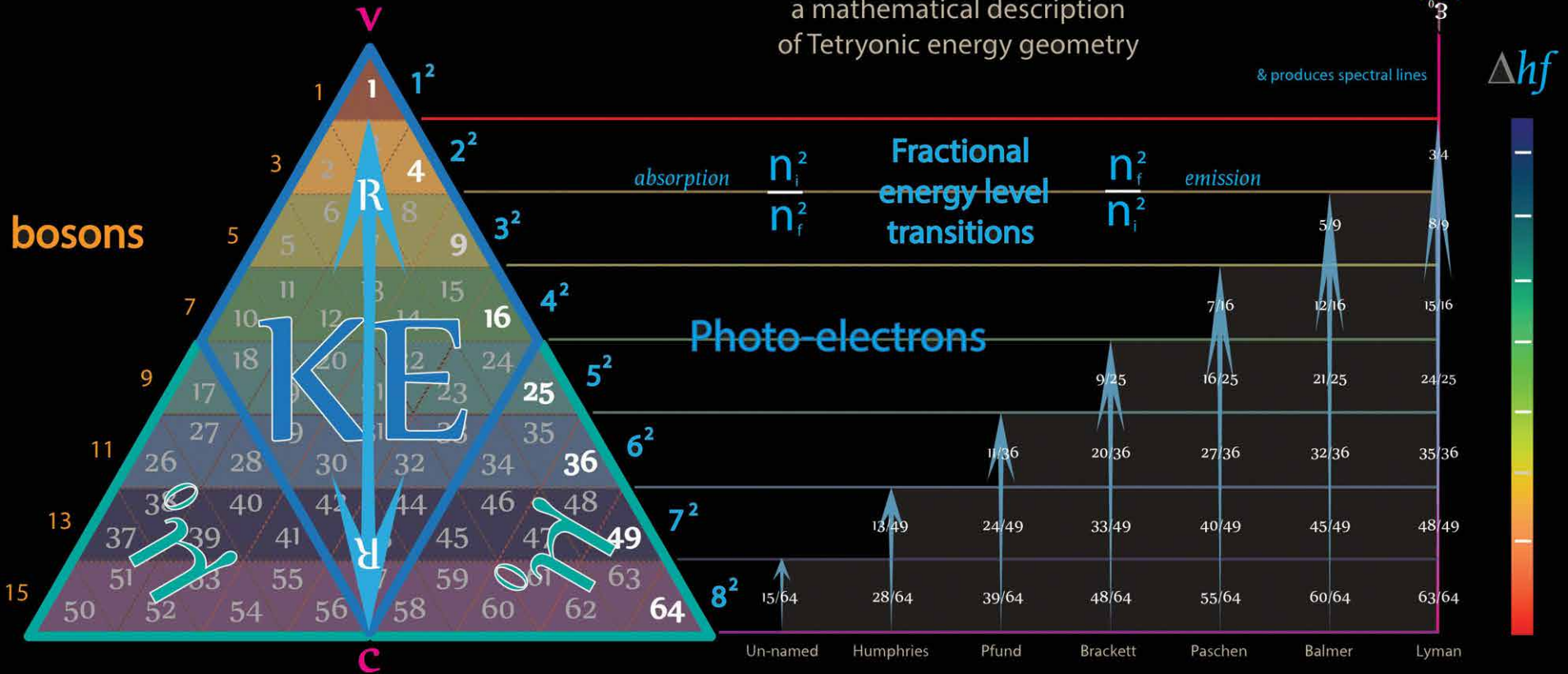
$$\Delta hv = \Delta Mv = \Delta p$$

changes to energy momenta

accelerate photo-electrons

$$\frac{1}{\lambda} = \frac{R_H}{hc} \left(\frac{1}{n_1^2} - \frac{1}{n_2^2} \right)$$

Ryberg's formula is a mathematical description of Tetryonic energy geometry



Ryberg's constant reflects the changing energy momentum of a transitioning electron

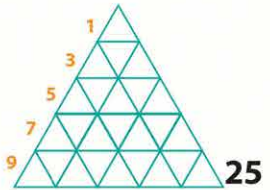
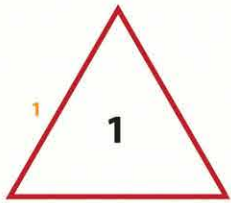
$$Mv^2 = KEM = hcR$$

All of the transitions of photo-electrons bound to Hydrogen atoms can now be revealed in the fractional geometry of KEM field energies

KEM field energies

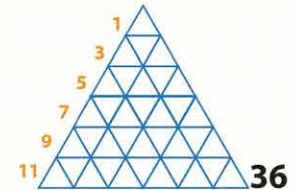
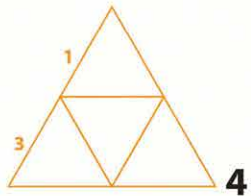
Fermat's method of Factoring

also known as 'the difference of two squares' is used to factorise large numbers



$$[x-y] \cdot [x+y]$$

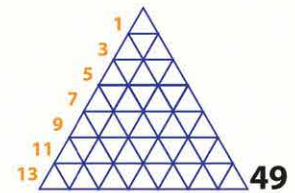
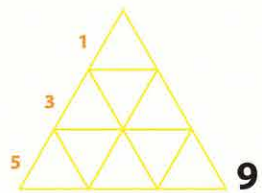
$$x^2 - y^2$$



All spectral lines transitions are an example of

Fermat's difference of two squares in action at the quantum level

leading in turn to Ryberg's formula

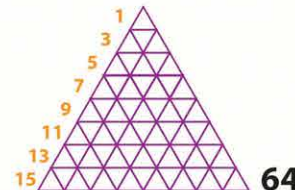
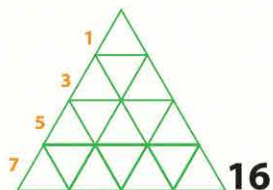


$$[x-y]$$

$$[x+y]$$

$$y^2$$

$$x^2$$



Fermat knew that every odd number could be written as the difference of two squares or as revealed geometrically through Tetronic theory's equilateral geometry, every 'SQUARE' number is the sequential sum of ODD numbers

Fractions

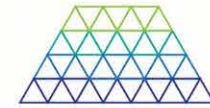
A fraction is a number that shows how many equal parts there are

In quantum mechanics fractions appear in quantum steps as a result of the equilateral geometry of Planck energy momenta

3/4



40/49



24/25



48/64



80/81

.987654321

$$\frac{1}{\lambda} = R \left(\frac{1}{1} - \frac{1}{81} \right)$$

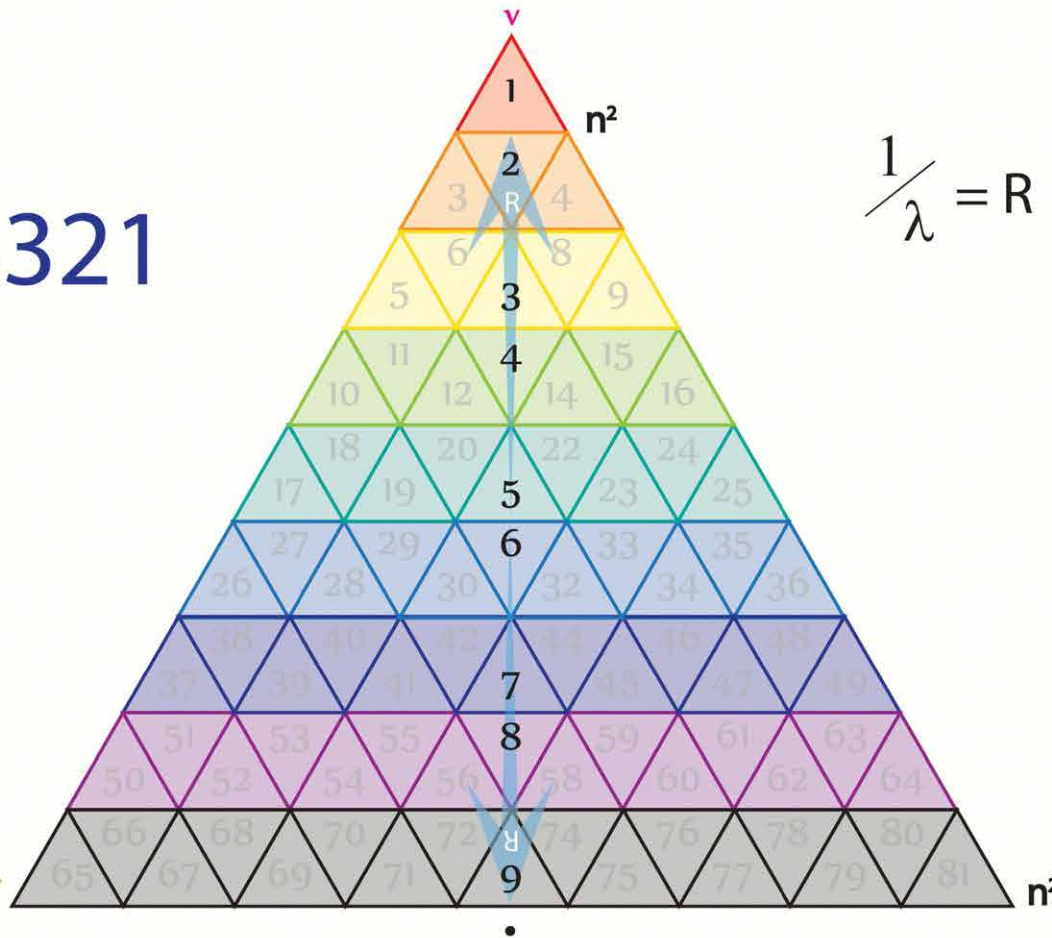
.987654321

Cos 60

.5

1/2

$h\nu$



Sin 60

.866025403

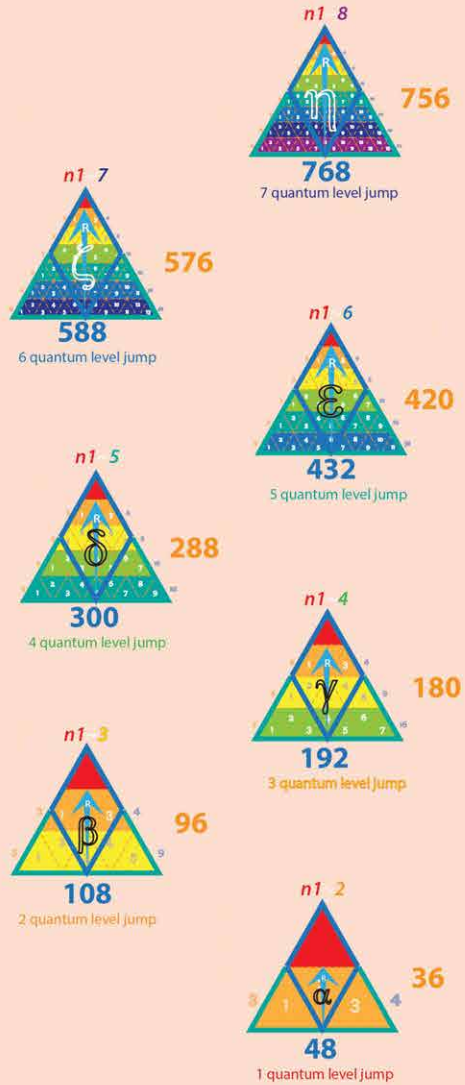
$\sqrt{3/2}$

Tetryonic geometry explains the fractional mathematics of Rydberg's formula

Lyman spectral transitions

$$\Delta h\nu = \text{Planck} = \text{KEM} = \text{Rydberg} = hcR$$

13.525 eV



Wavelength (nm)	Quantum Level	Transition	Wavelength (nm)	Quantum Level	Transition
180	15	[n1-8]	756	[n8-1]	15
156	13	[n1-7]	576	[n7-1]	13
132	11	[n1-6]	420	[n6-1]	11
108	9	[n1-5]	288	[n5-1]	9
84	7	[n1-4]	180	[n4-1]	7
60	5	[n1-3]	96	[n3-1]	5
36	3	[n1-2]	36	[n2-1]	3

63/64	.9843
48/49	.9795
35/36	.9722
24/25	.9600
15/16	.9375
8/9	.8888
3/4	.7500

λ	94.17075598 nm
$\tilde{\nu}$	10,732,981.5 m ⁻¹
f	$3.217666905 \times 10^{15}$ Hz
E	13.31395504 eV
ϵ	$-7.03188095 \text{ m}^2/\text{s}$

$$R\left(\frac{1}{1} - \frac{1}{64}\right)$$

.984375

$$R\left(\frac{1}{1} - \frac{1}{49}\right)$$

.9795

$$R\left(\frac{1}{1} - \frac{1}{36}\right)$$

.9722

$$R\left(\frac{1}{1} - \frac{1}{25}\right)$$

.96

$$R\left(\frac{1}{1} - \frac{1}{16}\right)$$

.9375

$$R\left(\frac{1}{1} - \frac{1}{9}\right)$$

.8888

$$R\left(\frac{1}{1} - \frac{1}{4}\right)$$

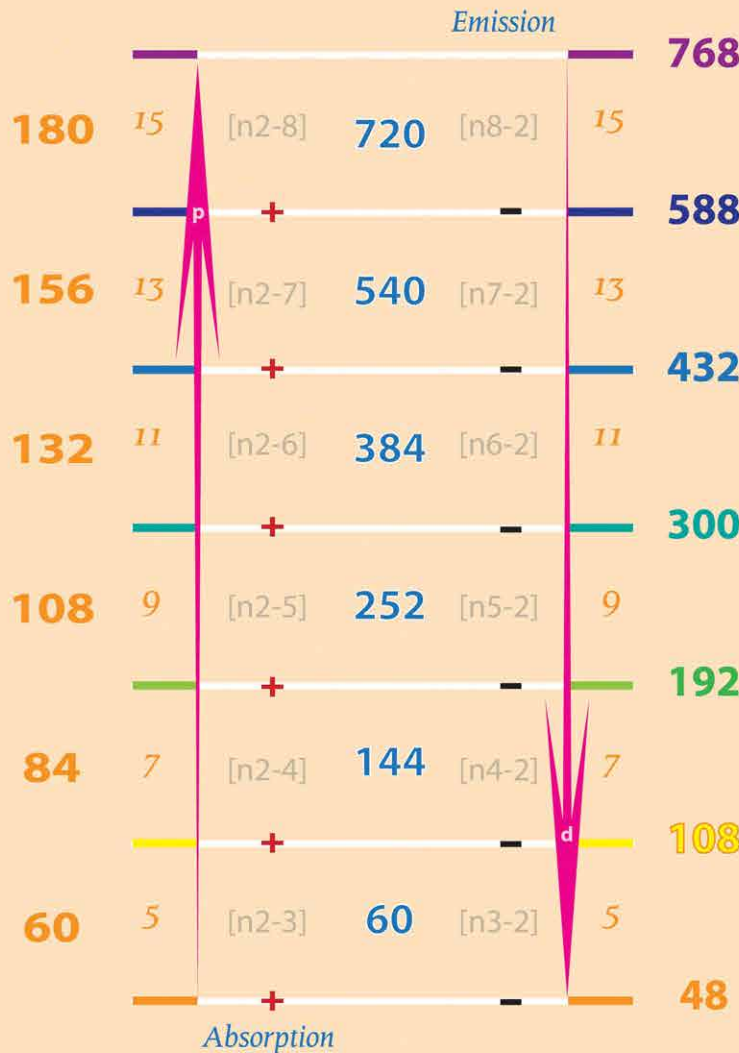
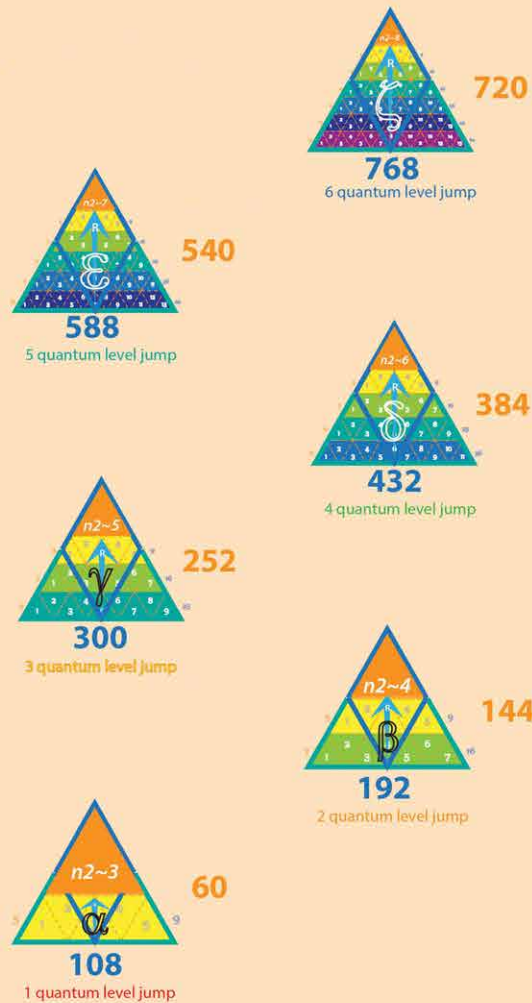
.75

$$\Delta Mv^2$$

Balmer spectral transitions

$$\Delta h\nu = \text{KEM} = hcR$$

Planck 3.381 eV Rydberg



60/64
.2343

λ	391.3171751	nm
$\bar{\nu}$	2.5554711785	m ⁻¹
f	$7.66111677 \times 10^{14}$	Hz
E	3.169989296	eV
σ	103.1079531	m ⁻¹

$$R \left(\frac{1}{4} - \frac{1}{64} \right)$$

.2343

45/49
.2295

λ	399.4696163	nm
$\bar{\nu}$	2.5033319299	m ⁻¹
f	$7.50476246 \times 10^{14}$	Hz
E	3.105295637	eV
σ	101.0057092	m ⁻¹

$$R \left(\frac{1}{4} - \frac{1}{49} \right)$$

.2295

32/36
.2222

λ	412.7173331	nm
$\bar{\nu}$	2.422065384	m ⁻¹
f	$7.26386885 \times 10^{14}$	Hz
E	3.00561948	eV
σ	97.78161483	m ⁻¹

$$R \left(\frac{1}{4} - \frac{1}{36} \right)$$

.2222

21/25
.2100

λ	436.7379187	nm
$\bar{\nu}$	2.289702719	m ⁻¹
f	$6.864356063 \times 10^{14}$	Hz
E	2.840310409	eV
σ	83.38429601	m ⁻¹

$$R \left(\frac{1}{4} - \frac{1}{25} \right)$$

.21

12/16
.1875

λ	489.1464689	nm
$\bar{\nu}$	2.044377428	m ⁻¹
f	$6.128889342 \times 10^{14}$	Hz
E	2.535991437	eV
σ	82.48616251	m ⁻¹

$$R \left(\frac{1}{4} - \frac{1}{16} \right)$$

.1875

5/9
.138

λ	660.247733	nm
$\bar{\nu}$	1.51435365	m ⁻¹
f	$4.539918031 \times 10^{14}$	Hz
E	1.878512175	eV
σ	61.10100927	m ⁻¹

$$R \left(\frac{1}{4} - \frac{1}{9} \right)$$

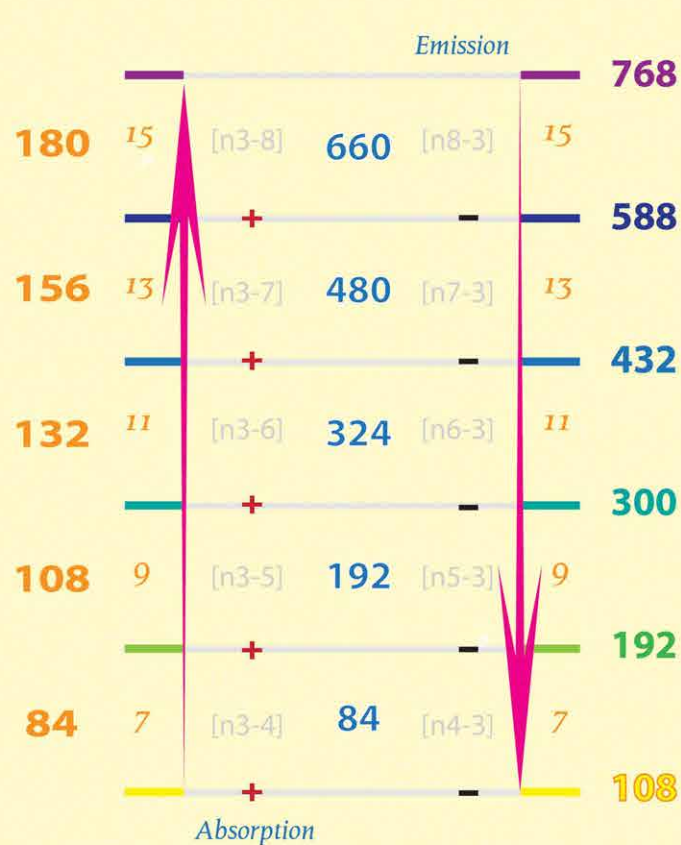
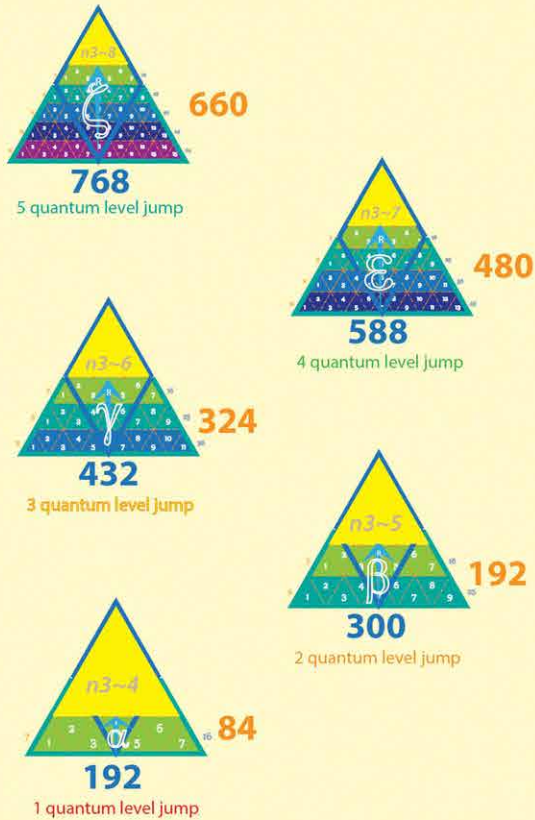
.138

$$\Delta Mv^2$$

Paschen spectral transitions

$$\Delta h\nu = \text{KEM} = hcR$$

Planck 1.502 eV Rydberg



55/64
.0954

40/49
.0907

27/36
.8033

16/25
.0711

7/16
.0486

λ	960.3057935	nm
$\tilde{\nu}$	1.041,118.135	m ⁻¹
f	3.121193646 x 10 ¹⁴	Hz
E	1.29147712	eV
Ω	287.9523928	m ² /s

$$R \left(\frac{1}{9} - \frac{1}{64} \right)$$

.09548

λ	1,011.157466	nm
$\tilde{\nu}$	988.965.6492	m ⁻¹
f	2.9464844428 x 10 ¹⁴	Hz
E	1.226783461	eV
Ω	303.1323822	m ² /s

$$R \left(\frac{1}{9} - \frac{1}{49} \right)$$

.0907

λ	1,100.579555	nm
$\tilde{\nu}$	908.612.1902	m ⁻¹
f	2.723950819 x 10 ¹⁴	Hz
E	1.127107305	eV
Ω	329.94545	m ² /s

$$R \left(\frac{1}{9} - \frac{1}{36} \right)$$

.0833

λ	1,289.741666	nm
$\tilde{\nu}$	775.349.069	m ⁻¹
f	2.324438032 x 10 ¹⁴	Hz
E	0.961798233	eV
Ω	386.6548243	m ² /s

$$R \left(\frac{1}{9} - \frac{1}{25} \right)$$

.0711

λ	1,886.707809	nm
$\tilde{\nu}$	530,023.7776	m ⁻¹
f	1.588971311 x 10 ¹⁴	Hz
E	0.657479261	eV
Ω	565.6207715	m ² /s

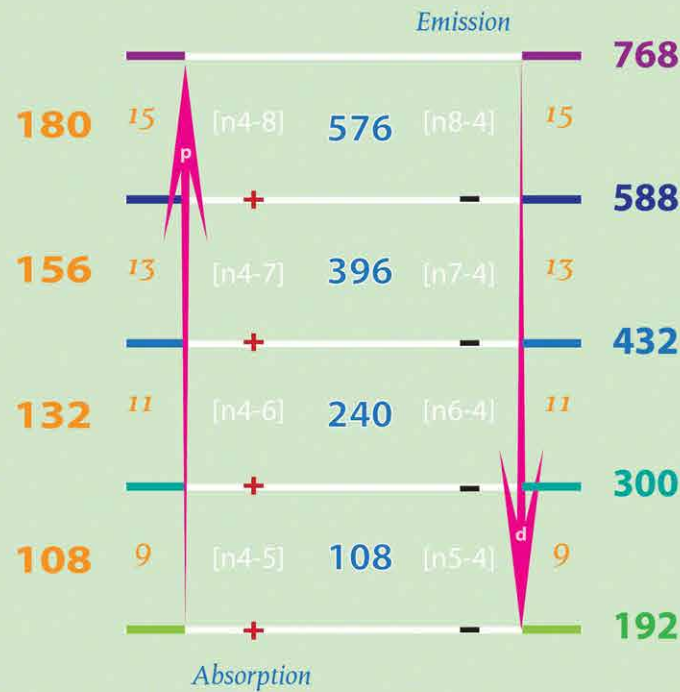
$$R \left(\frac{1}{9} - \frac{1}{16} \right)$$

.0486

$$\Delta Mv^2$$

Brackett spectral transitions

$$\underset{\text{Planck}}{\Delta h\nu} = \underset{0.8451 \text{ eV}}{\text{KEM}} = \underset{\text{Rydberg}}{hcR}$$



48/64
.0468

λ	1.956585876	nm
$\tilde{\nu}$	511,094.357	m ⁻¹
f	1.532222335 x 10 ¹⁴	Hz
E	0.634001085	eV
Ω	586.509689	m ² /s

$$R \left(\frac{1}{16} - \frac{1}{64} \right)$$

33/49
.04209

λ	2.17892518	nm
$\tilde{\nu}$	458,941.8716	m ⁻¹
f	1.375873118 x 10 ¹⁴	Hz
E	0.569307096	eV
Ω	653.2253334	m ² /s

$$R \left(\frac{1}{16} - \frac{1}{49} \right)$$

20/36
.0347

λ	2.641390932	nm
$\tilde{\nu}$	378,588.4126	m ⁻¹
f	1.134979508 x 10 ¹⁴	Hz
E	0.469630433	eV
Ω	391.8690801	m ² /s

$$R \left(\frac{1}{16} - \frac{1}{36} \right)$$

9/25
.0225

λ	4.076220574	nm
$\tilde{\nu}$	245,325.2914	m ⁻¹
f	7.35466721 x 10 ¹³	Hz
E	0.30432052	eV
Ω	1.222020185	m ² /s

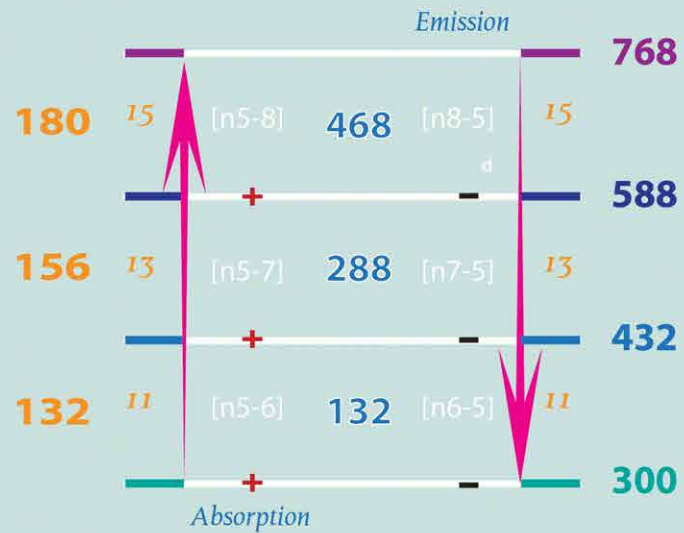
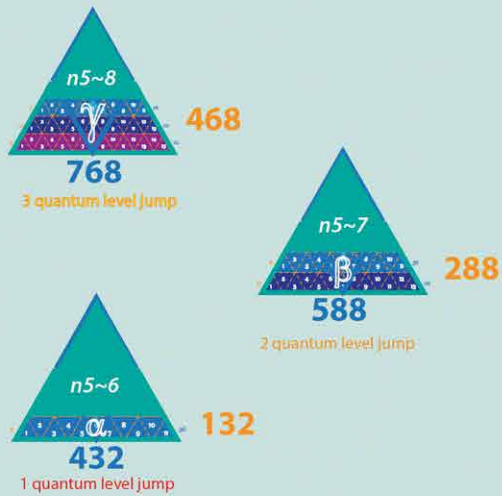
$$R \left(\frac{1}{16} - \frac{1}{25} \right)$$

$$\Delta Mv^2$$

Pfund spectral transitions

$$\Delta h\nu = KEM = hcR$$

Planck P 0.541 eV Rydberg



39/64
.0243

λ	3,762,665,146	nm
$\tilde{\nu}$	265,769,0656	m ⁻¹
f	$7.967556145 \times 10^{13}$	Hz
E	0.329678886	eV
Ω	1.128,018633	m ² /s

$$R \left(\frac{1}{25} - \frac{1}{64} \right)$$

.0243

24/49
.0195

λ	4,681,284,566	nm
$\tilde{\nu}$	213,616,5802	m ⁻¹
f	$6.404063965 \times 10^{13}$	Hz
E	0.264985227	eV
Ω	1,403,413807	m ² /s

$$R \left(\frac{1}{25} - \frac{1}{49} \right)$$

.01959

11/36
.0122

λ	7,503,951,512	nm
$\tilde{\nu}$	133,263,1212	m ⁻¹
f	$3.995127867 \times 10^{13}$	Hz
E	0.165309071	eV
Ω	2,249,628068	m ² /s

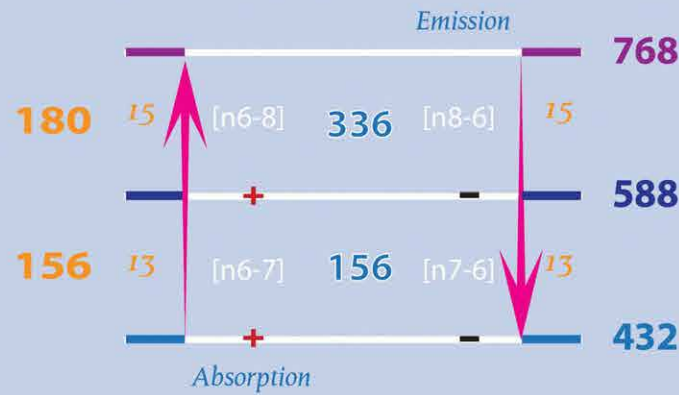
$$R \left(\frac{1}{25} - \frac{1}{36} \right)$$

.0122

$$\Delta Mv^2$$

Humphreys spectral transitions

$$\Delta h\nu \underset{\text{Planck}}{=} \underset{0.375 \text{ eV}}{\text{KEM}} = \underset{\text{Rydberg}}{hcR}$$

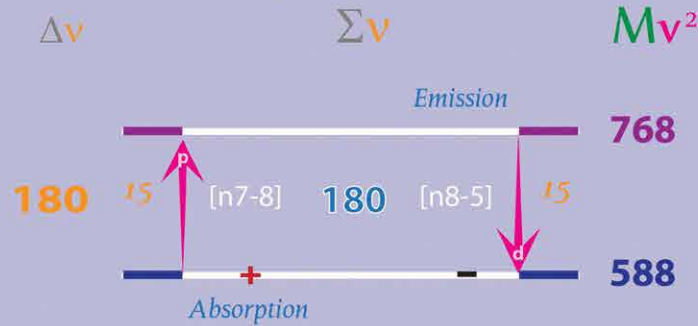
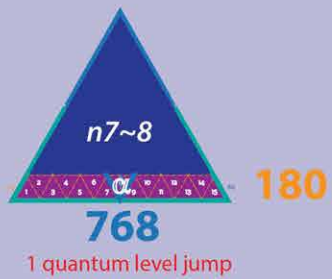


$28/64$	λ 7,546.831235 nm	$R \left(\frac{1}{36} - \frac{1}{64} \right)$.01215
$.01215$	$\tilde{\nu}$ 132,505.9444 m ⁻¹	
	f 3.972428277 x 10 ¹³ Hz	
	E 0.164369815 eV	
	Ω 1.128.018633 m ² /s	
$13/49$	λ 12,445.01497 nm	$R \left(\frac{1}{36} - \frac{1}{49} \right)$.0073
$.00733$	$\tilde{\nu}$ 80,353.459 m ⁻¹	
	f 2.4089936098x 10 ¹³ Hz	
	E 0.099676156 eV	
	Ω 1.403.413807 m ² /s	

$$\Delta Mv^2$$

Un-named spectral transition

$$\underset{\text{Planck}}{\Delta h\nu} = \underset{0.276 \text{ eV}}{\text{KEM}} = \underset{\text{Rydberg}}{hcR}$$



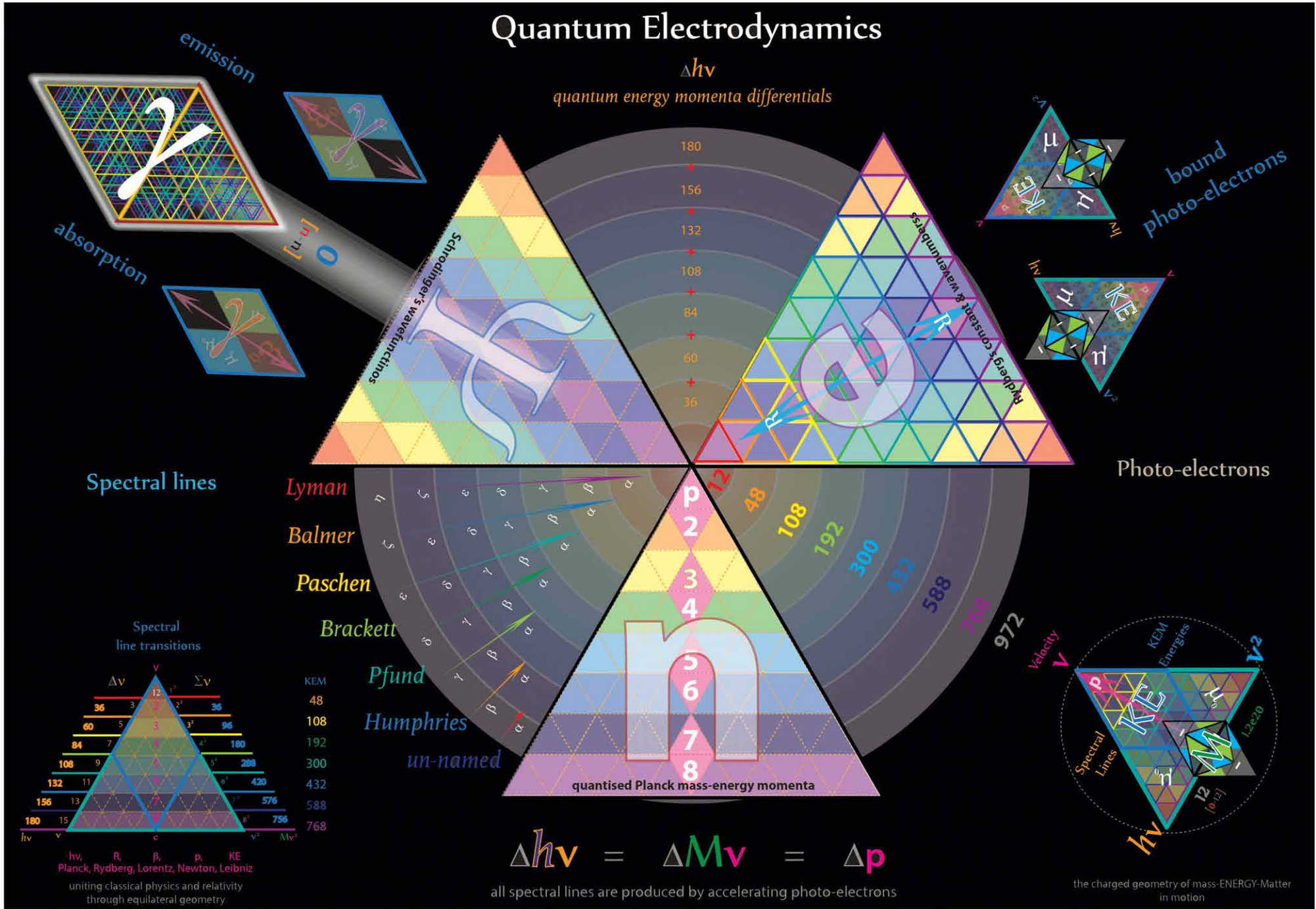
15/64
.0047

λ	19.174.54158	nm
$\bar{\nu}$	52.152.48541	m ⁻¹
f	$1.563492179 \times 10^{13}$	Hz
E	0.064693658	eV
Ω	5.748.382952	m ² /s

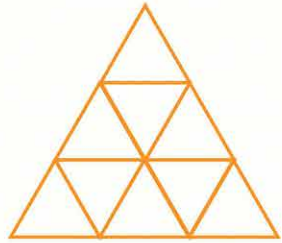
$$R \left(\frac{1}{49} - \frac{1}{64} \right)$$

.0047

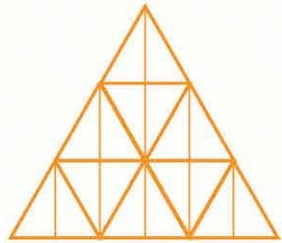
$$\Delta Mv^2$$



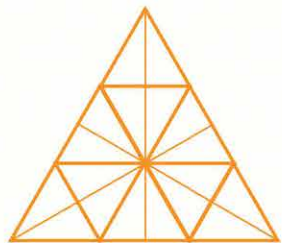
Tetryonics 96.11 - Atomic spectral series transitions



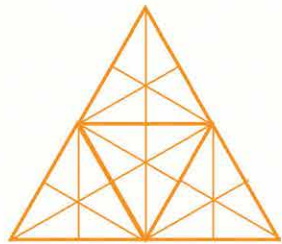
ninths



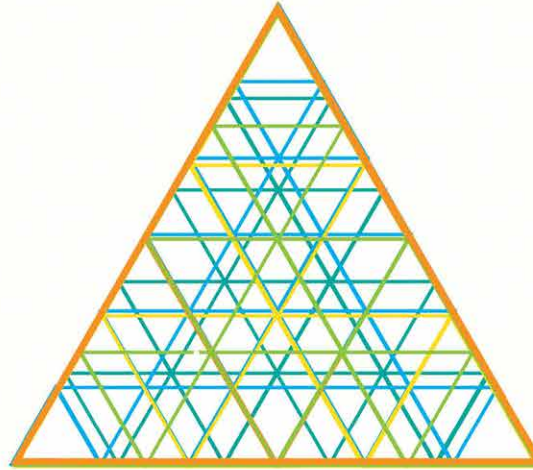
eigtheenths



Eighteenths

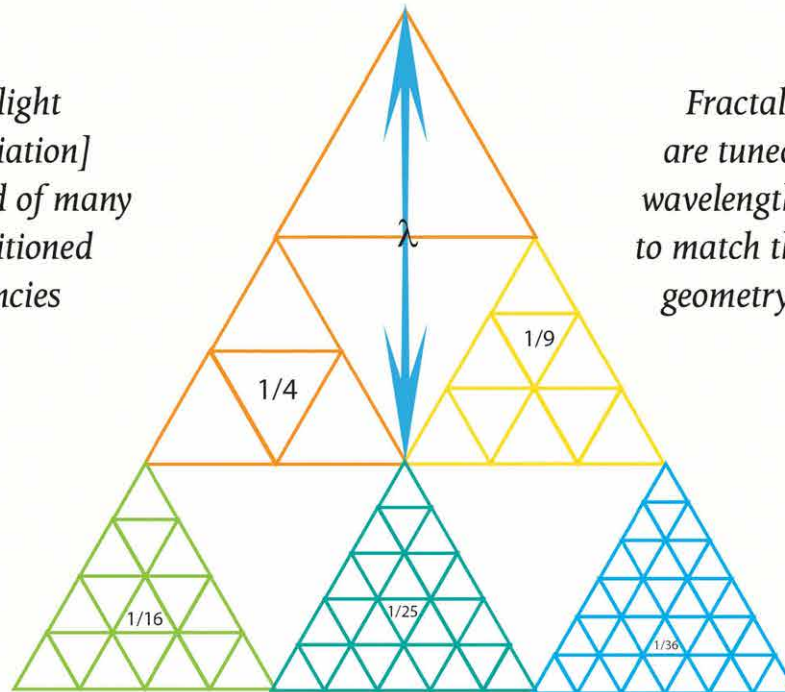


Twenty-fourths

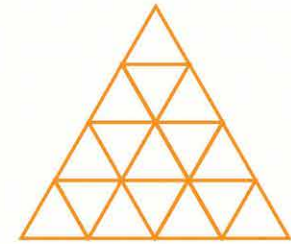


Fractionals and fractals

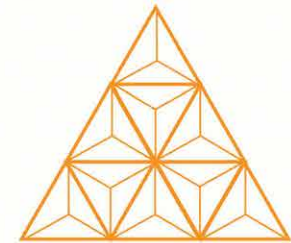
*White light
[EM radiation]
is comprised of many
superpositioned
frequencies*



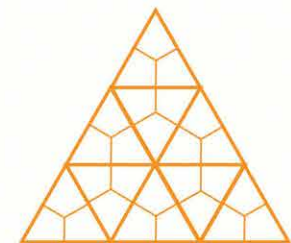
*Fractal antennas
are tuned to specific
wavelength-frequencies
to match the equilateral
geometry of photons*



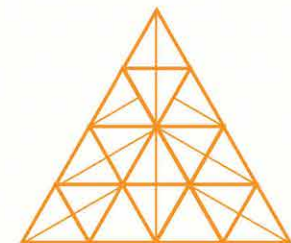
Sizteenths



Twenty-sevenths



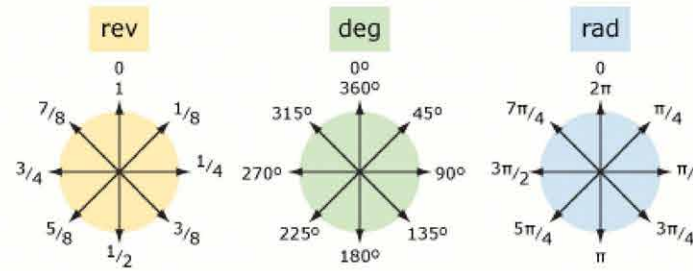
Twenty-sevenths



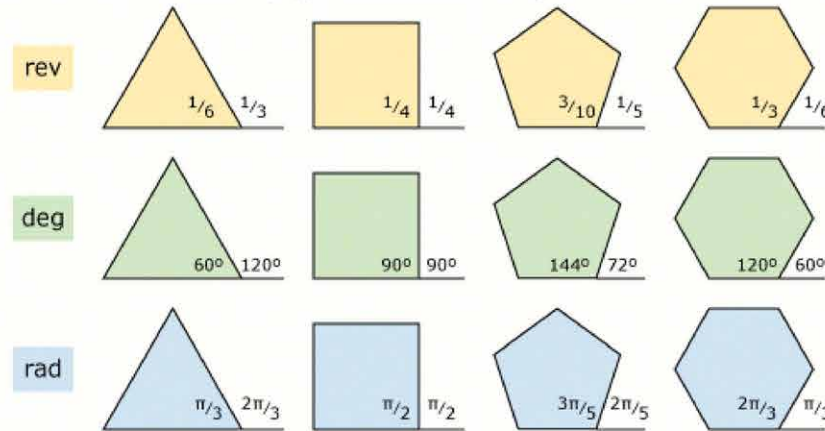
Thirty-seconds

Polygons

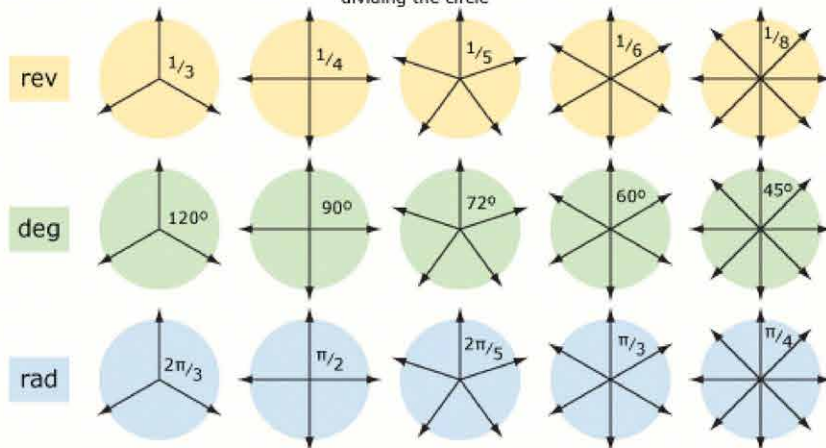
and Angles



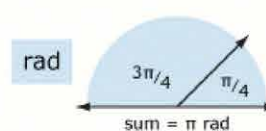
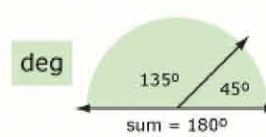
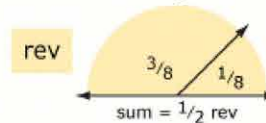
polygon exterior and interior angles



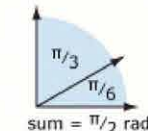
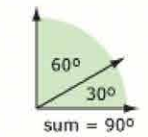
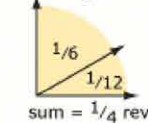
dividing the circle



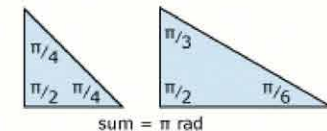
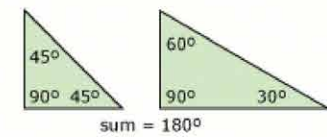
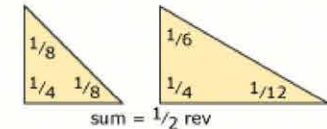
supplementary angles



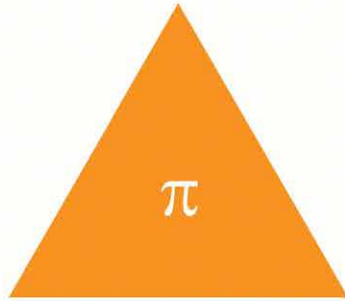
complementary angles



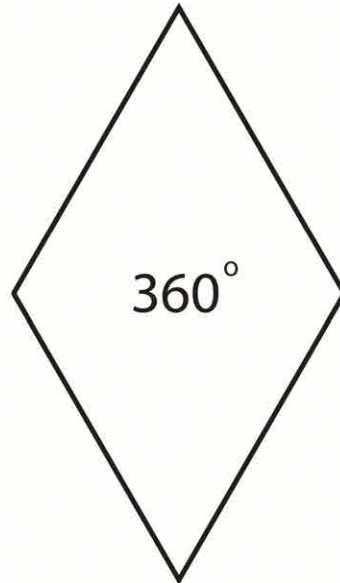
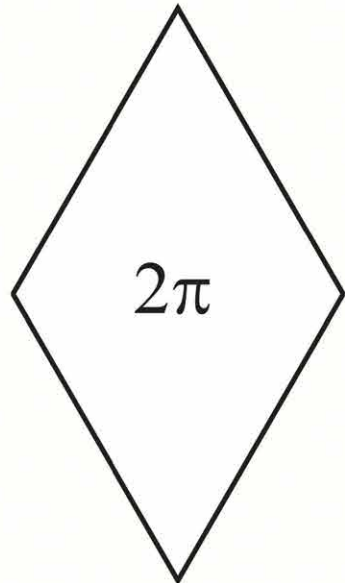
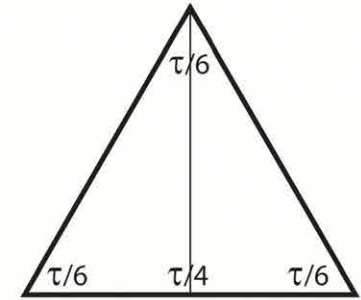
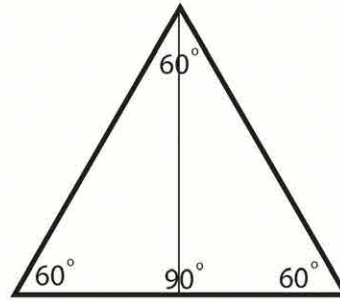
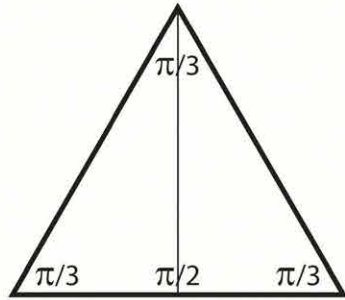
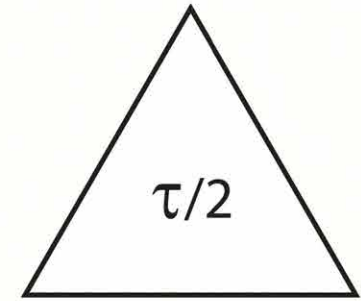
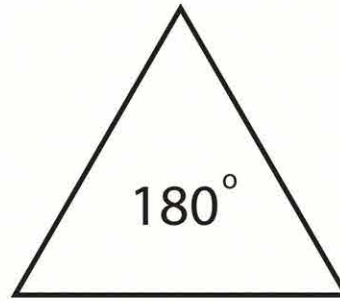
triangles



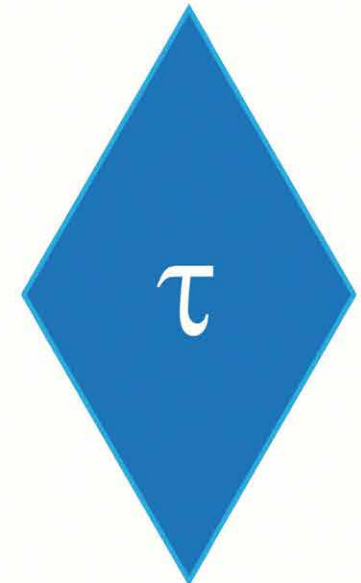
Pi vs Tau



bosons

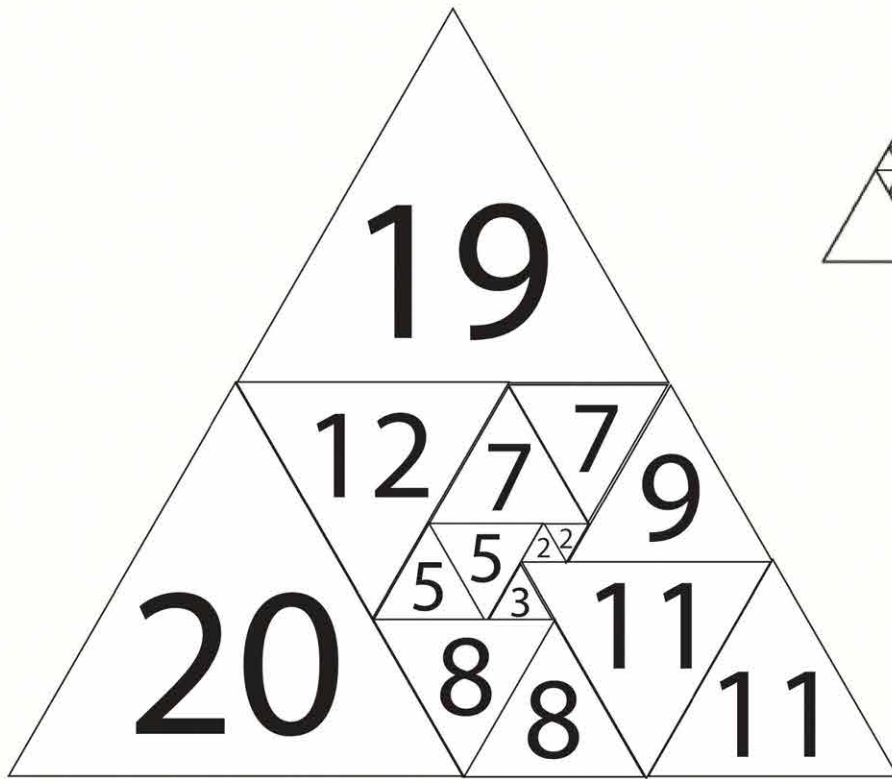
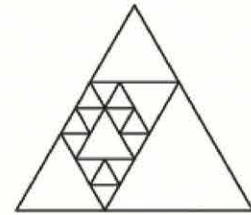
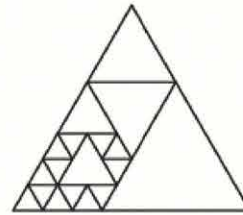
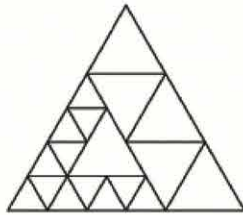
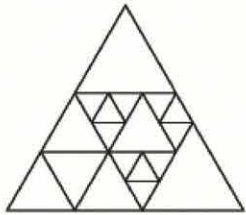


photons

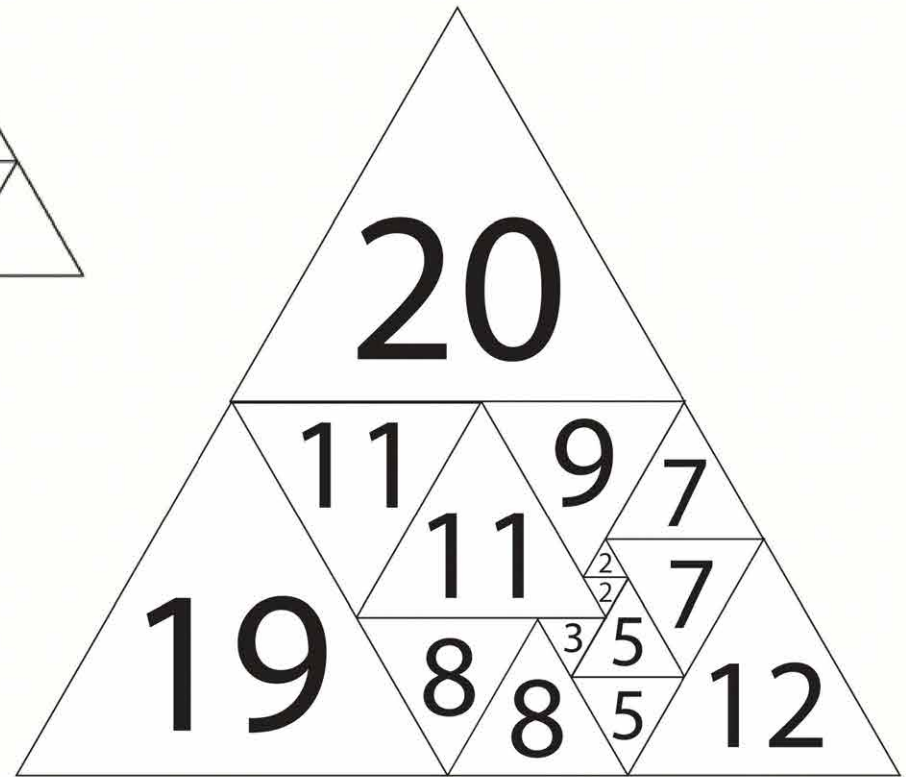
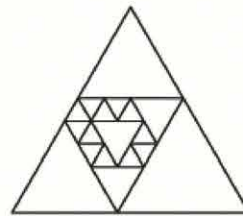


Triangular dissection of an equilateral triangle

is a way of dividing up a original triangle into smaller equilateral triangles, such that none of the smaller triangles overlap



lowest order perfect equilateral triangle dissected by equilateral triangles



lowest order perfect dissected equilateral triangle, an isomer of the first

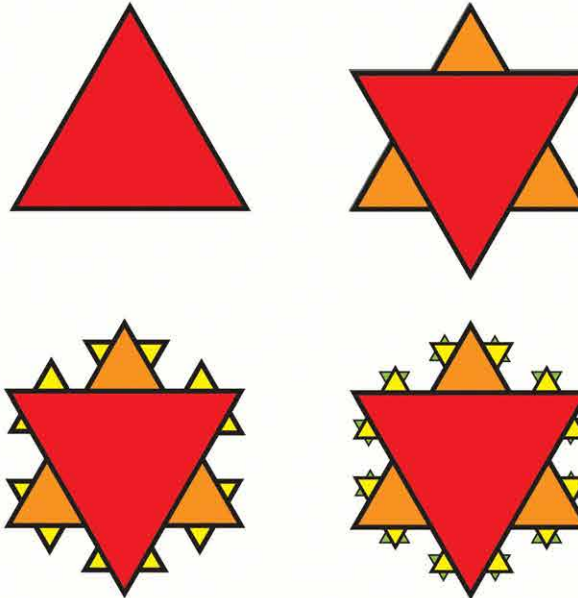
Koch fractal Curve

Niels Fabian Helge von Koch (January 25, 1870 – March 11, 1924) was a Swedish mathematician who gave his name to one of the earliest fractal curves ever known

He described the Koch curve, or Koch snowflakes as it popularly known, in a 1904 paper entitled "On a continuous curve without tangents constructible from elementary geometry"

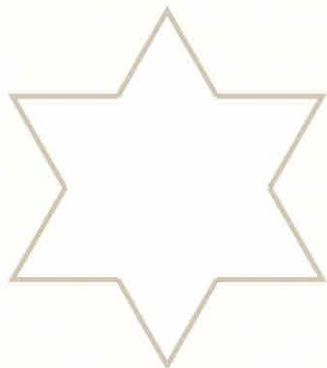
Von Koch wrote several papers on number theory . One of his results was a 1901 theorem proving that the Riemann hypothesis is equivalent to a strengthened form of the prime number theorem.

Three Koch curves form the snowflake.



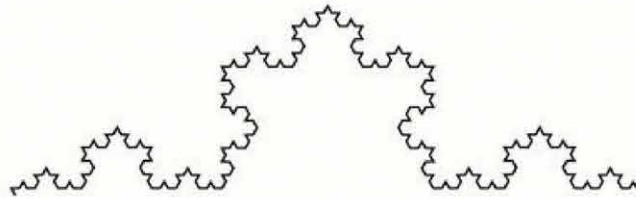
The Koch snowflake (or Koch star) is a mathematical curve and one of the earliest fractal curves to have been described.

Actually Koch described what is now known as the Koch curve, which is the same as the now popular snowflake, except it starts with a line segment instead of an equilateral triangle.

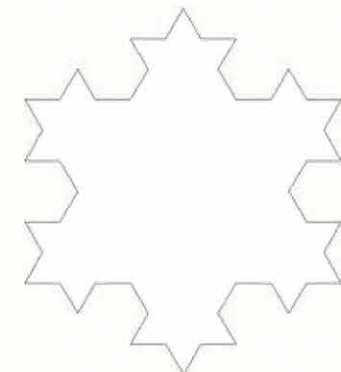


$$a = \frac{1}{2} + \frac{i}{\sqrt{12}}$$

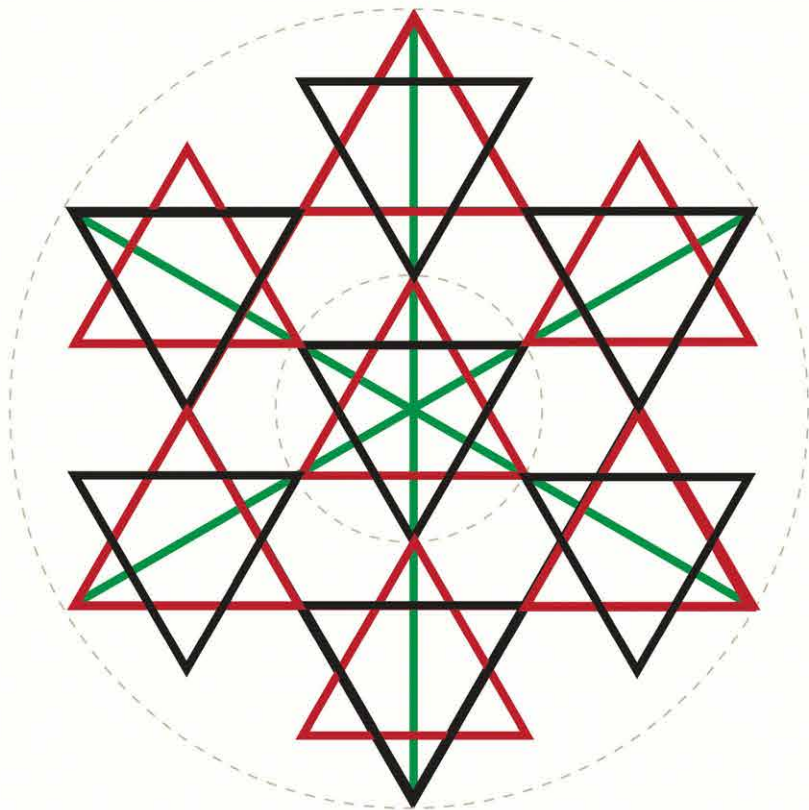
The Koch curve is a special case of the Cesaro curve where:



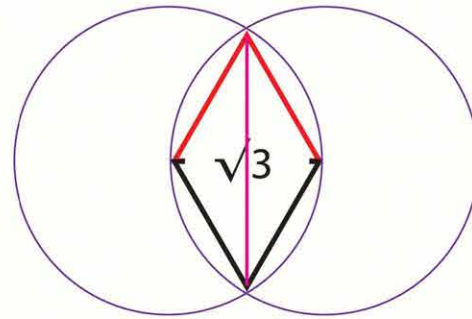
which is in turn a special case of the de Rham curve.



Koch snowflake



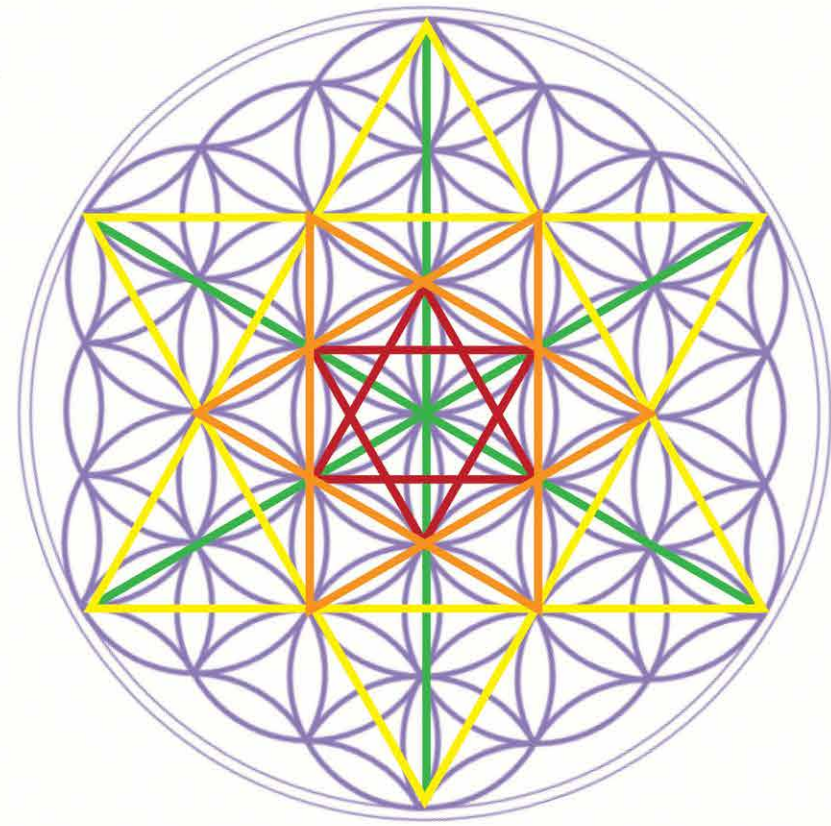
space-time



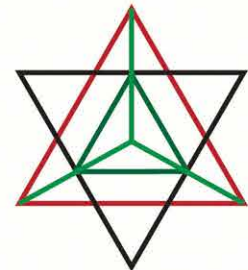
vesica piscis

$$\frac{1351}{780} > \sqrt{3} > \frac{265}{153}$$

Flower of Life



star tetrahedron



The Flower of Life is a name for a geometrical figure composed of multiple evenly-spaced, overlapping circles.

Unit circles - SINE WAVES - Photons

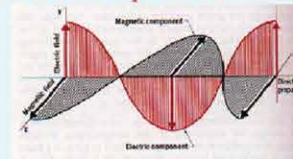
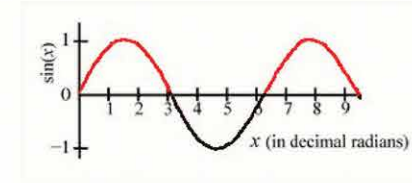
Classic model of a photon

Maxwell's Equations

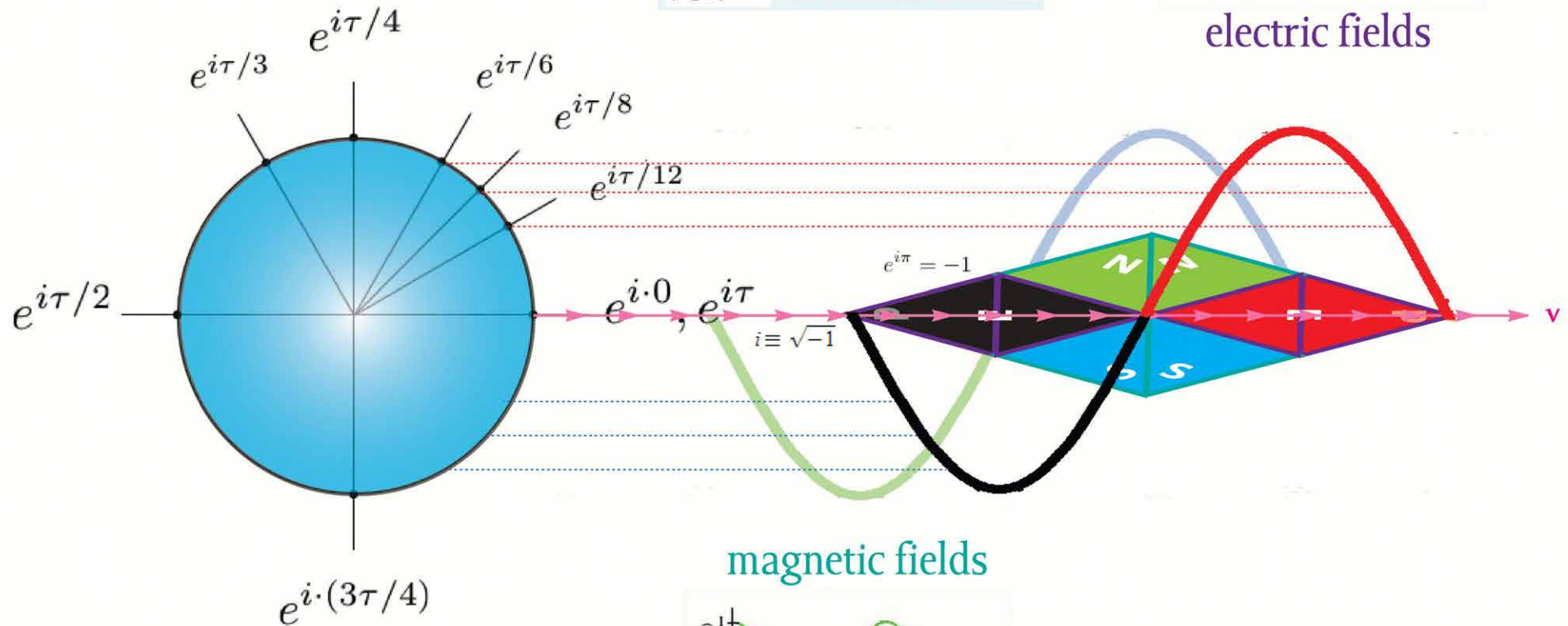
$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\nabla \cdot \vec{D} = \rho$$

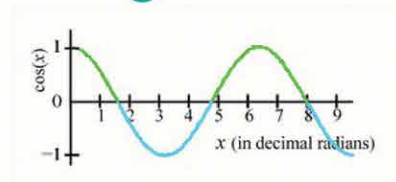
$$\nabla \times \vec{H} = \frac{\partial \vec{D}}{\partial t} + \vec{J}$$

$$\nabla \cdot \vec{B} = 0$$



electric fields



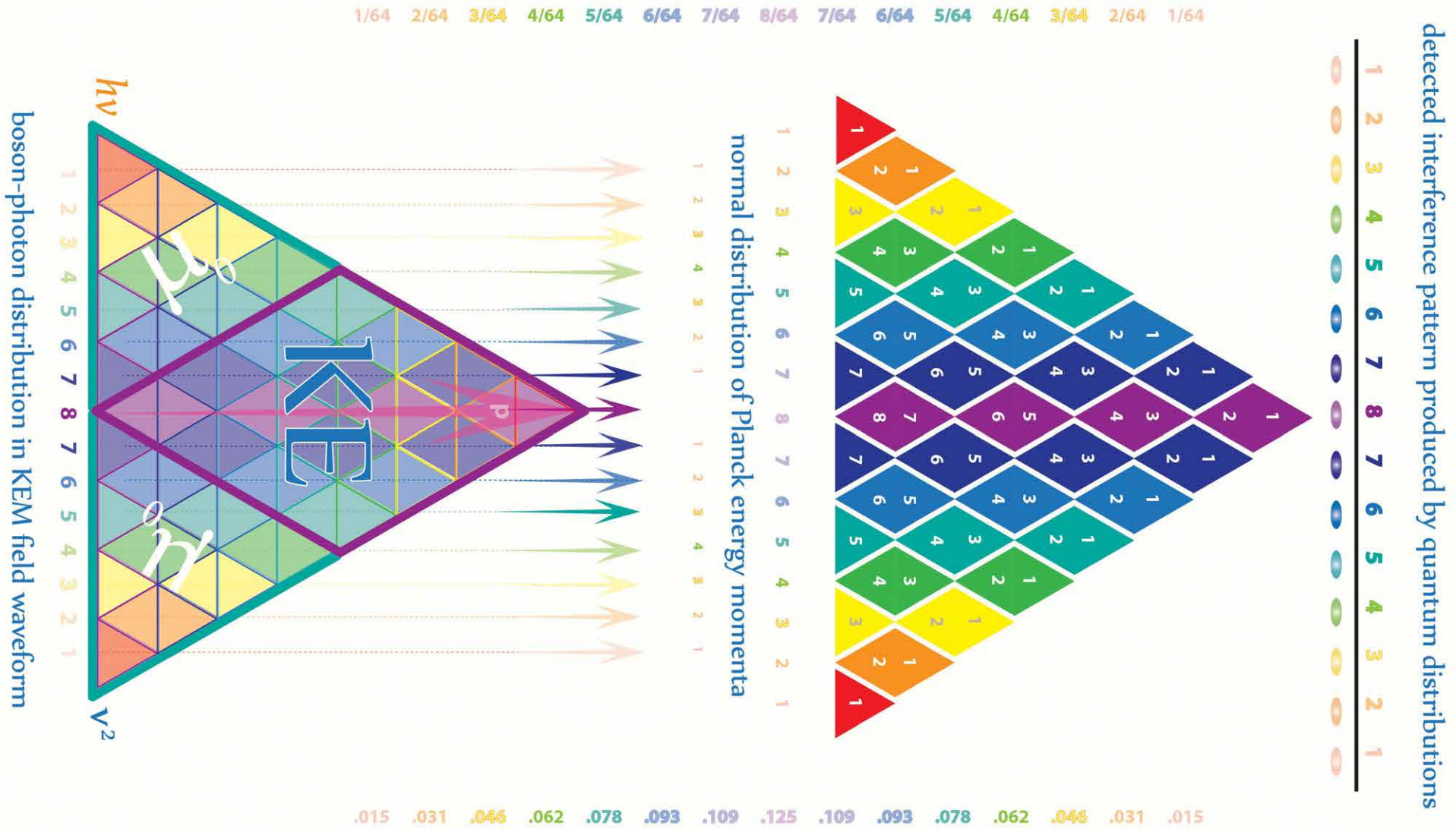
magnetic fields



Tetryonic model of a photon

Magnetic waveforms are 90 degrees out of phase with Electric waveforms

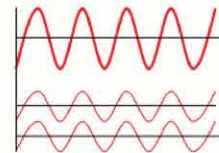
Boson distributions in monochromatic EM waves



Probability distributions of monochromatic EM waves

Quantum computing via EM wave super-positioning

By superpositioning two beams of EM radiation the resultant 'colours' will perform quantum level computations that can be read via the resultant interference patterns produced



In phase

constructive interference

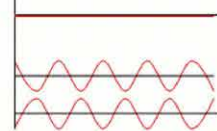
additive in-phase EM waves

Additive



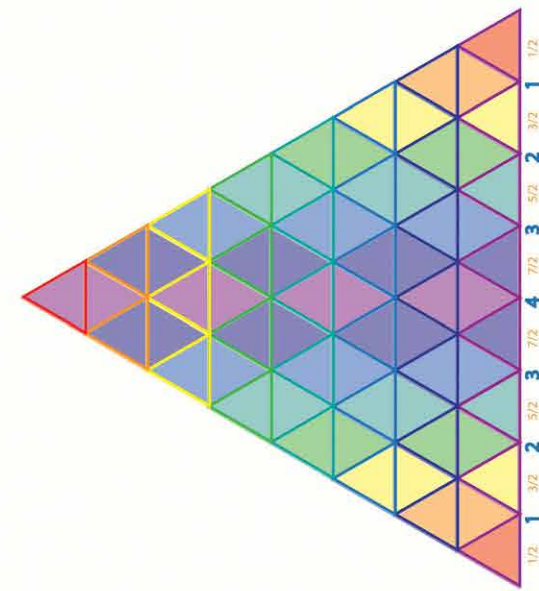
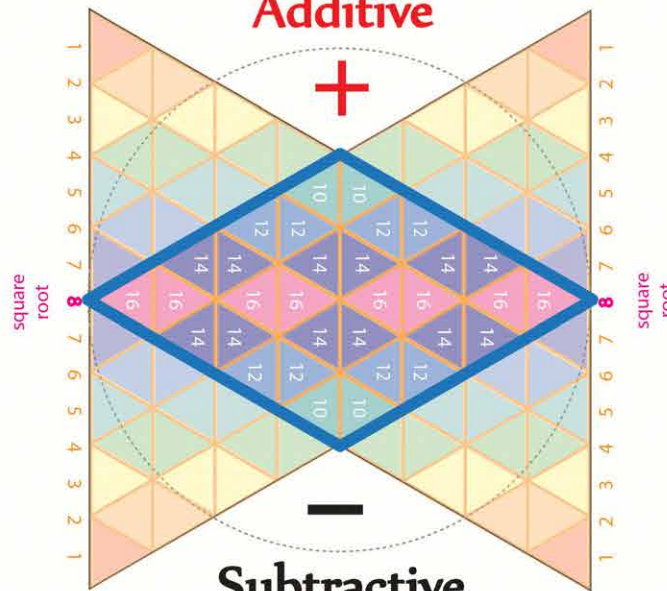
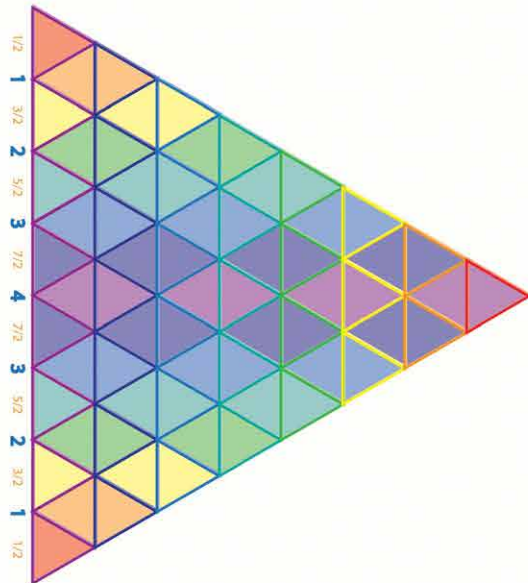
Subtractive

Out of phase



destructive interference

subtractive out-of-phase EM waves



Various basic operations, such as ADDITION, SUBTRACTION and SQUARE ROOTS etc are all easily computed using EM wave super-positioning

The lines of Force

By utilising the statistical distribution of equilateral Planck energy momenta quanta in EM waves
Tetryonic theory provides a practical geometric solution to quantum computing problems

The set of all decision problems for which an algorithm exists which can be carried out by a deterministic Turing machine in polynomial time

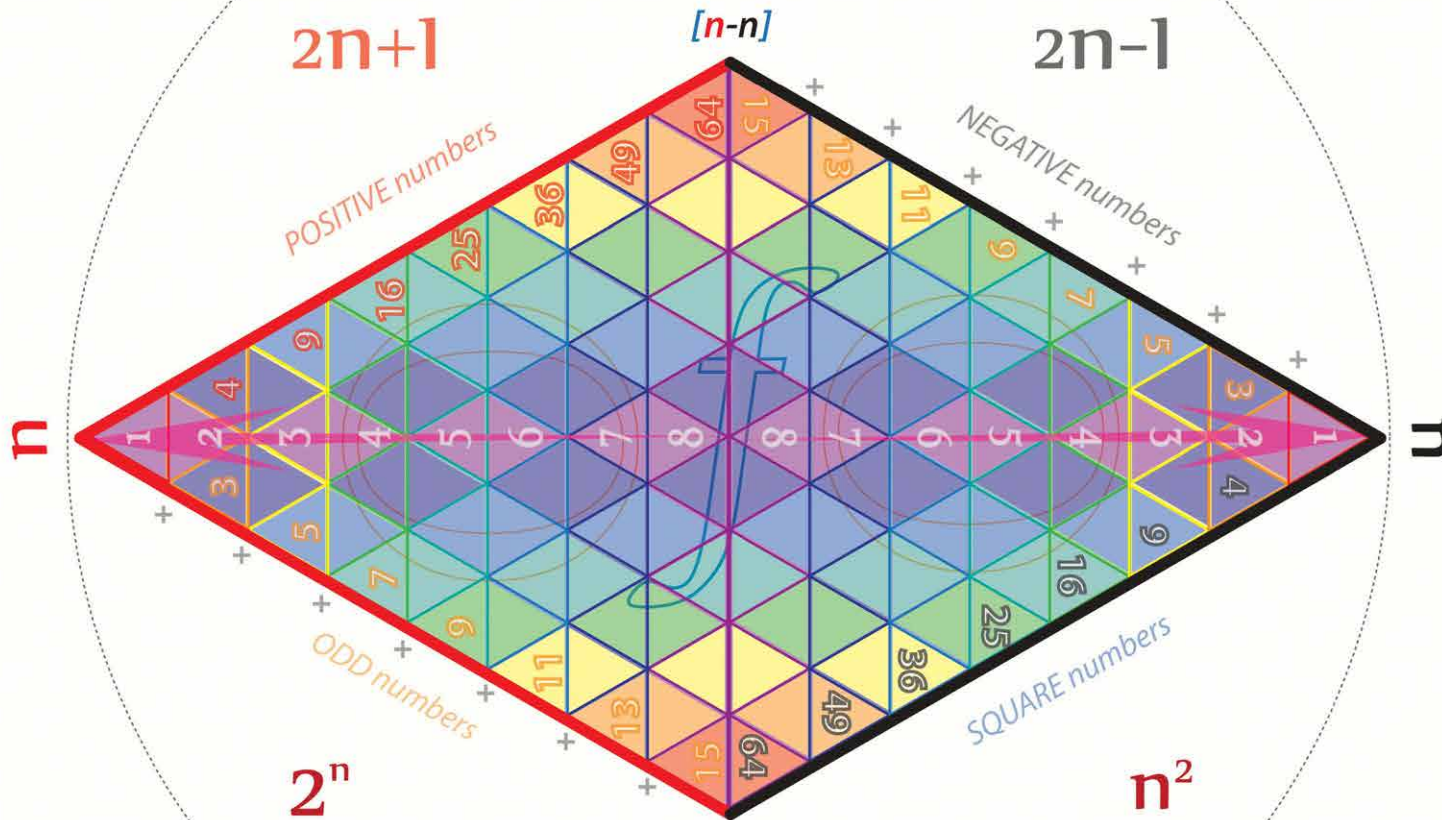
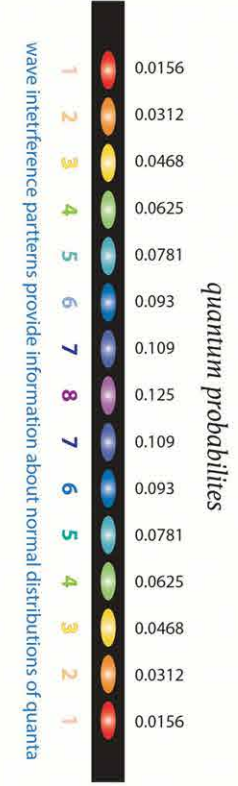
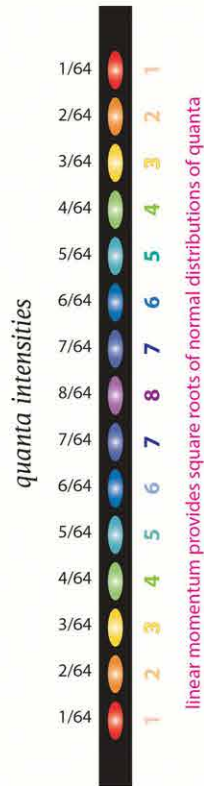
P vs. NP

the set of all decision problems for which an algorithm exists which can be carried out by a non-deterministic Turing machine in polynomial time

An algorithm of time complexity $O(n)$ is one which increases in time linearly as the "size of the problem" (whatever n stands for) increases.

q
bosons

E
photons



An algorithm of complexity $O(2^n)$ utilises exponential quanta; increasing n by 1 will double the quanta required

An algorithm of complexity $O(n^2)$ utilises quadratic quanta, meaning that if you double n it will use four times as many quanta.

Unlike Math treatise on P vs Np that require exponential polynomial time $O(n^k)$ Tetryonic geometry of EM fields utilise exponential energies per second

$2h\nu$

1 second

hf

By relating p to the number of equilateral wave fields in any EM wave very large $[pn^2]$ data sets can be modelled and processed every second

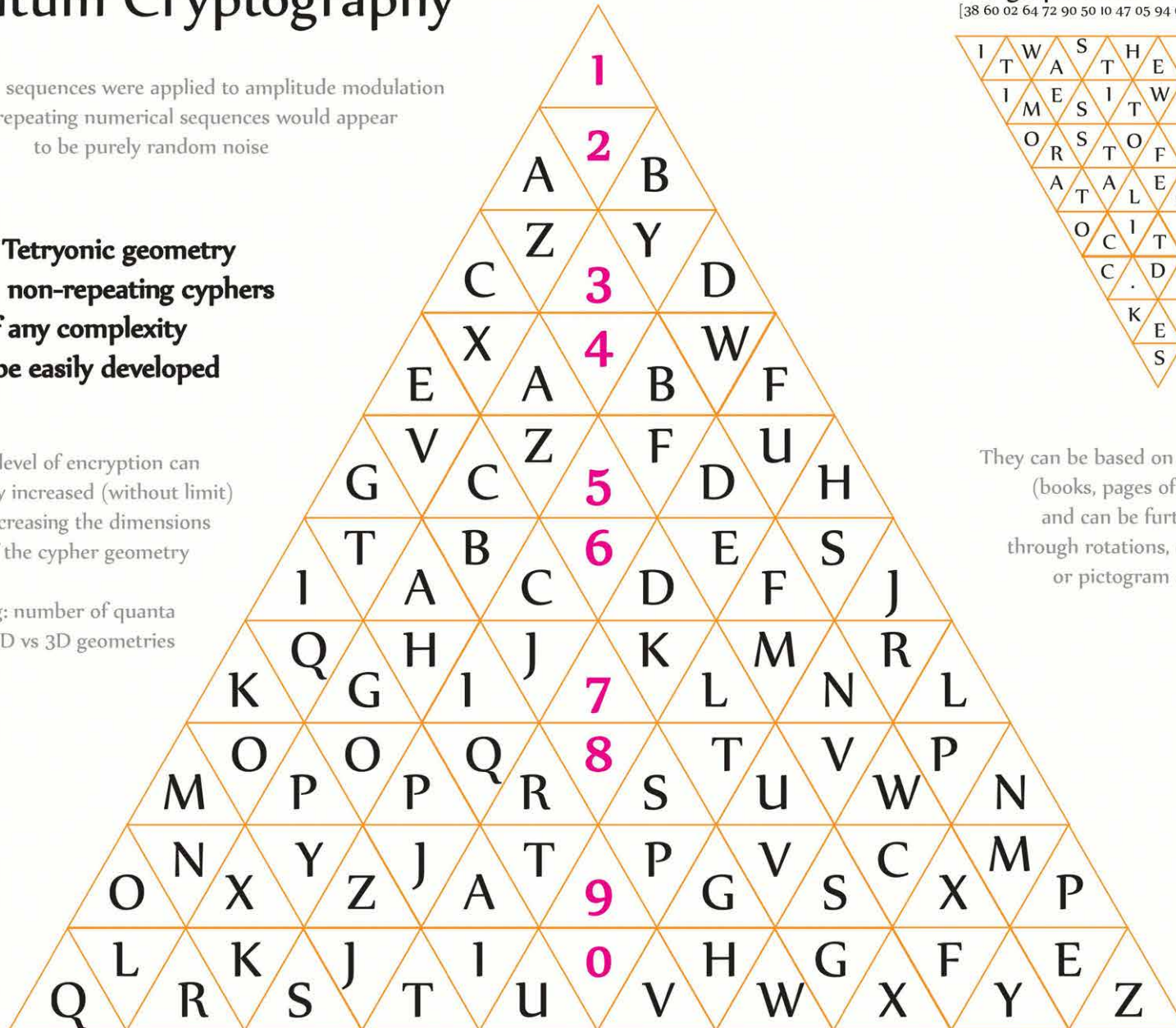
Quantum Cryptography

If the numerical sequences were applied to amplitude modulation their non-repeating numerical sequences would appear to be purely random noise

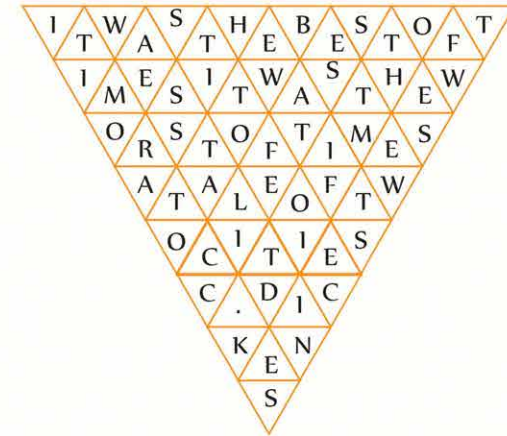
Using Tetryonic geometry advanced non-repeating cyphers of any complexity can be easily developed

The level of encryption can be easily increased (without limit) by increasing the dimensions of the cypher geometry

eg: number of quanta
2D vs 3D geometries



eg: quantum encryption 1024
[38 60 02 64 72 90 50 10 47 05 94 08 48 52 27 26 51 66 01 91 03 20]



They can be based on known letter sources (books, pages of magazines etc) and can be further encrypted through rotations, double encrypting or pictogram substitutions

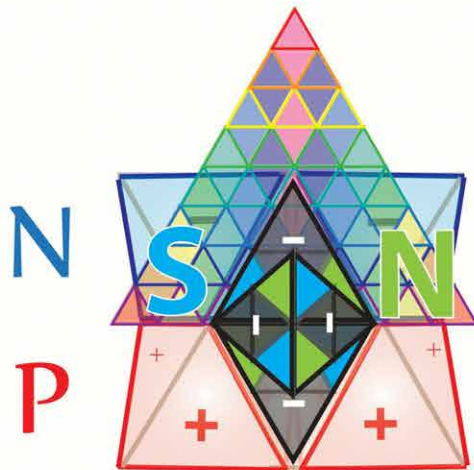
Quantum Computing

The Proton/Neutron geometries of atomic nuclei can be built at the quantum scale to create an atomic nuclei that can operate as a Opto-memory-transistive computing element, many elements can then be combined in lattices to create super computers no larger than bacterium

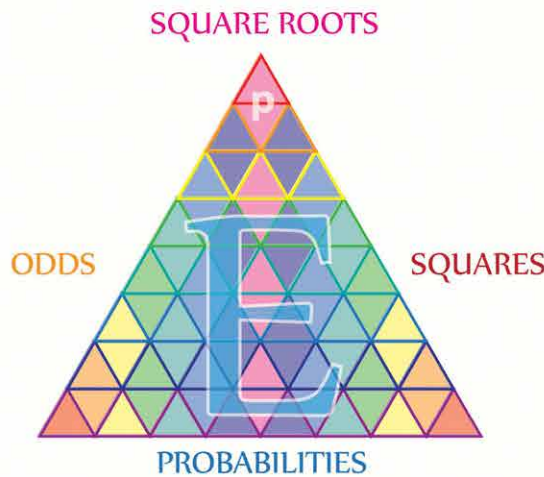
Spin UP

Energy can be gated through individual nuclei using the centre Baryon as the base transistor element, in turn effecting the energies of bound photo-electrons

Spin DOWN

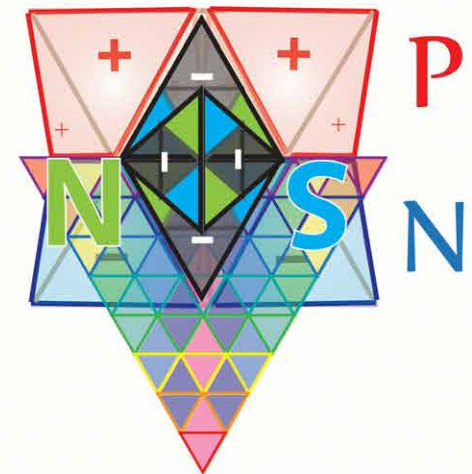


1



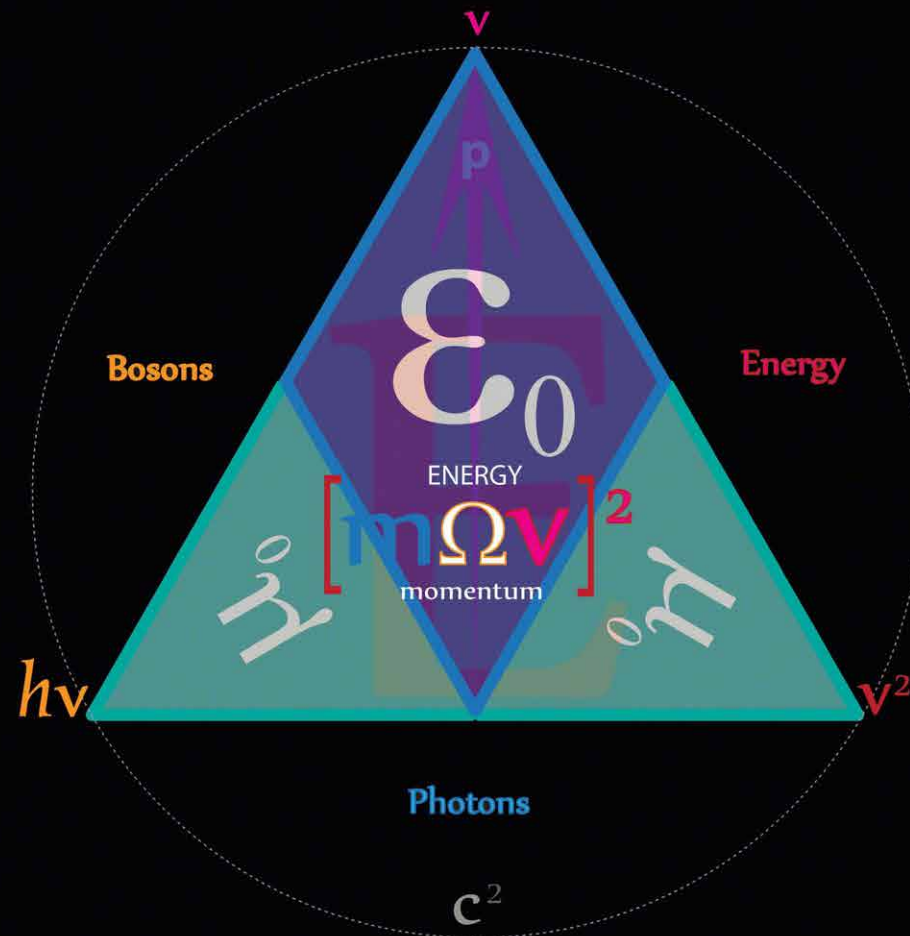
Q-bits

photo-electronic transitions can be used to directly receive or emit memory states through the absorption and emission of spectral photons of specific energy momenta

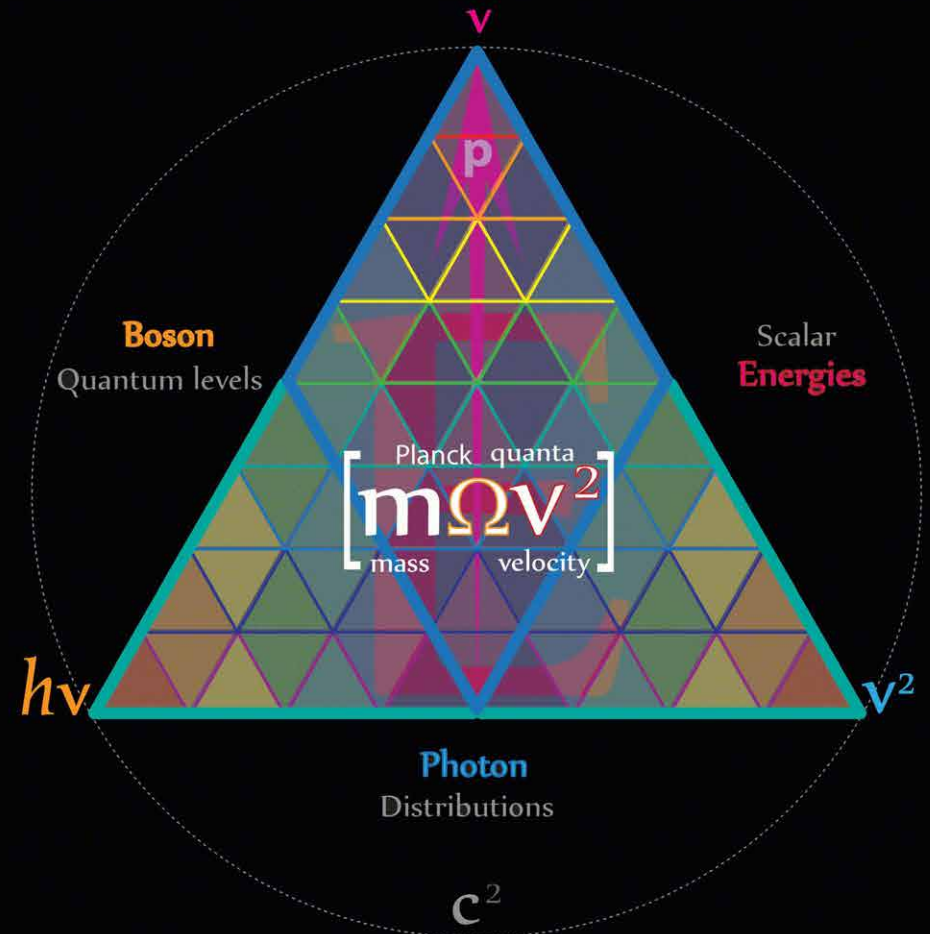


0

Scalar mass-energies



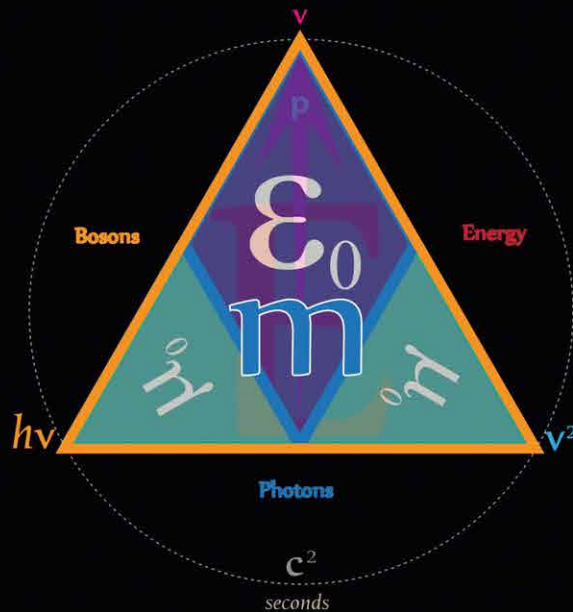
Quantum distributions



$$\frac{\text{EM mass } n\pi}{c^2} \left[\begin{array}{c} \text{Planck quanta} \\ [m\Omega v^2] \\ \text{mass} \quad \text{velocity} \end{array} \right]$$

2D mass

$$\frac{n\pi}{c^2} \left[\begin{array}{l} \text{Planck quanta} \\ m\Omega v^2 \\ \text{mass} \quad \text{velocity} \end{array} \right]$$



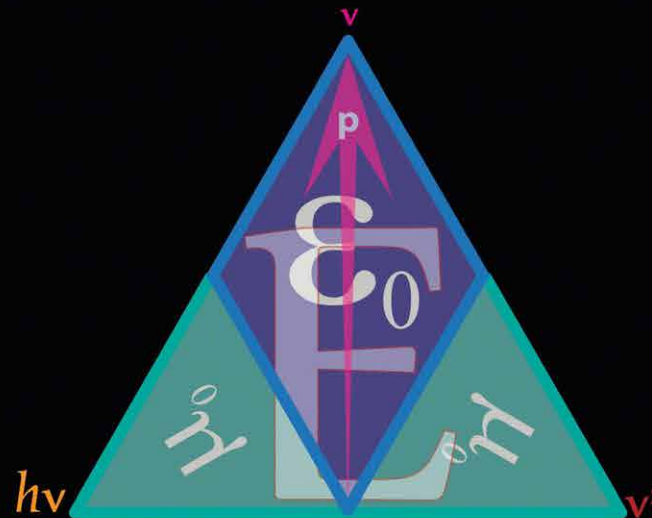
Measure of planar energies
in a $n\pi$ radiant wave
geometry
[per second]

mass quantum
7.376238634 e-51 kg

ENERGY

$$n\pi \left[\begin{array}{l} \text{ENERGY} \\ m\Omega v^2 \\ \text{momenta} \end{array} \right]$$

Equilateral energy momenta
has a mass equivalence
per unit of Time



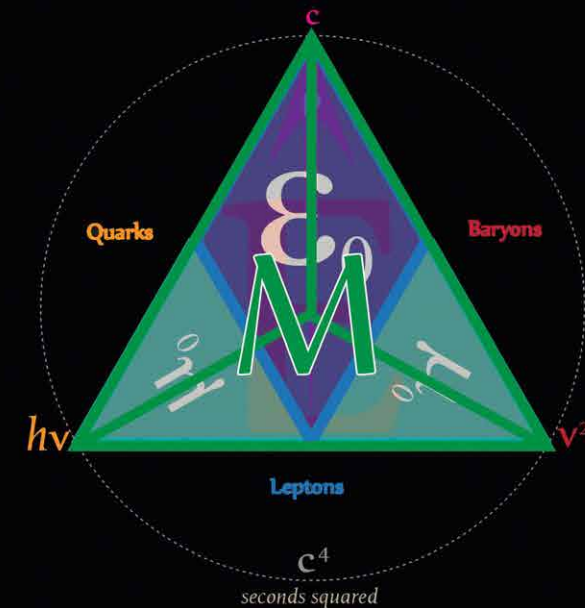
c^2 is the radial geometry
created by radiant energy
in 1 second

Planck Constant
6.629432672 e-34].s

3D Matter

$$\frac{T\pi}{c^4} \left[\begin{array}{l} \text{Matter} \\ \text{Planck quanta} \\ m\Omega v^2 \\ \text{mass} \quad \text{velocity} \end{array} \right]$$

Measure of mass-energy
in a $4n\pi$ standing wave
topology
[per second squared]

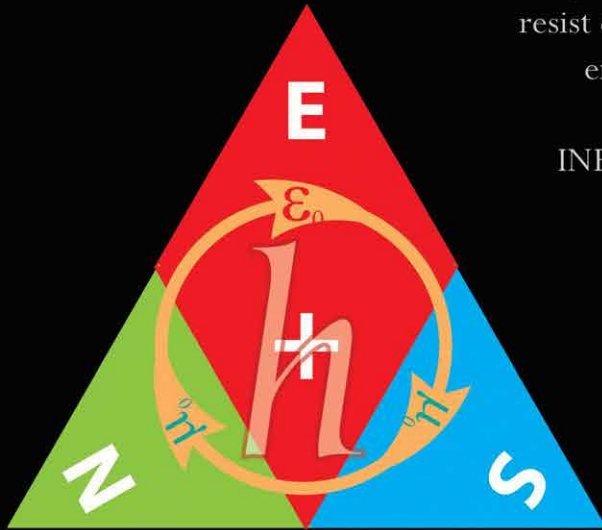


Matter quantum
2.9504955454 e-50 kg

Planck's constant - the quantum of Action

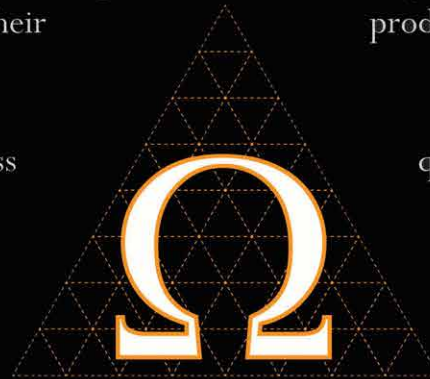
all ideal quantum inductive loops resist changes to their energy levels

all equilateral energy momenta produce square root vector Forces



INERTIAL mass

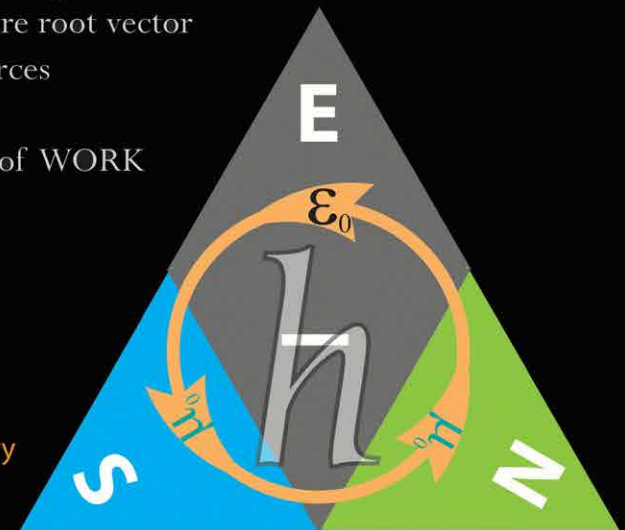
quantum of WORK



Quantised angular momentum is equilateral geometry

The two sides of Planck's Constant

The square root of all Energy is linear momentum

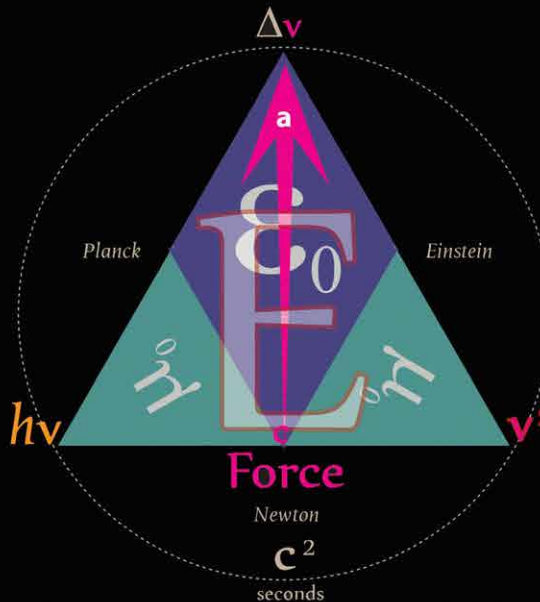


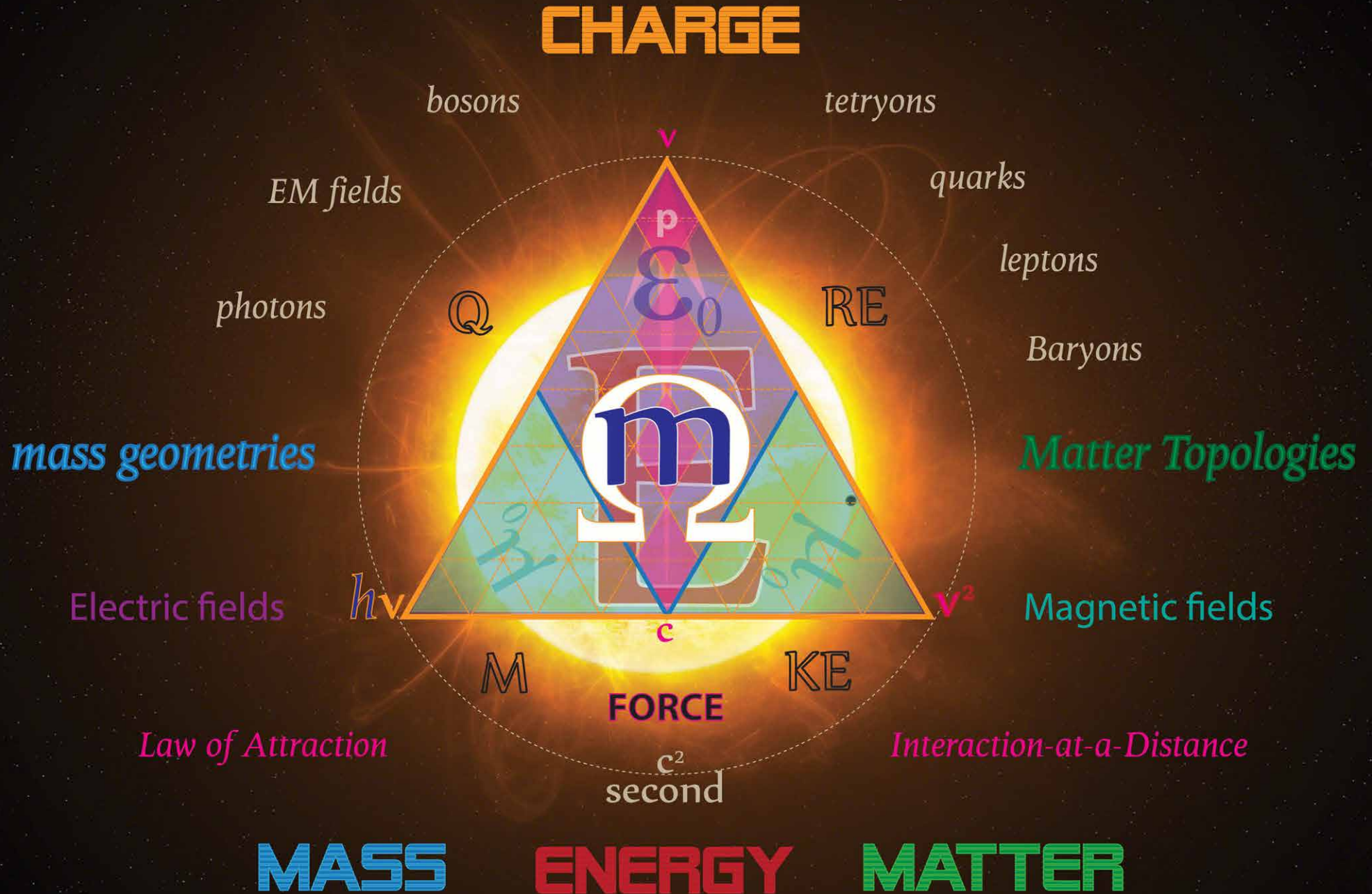
Equilateral energy quanta per second

Quantised angular momenta per second

mass

time

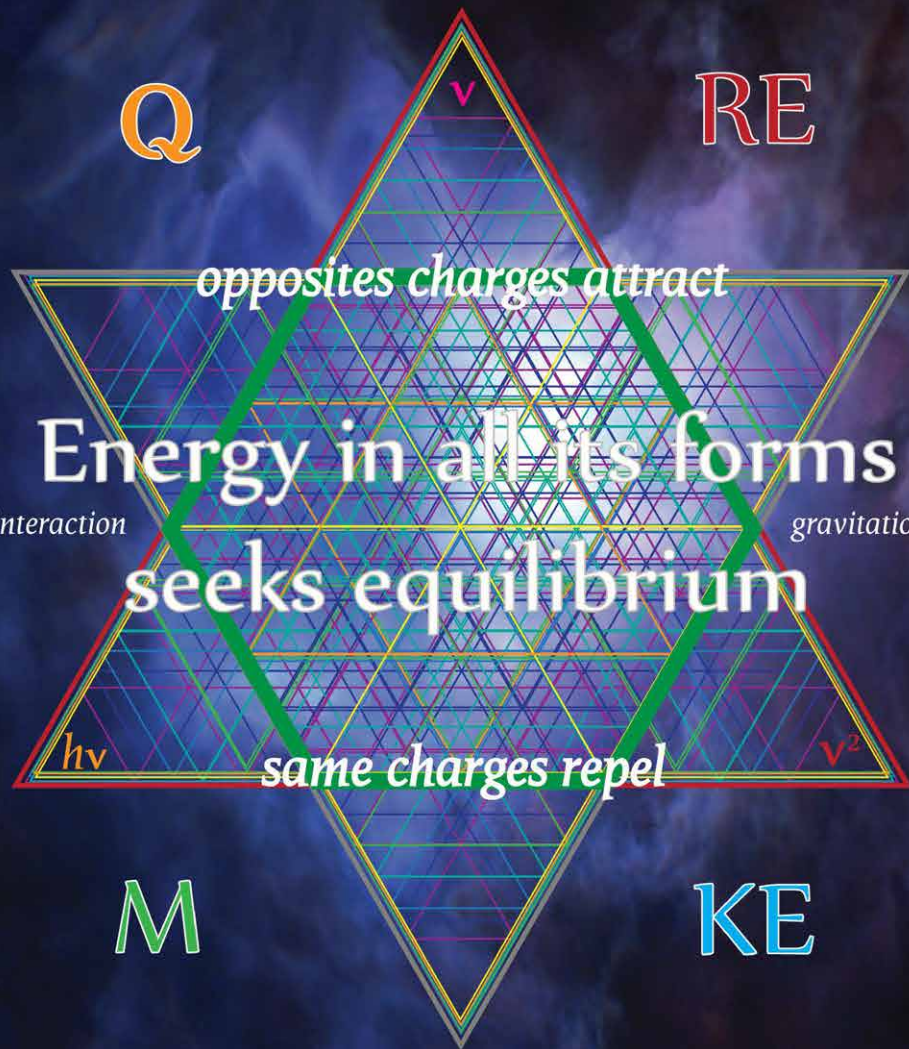




All squared energies have equilateral geometries



2D
radiant
mass-energy
geometries



Proton

3D
standing-wave
Matter
topologies



Neutron

There are NO infinities
only Eternity

Clean, limitless Energy

Unlimited resources

The geometric field equation of mass-ENERGY-Matter

$$\begin{matrix} \text{Matter} \\ \tau \pi \\ \text{topology} \end{matrix} \left[\begin{matrix} \text{spatial} \\ \epsilon_0 \mu_0 \\ \text{impedance} \end{matrix} \right] \cdot \left[\begin{matrix} \text{Planck} & \text{quanta} \\ m \Omega v^2 \\ \text{mass} & \text{velocity} \end{matrix} \right]$$

Unifying Science and Religion

Tetryonic Theory

All EM mass, energy momenta & Matter can be measured and geometrised with respect to equilateral Quantised Angular Momenta

charged
Planck quanta

$$\frac{\text{Bosons}}{c^2} \left[\left[\frac{\text{Planck quanta}}{m \Omega v^2} \right] \right]$$

Total Relativistic
energies

$$\text{ENERGY } n\pi \left[\left[\frac{\text{Planck quanta}}{m \Omega v^2} \right] \right]$$

Quantum Mechanics

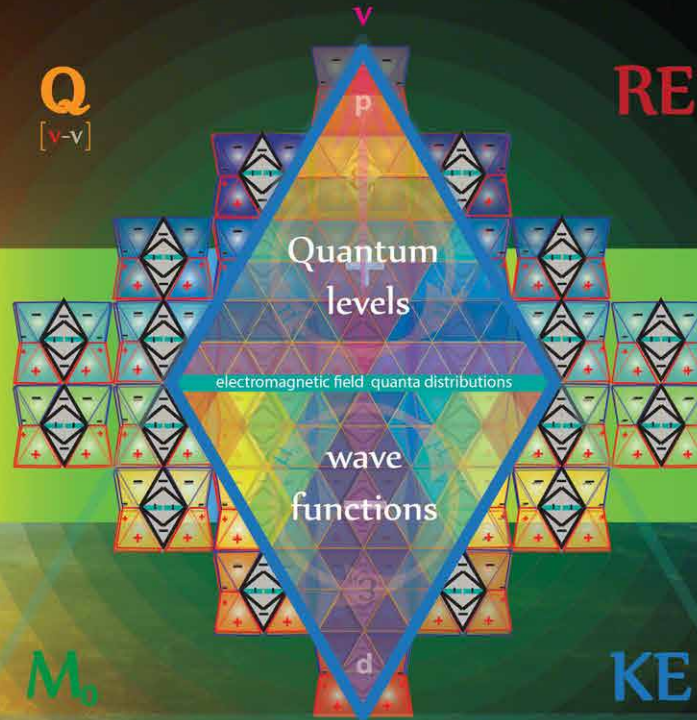
Q
[v-v]

RE

Quantum Cosmology

standing-wave mass-Matter

radiant EM mass-energies



Quantum Chemistry

Electrodynamics

$$\frac{\text{Matter}}{c^4} \left[\left[\frac{\text{Planck quanta}}{m \Omega v^2} \right] \right]$$

$$\frac{\text{EM waves}}{c^2} \left[\left[\frac{\text{Planck quanta}}{m \Omega v^2} \right] \right]$$

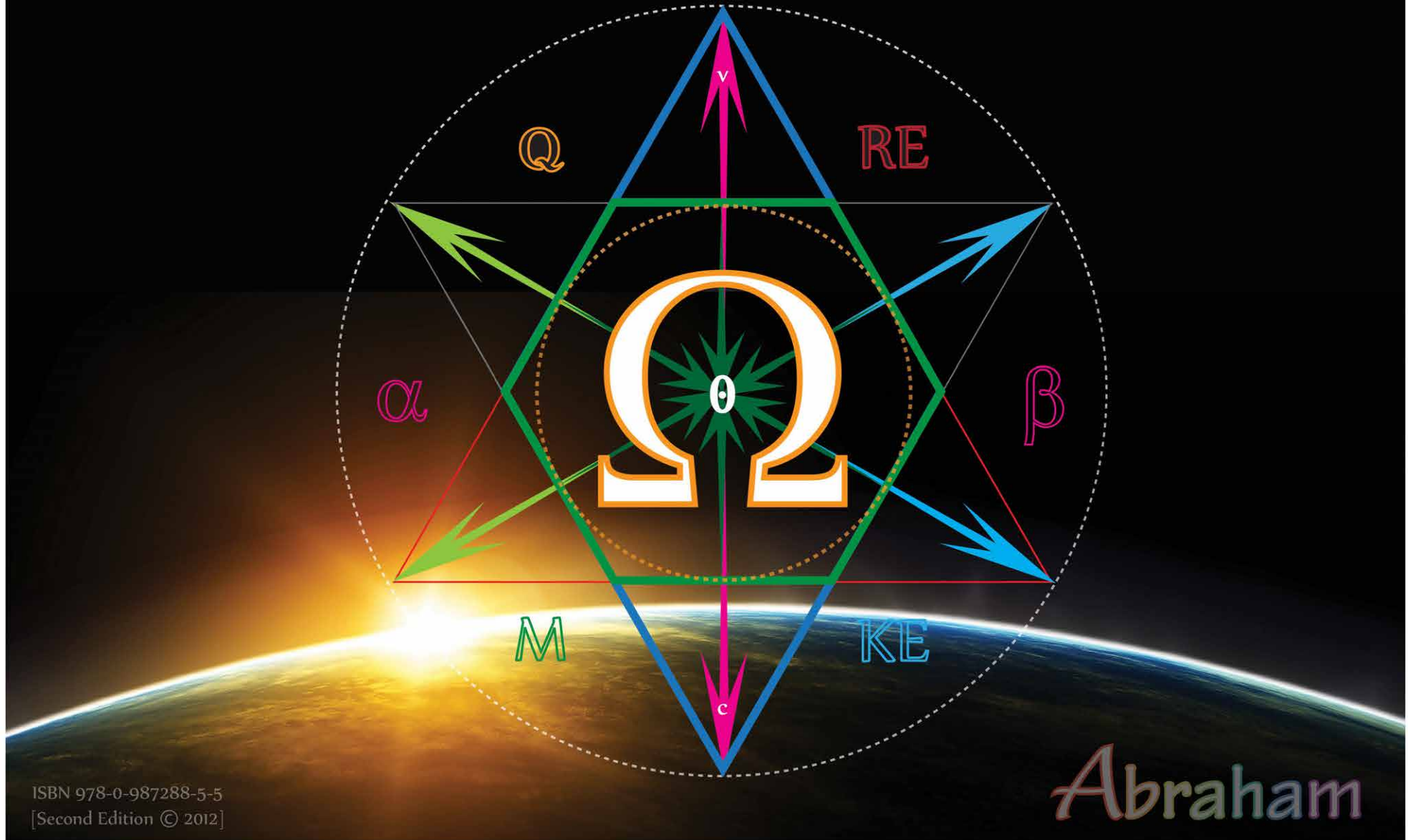
3D standing-wave
mass/Matter
topologies

2D radiant
mass-energy
geometries

The application of equilateral QAM geometries covers all of the Physical disciplines

Tetryonic Geometrics

The equilateral geometry underpinning the mathematics of Physics



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Abraham